



ABC Tree



Jungeum Kim

June 2024

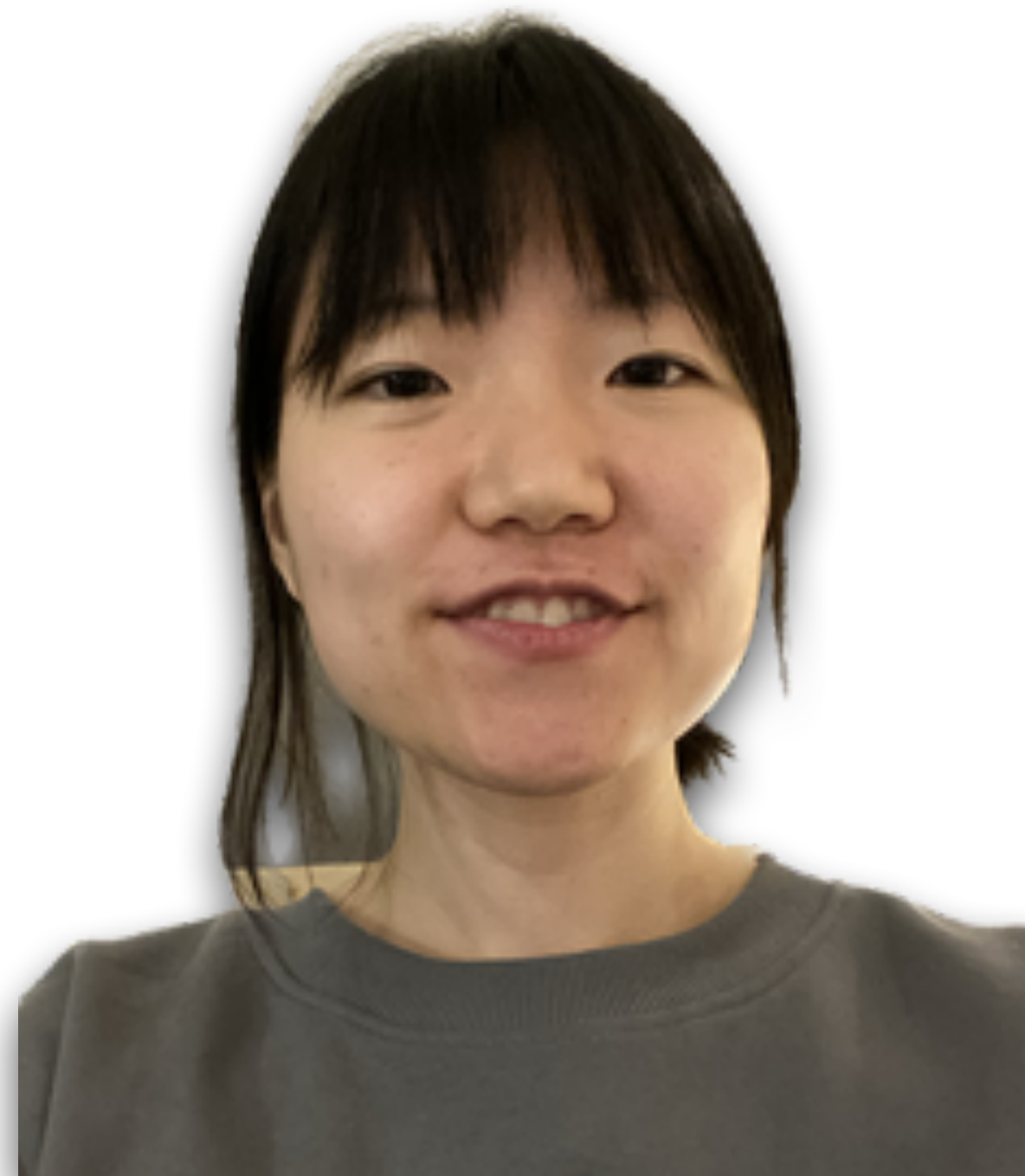
ABC: **A**pproximate **B**ayesian **C**omputation

Authors

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Veronika Rockova

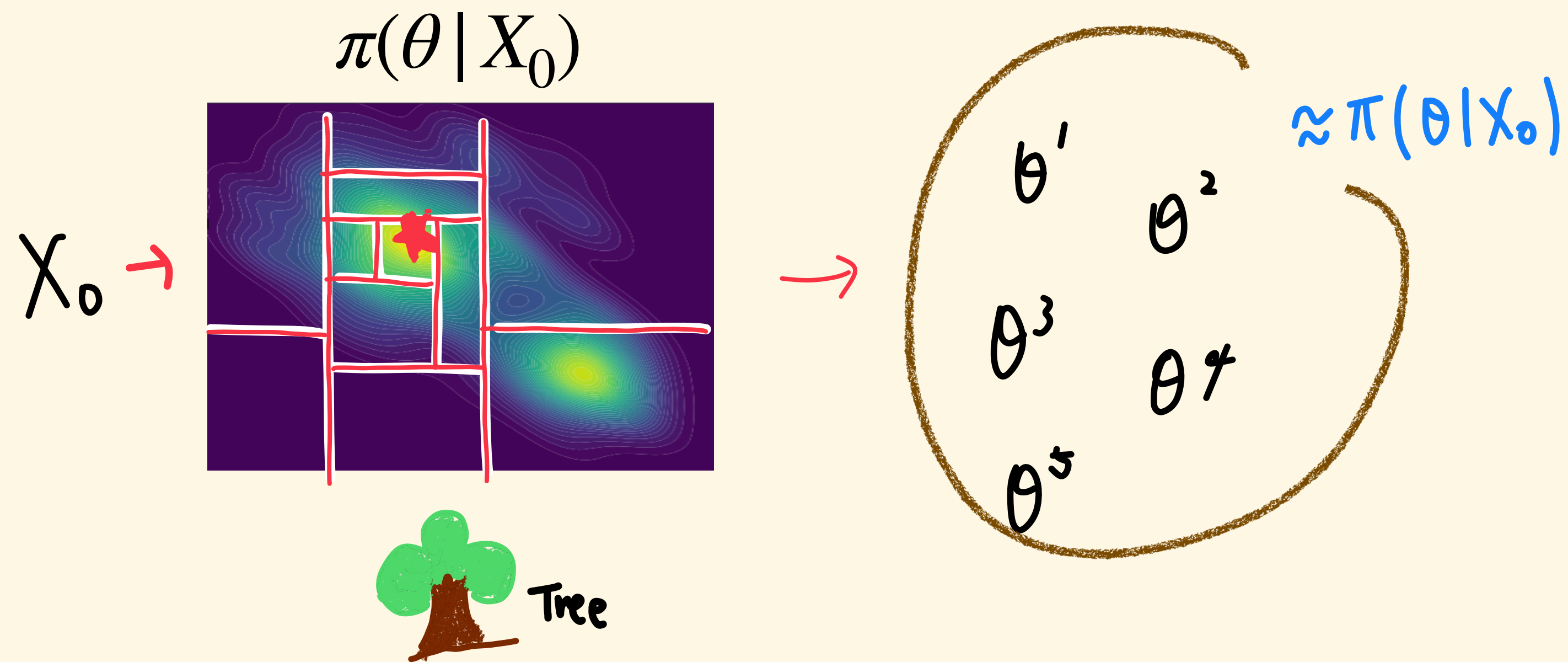


A B C



Our Contribution

By Combining **Tree** with
Active ABC learning

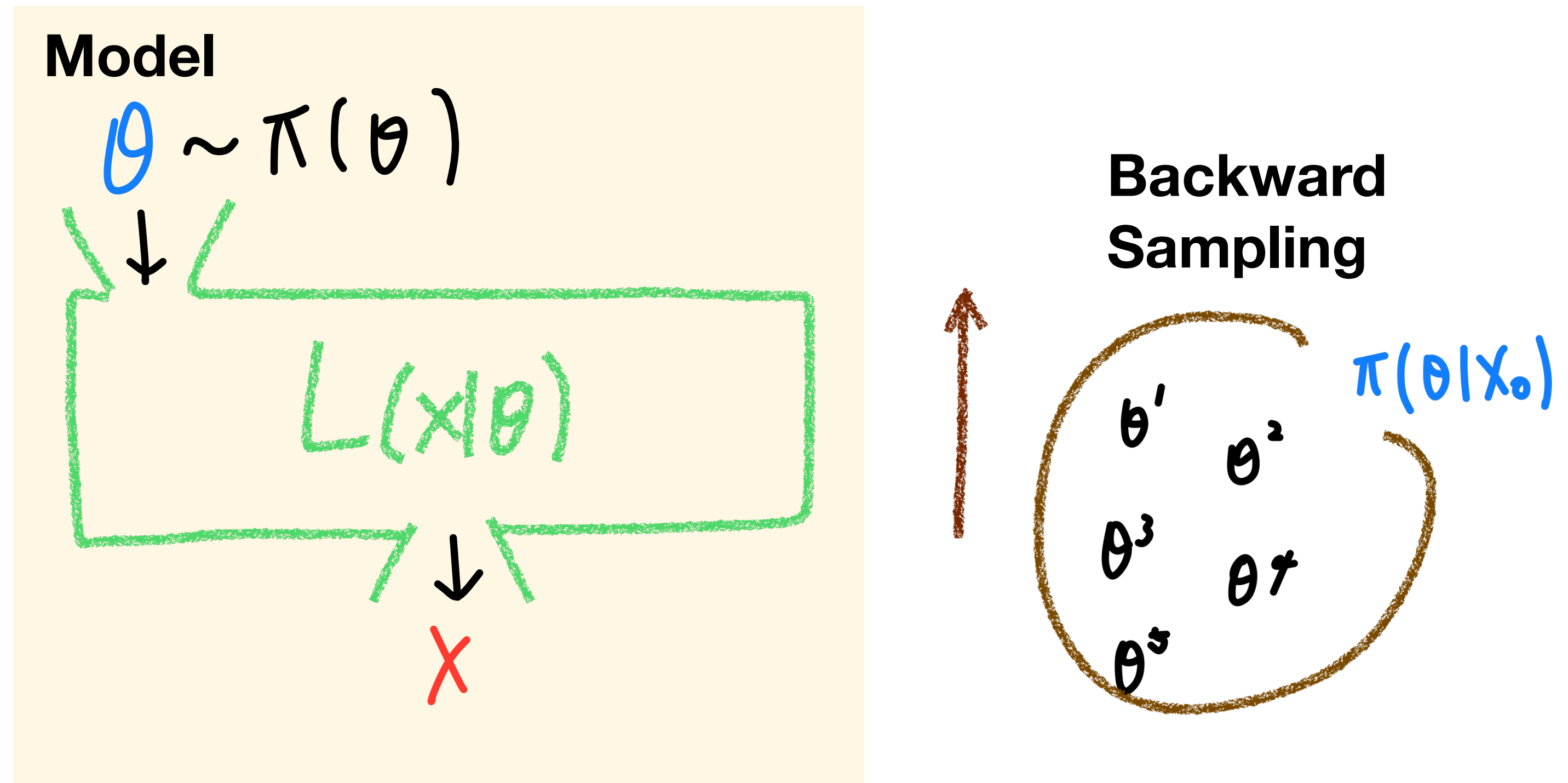


1. Query efficient ABC

2. Likelihood Free MAP
(Maximum a Posteriori)

Background

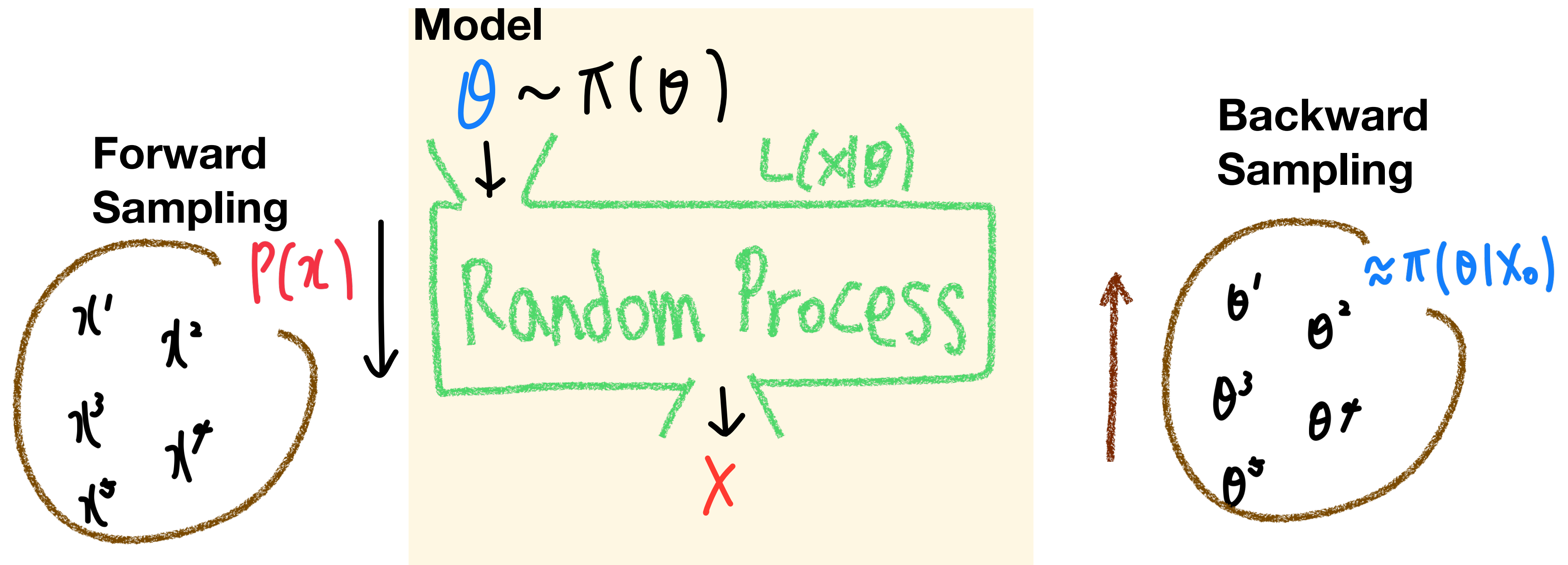
Bayesian Posterior Sampling



Conjugate Prior : Closed form $\pi(\theta | X)$

Likelihood given : MCMC $\rightarrow \pi(\theta | X) \propto L(X | \theta)\pi(\theta)$

Bayesian Posterior Sampling



Conjugate Prior : closed form $\pi(\theta | X)$

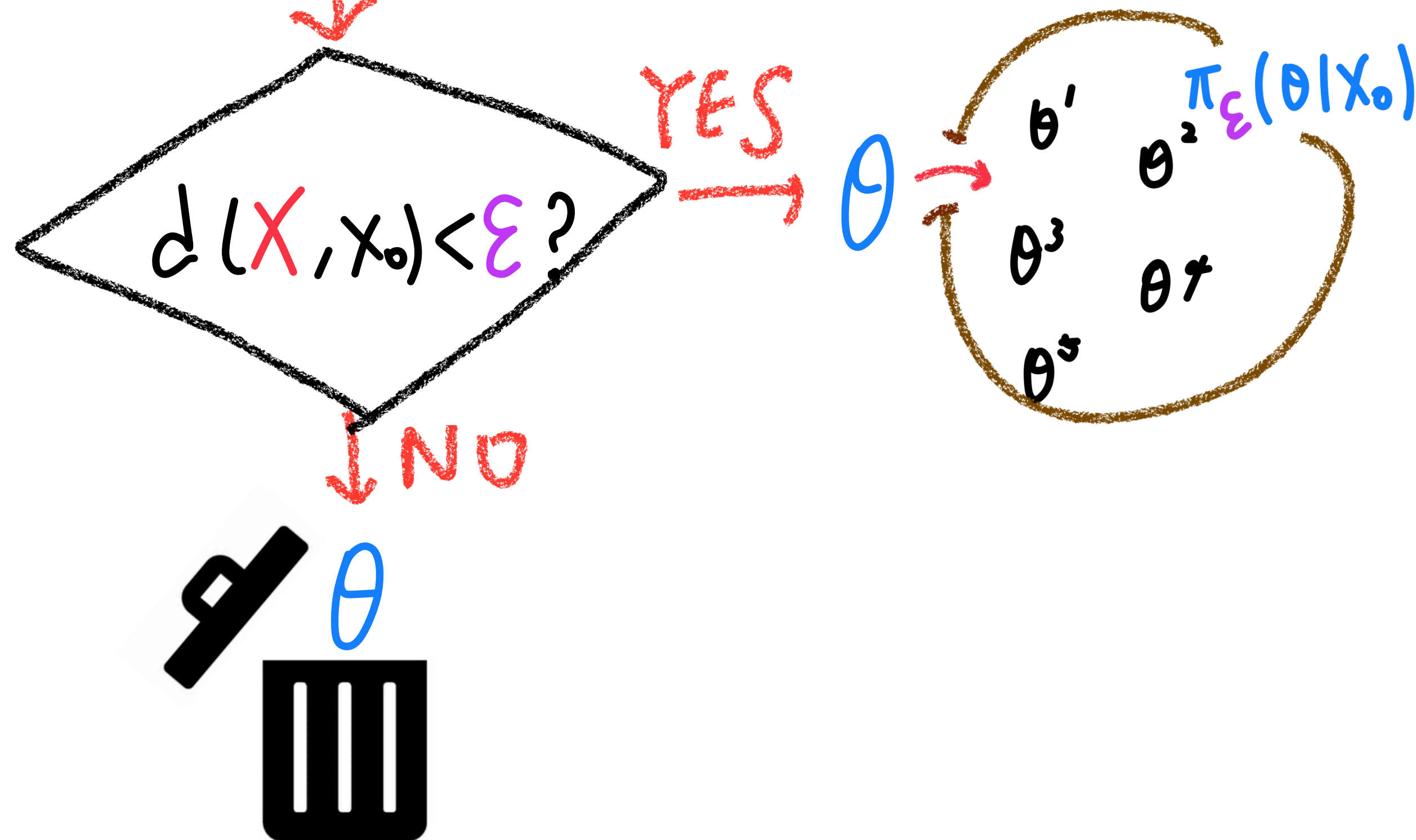
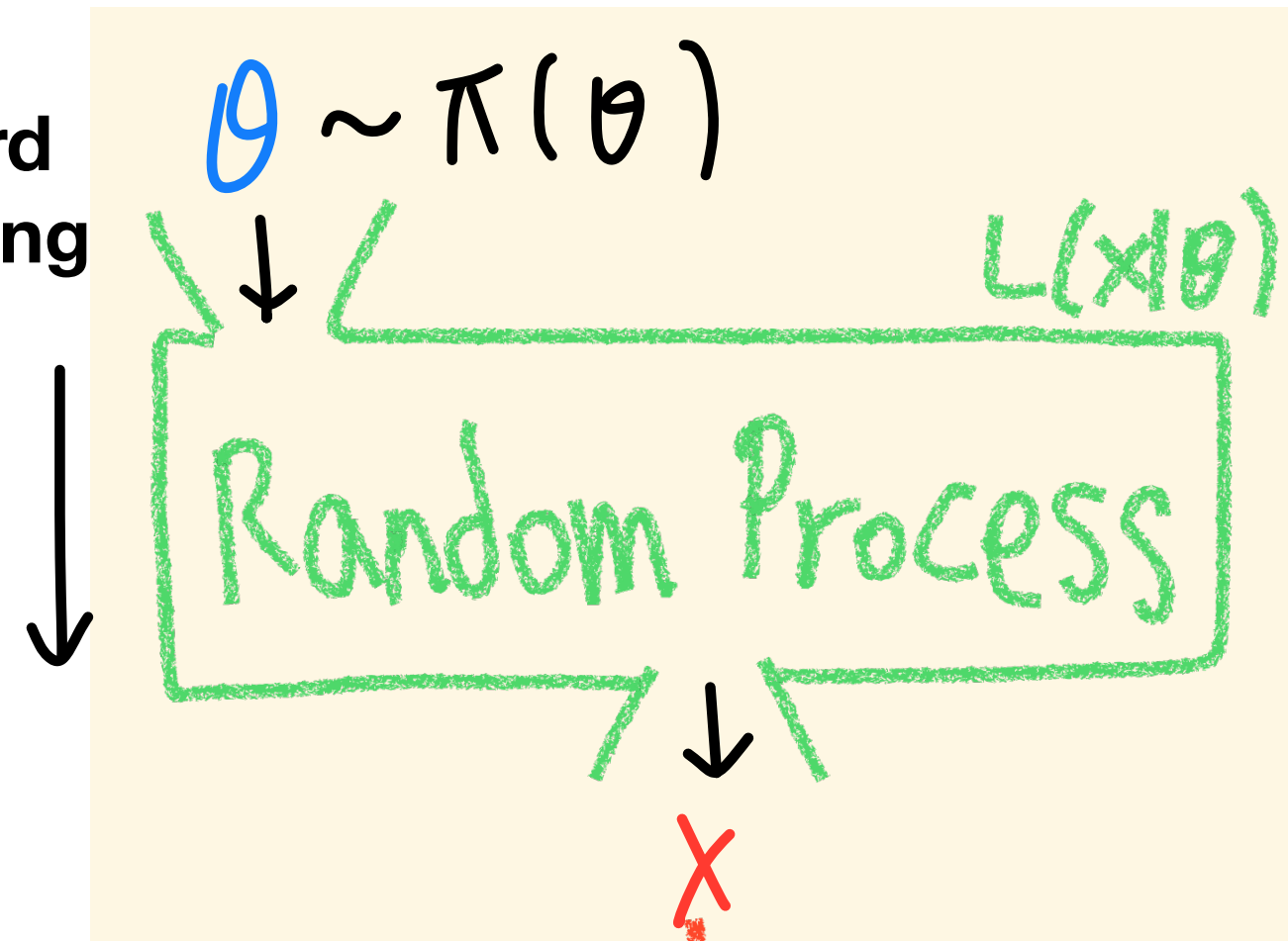
Likelihood given : MCMC $\rightarrow \pi(\theta | X) \propto L(X | \theta)\pi(\theta)$

Likelihood unavailable: **ABC** - use **forward sampling** (simulation)

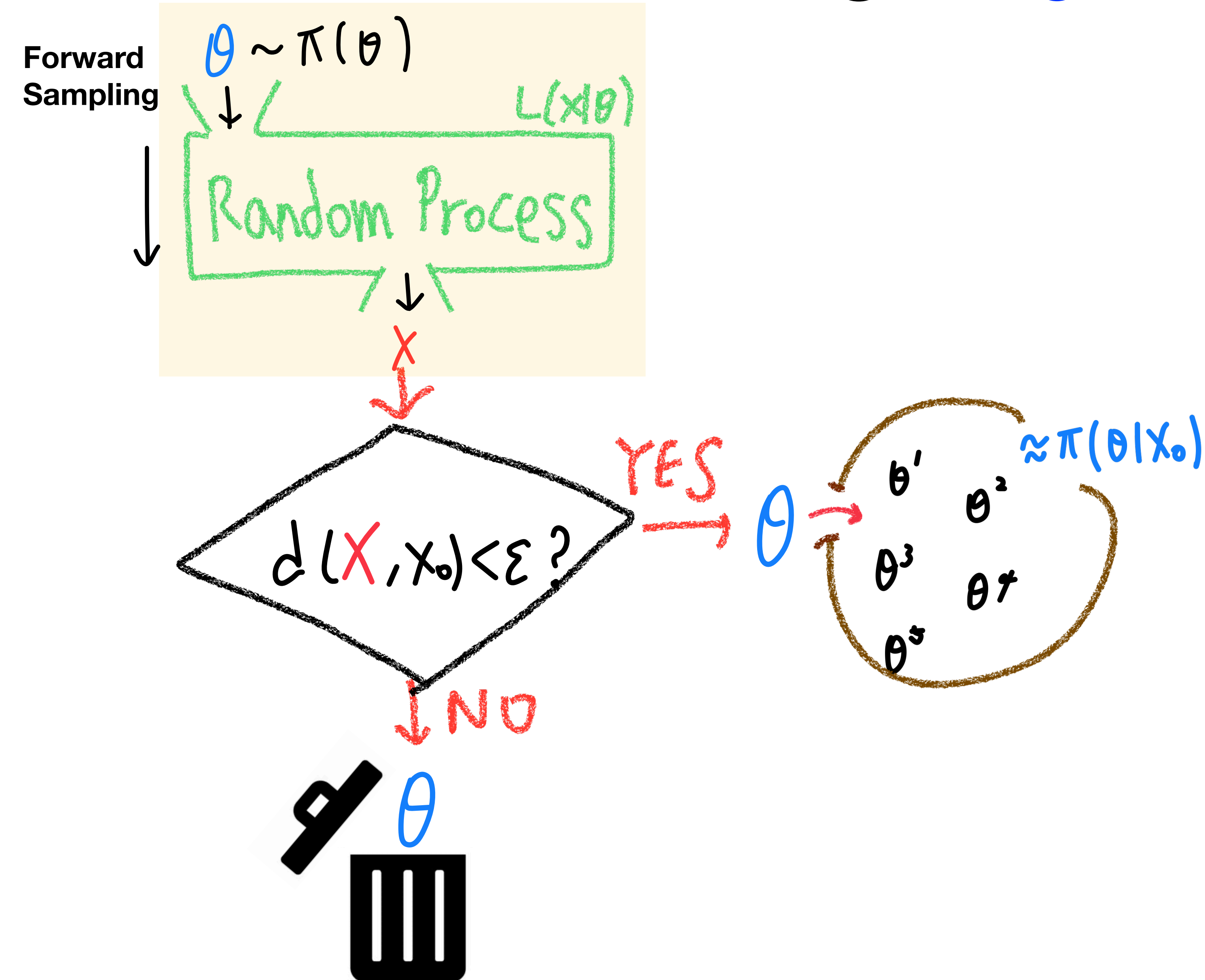
ABC (Approximate Bayesian Computation)

$$\pi_\varepsilon(\theta | X) \xrightarrow{\varepsilon \rightarrow 0} \pi(\theta | X)$$

Forward Sampling



ABC Dilemma



Small ϵ :

Sample quality \uparrow

Efficiency (acceptance) \downarrow

Large ϵ :

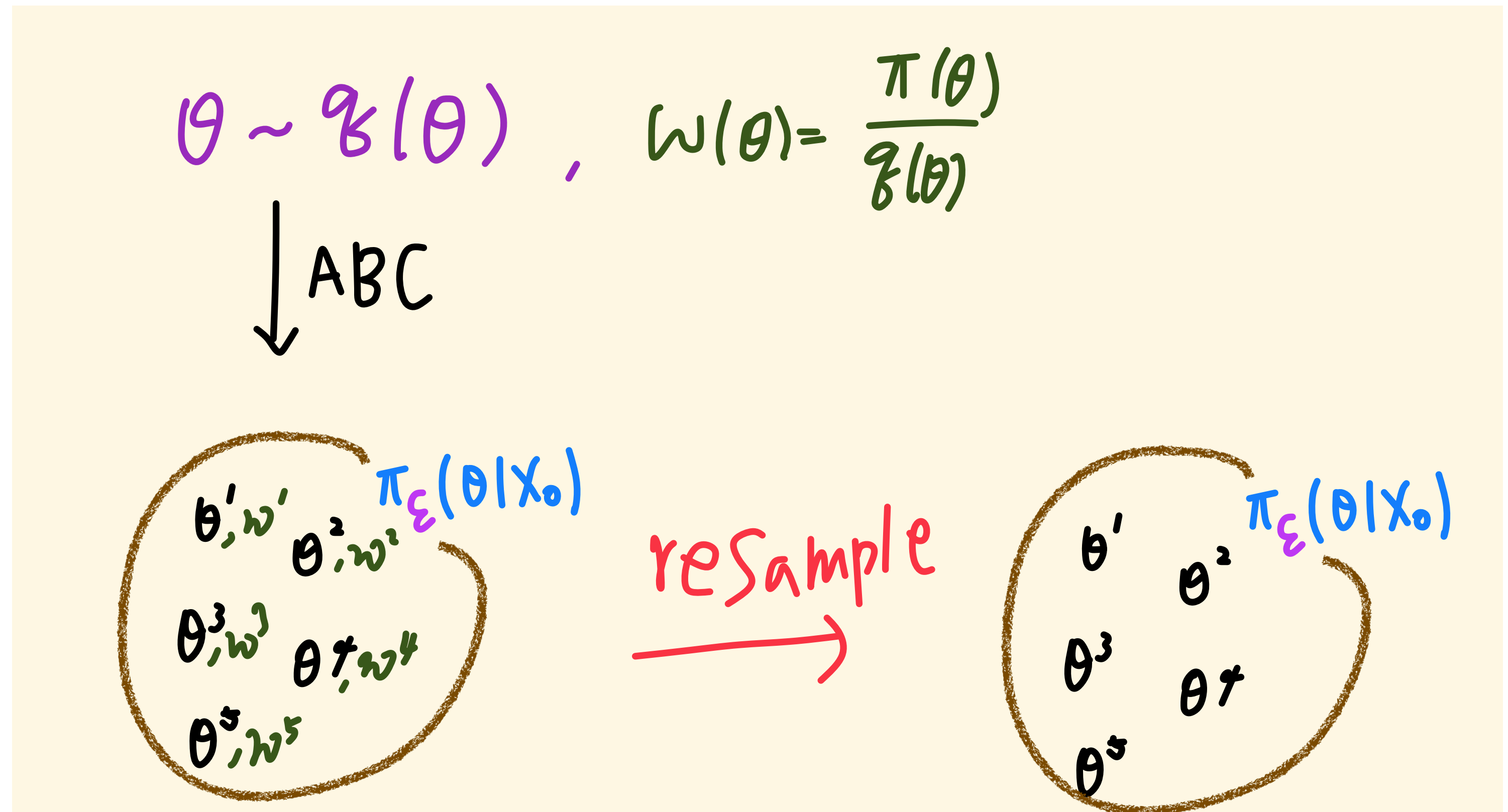
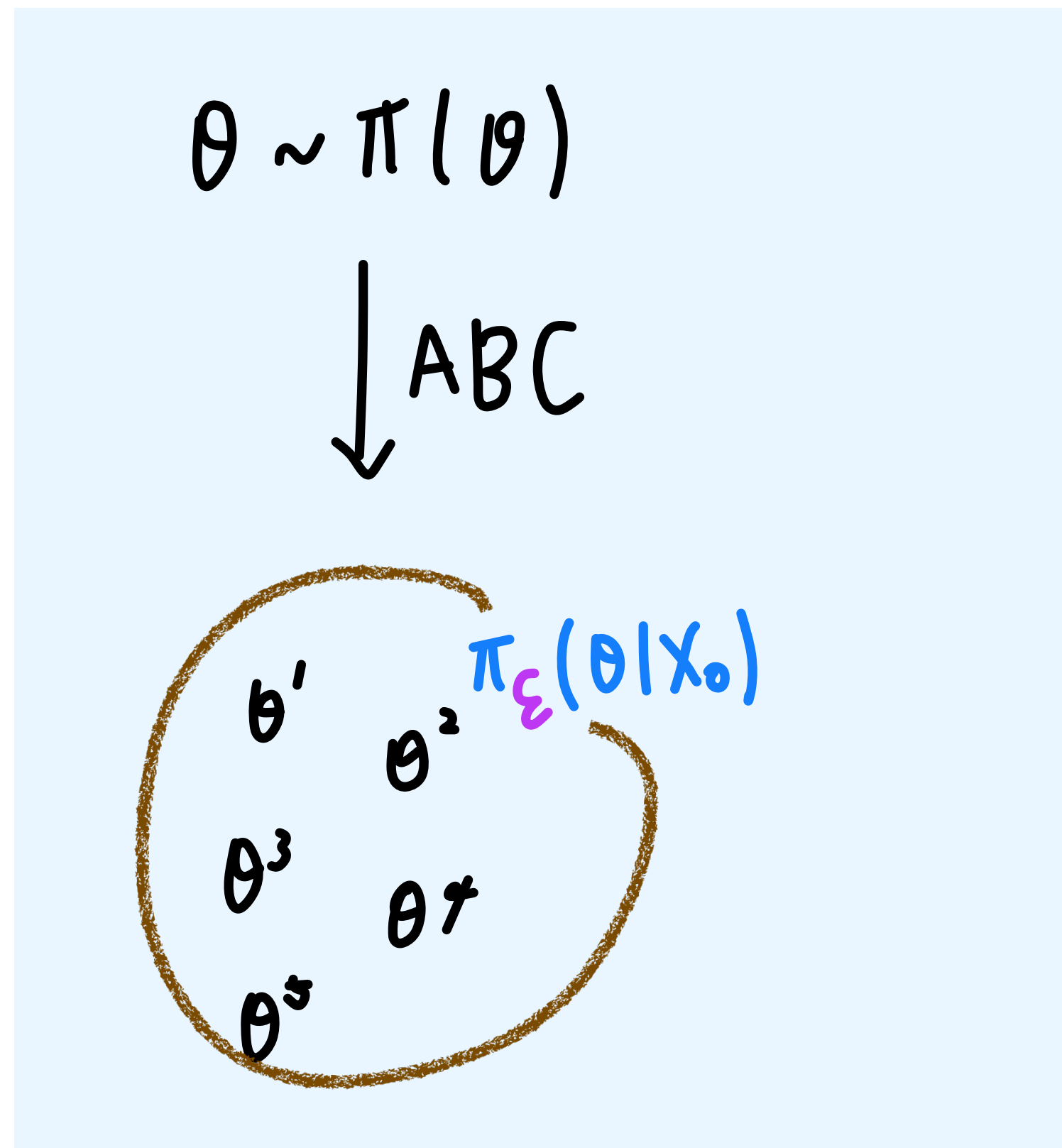
Sample quality \downarrow

Efficiency (acceptance) \uparrow

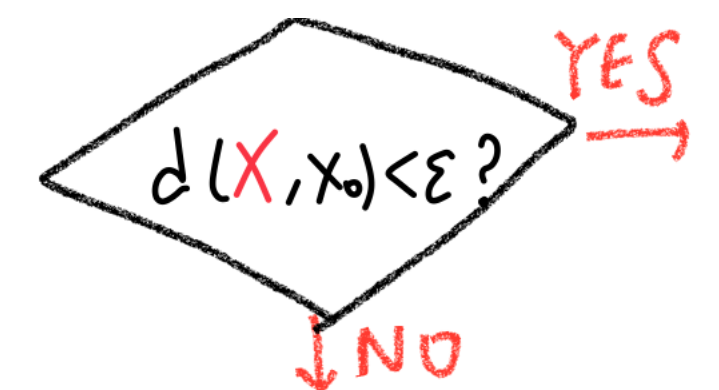
Goal: Query Efficient ABC

Small ϵ and acceptance \uparrow

Importance weighted ABC



We will learn proposal $q(\theta)$ can be learned **actively** by the history (

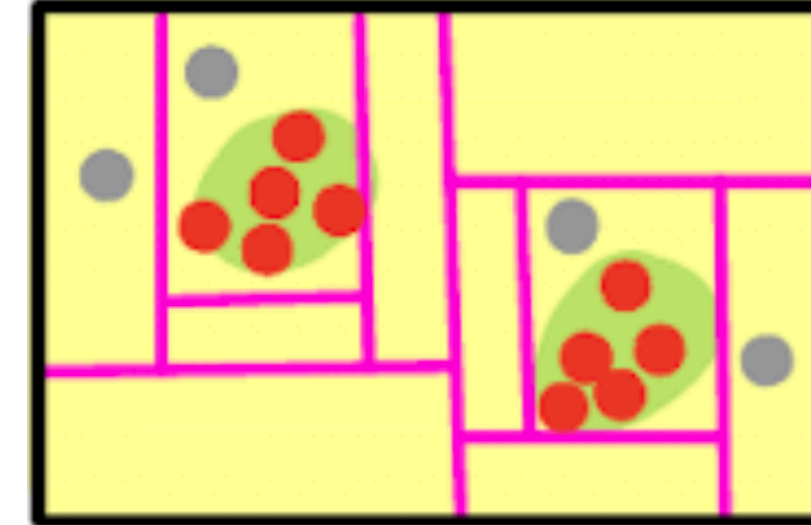
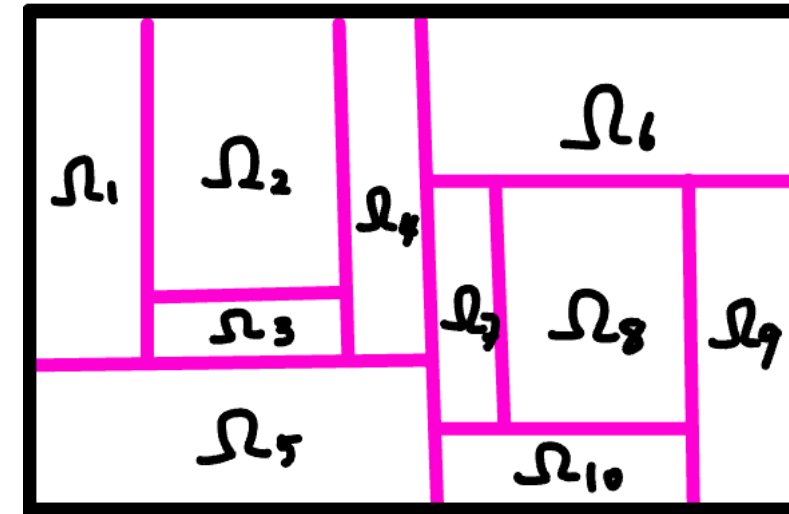
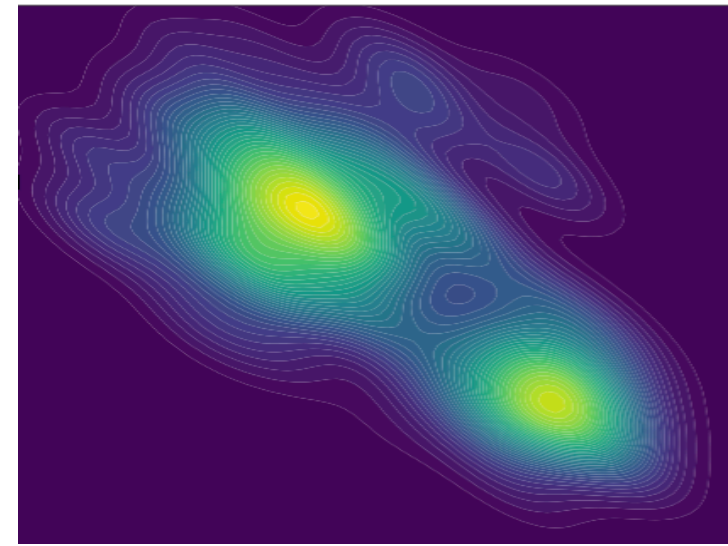


)

Our Approach

1. Partition Perspective

True Posterior



$$q(\theta) = \sum_{k=1}^K q_k \times \pi(\theta | \Omega_k) \mathbb{1}\{\theta \in \Omega_k\}, \text{ where } \Theta = \cup_{k=1}^K \Omega_k$$

2. Active Learning perspective

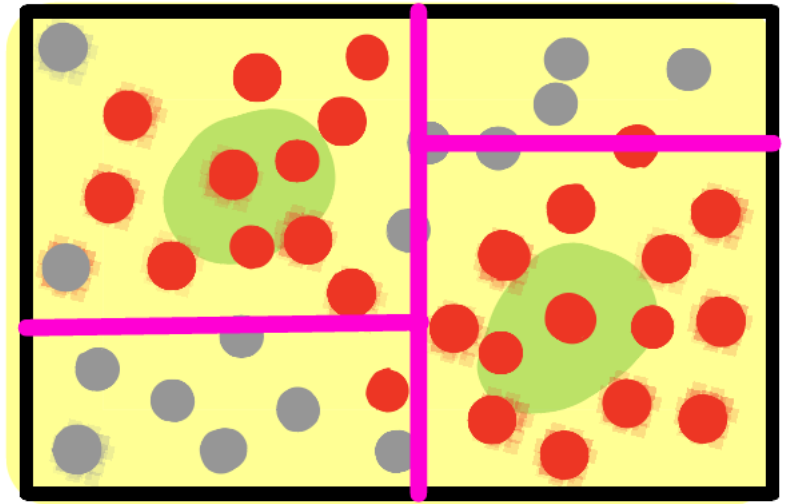
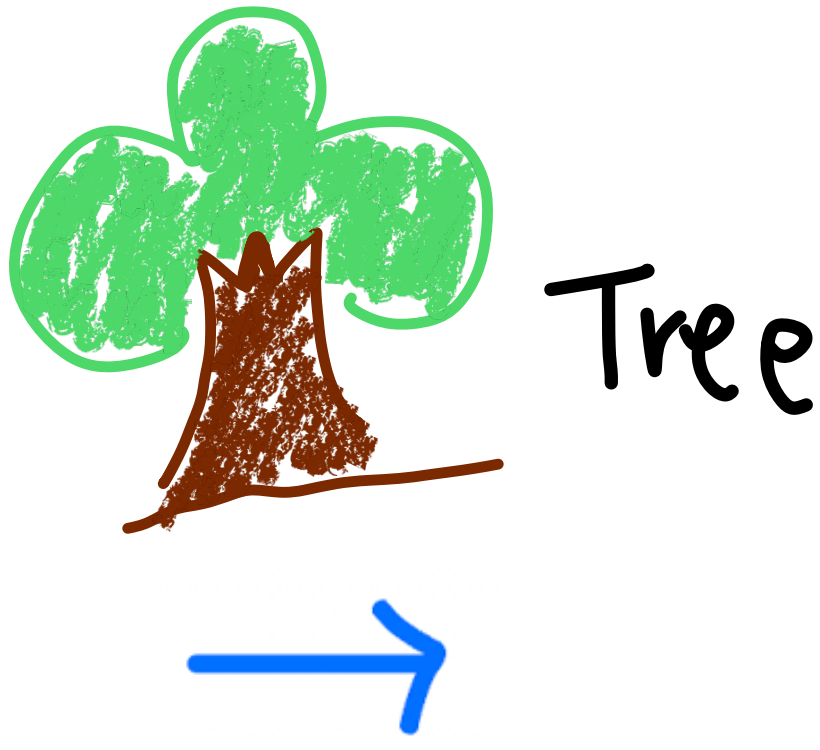
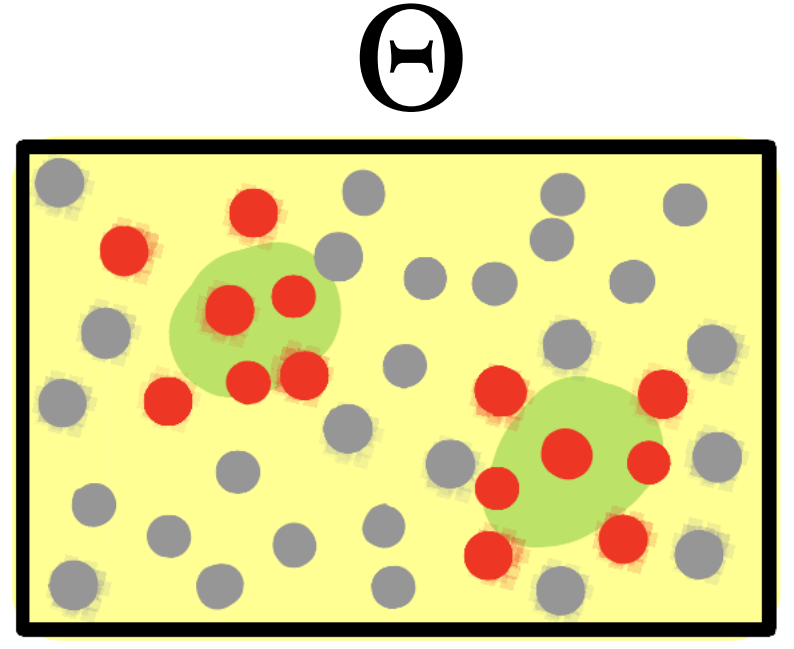
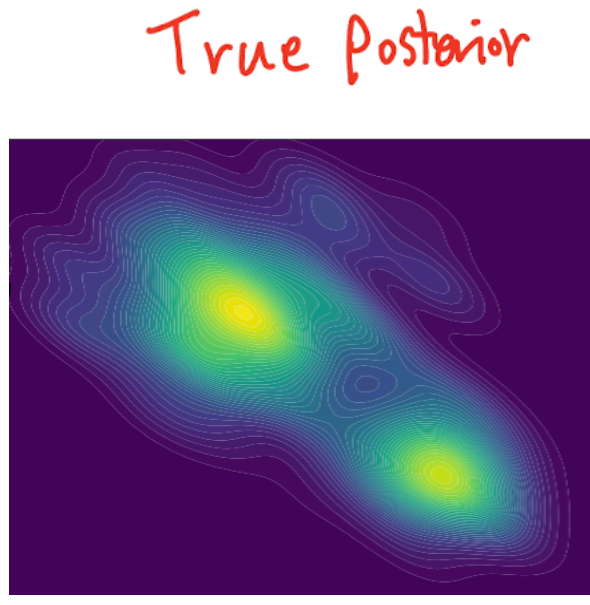
Question 1) How to get partition? (Outer Loop)

Question 2) How to get q_k ? (Inner Loop)

Question 1) How to get partition?

-> Tree fitting in the outer loop

Outer Loop: Partitioning by



$$Y^{(t)} = \text{ABC}(X^t, X_0, \epsilon)$$

We will learn by $Y^{(t)} = \text{ABC}(X^t, X_0) =$

$d(X^t, X_0) < \epsilon?$

YES →

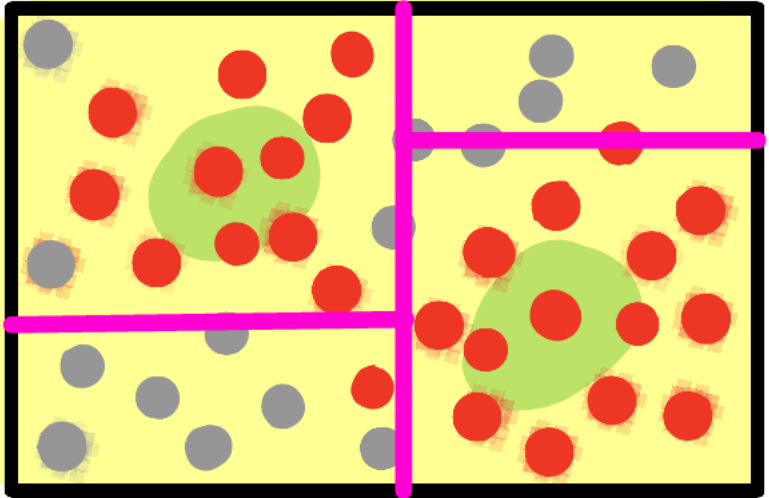
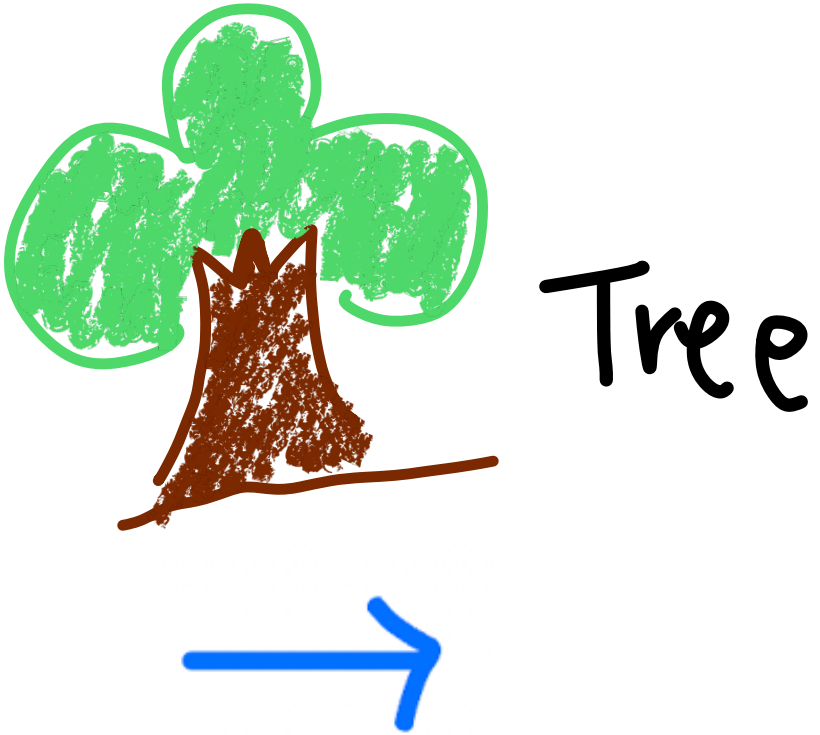
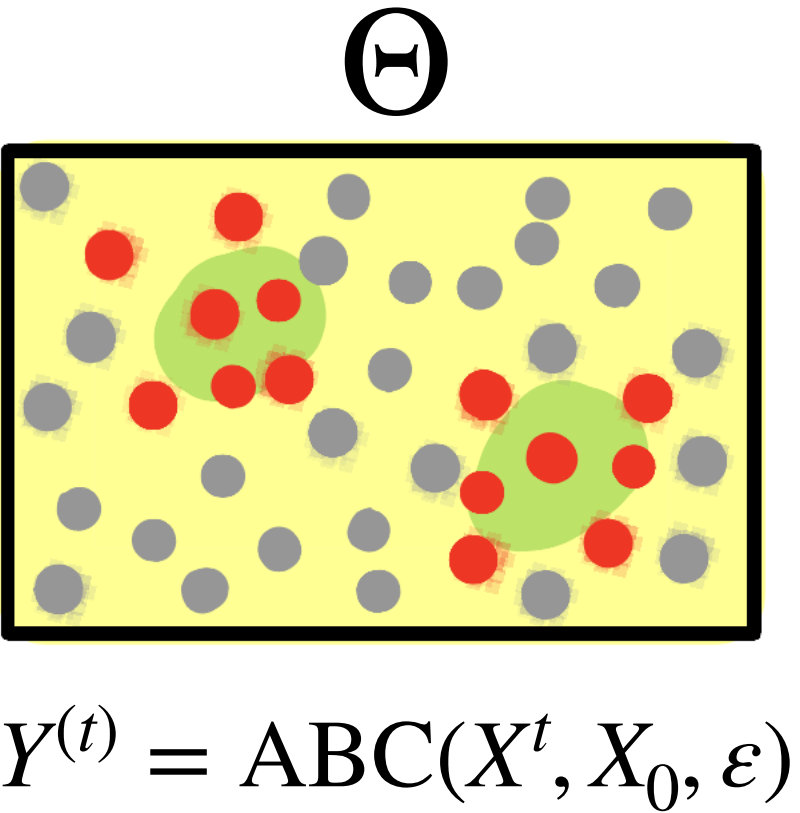
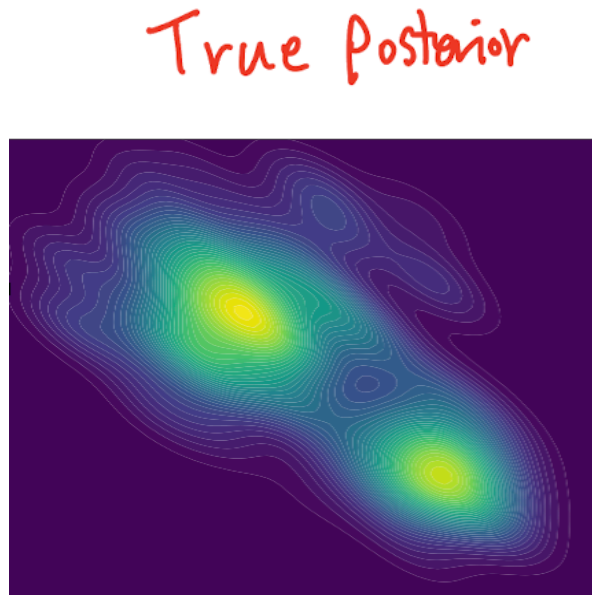
1

↓ NO

0

$$\pi_\epsilon(\theta | X^t) \propto \pi(\theta) \mathbb{E}_{X^t|\theta}[\text{ABC}(X^t, X_0, \epsilon)]$$

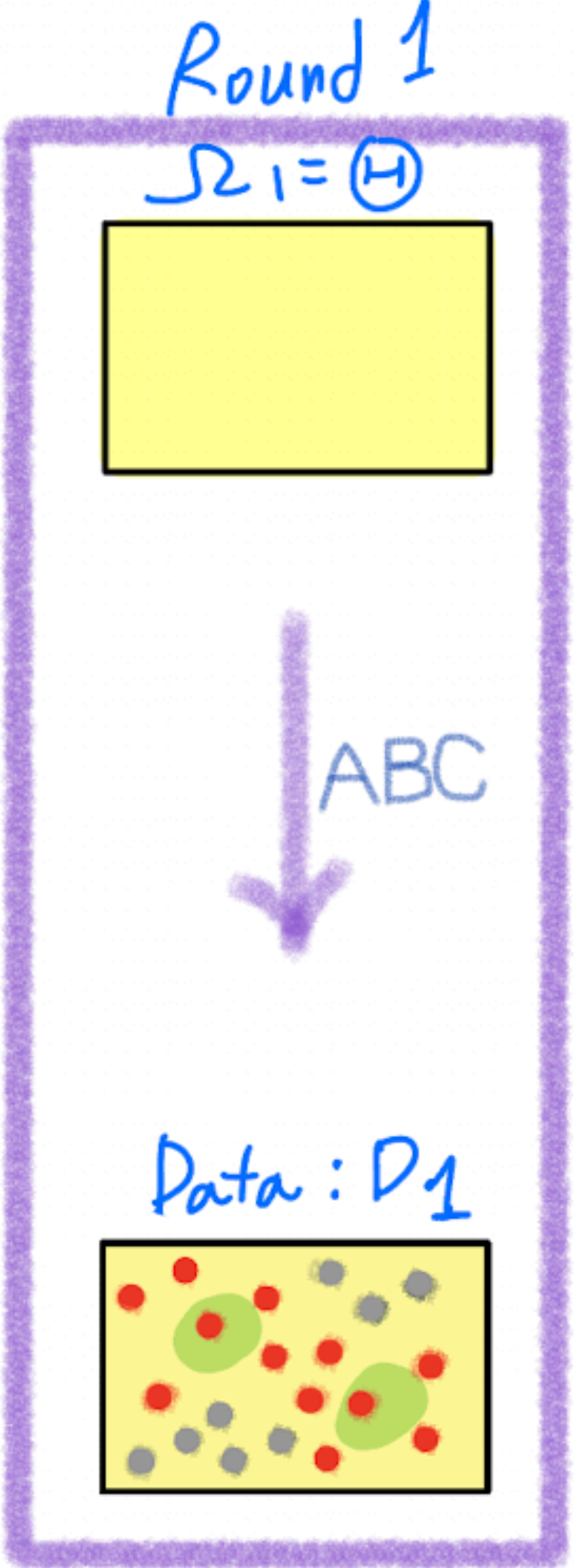
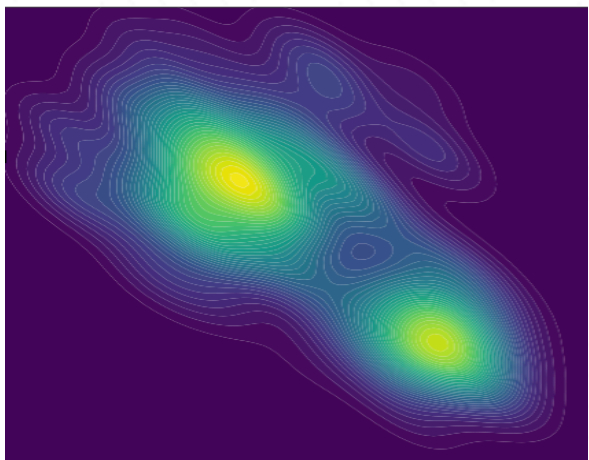
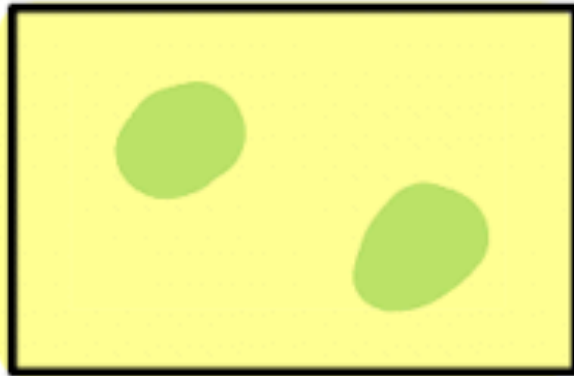
Outer Loop: Partitioning by



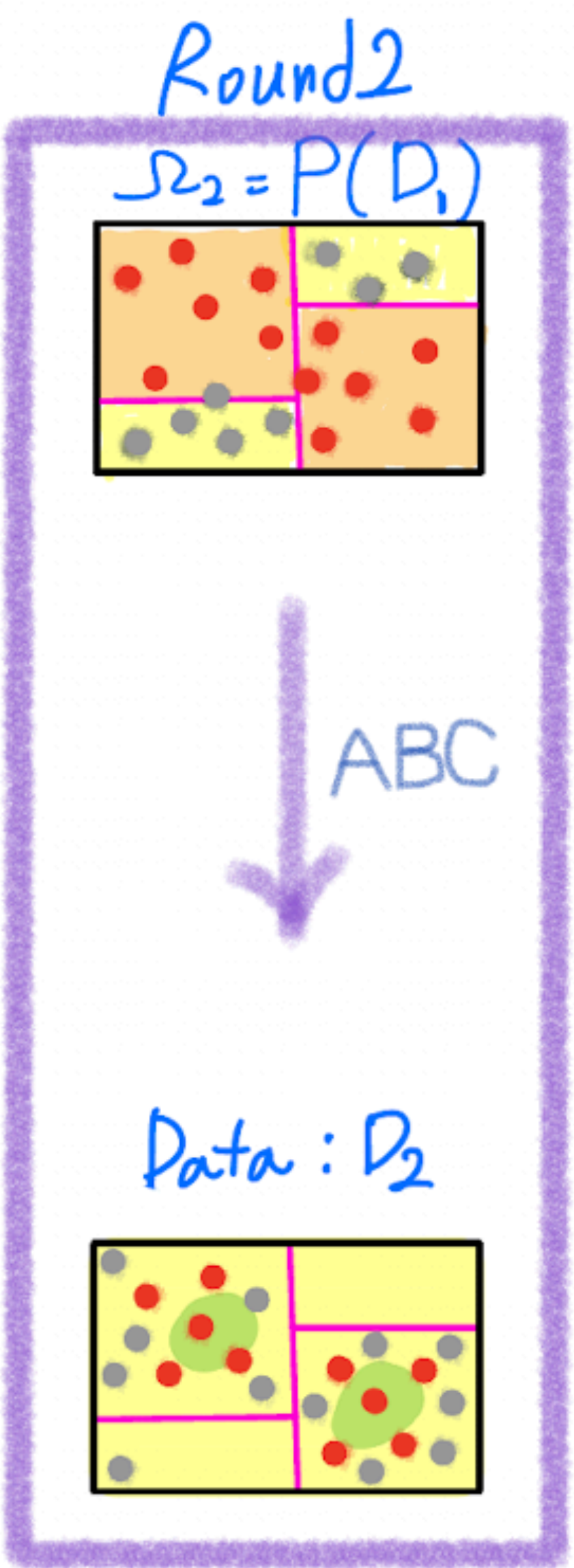
```
1 from sklearn.tree import DecisionTreeClassifier
2
3 tree_model = DecisionTreeClassifier()
4
5 tree_model.fit(thetas, Y)
```

Outer Loop

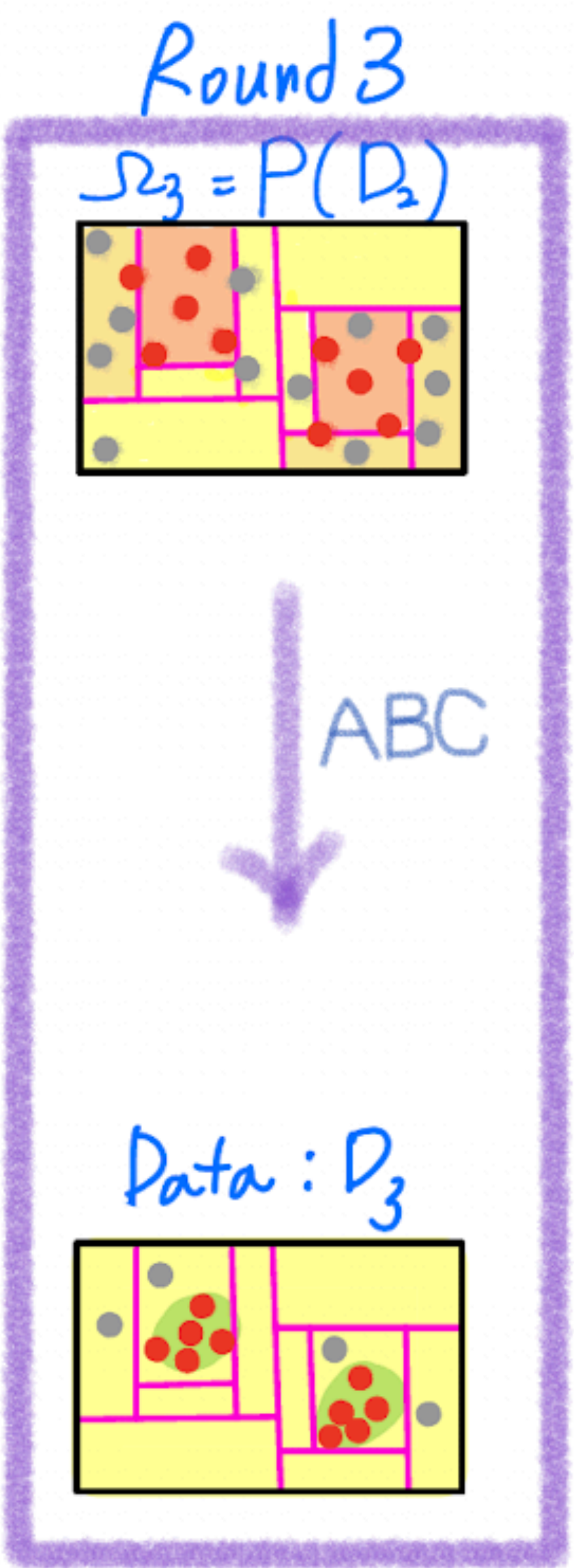
True Posterior



ξ_1



ξ_2

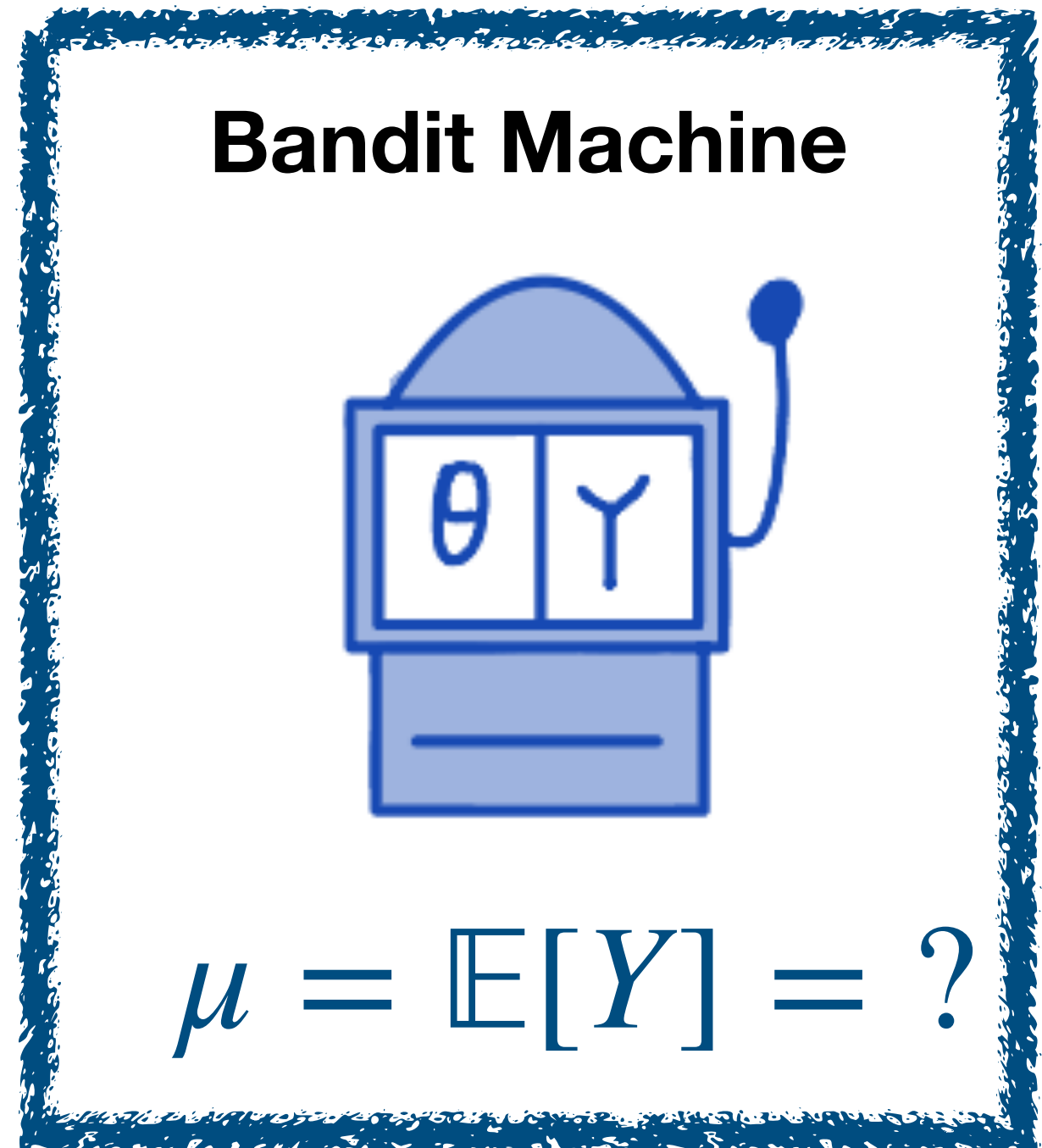


ξ_3

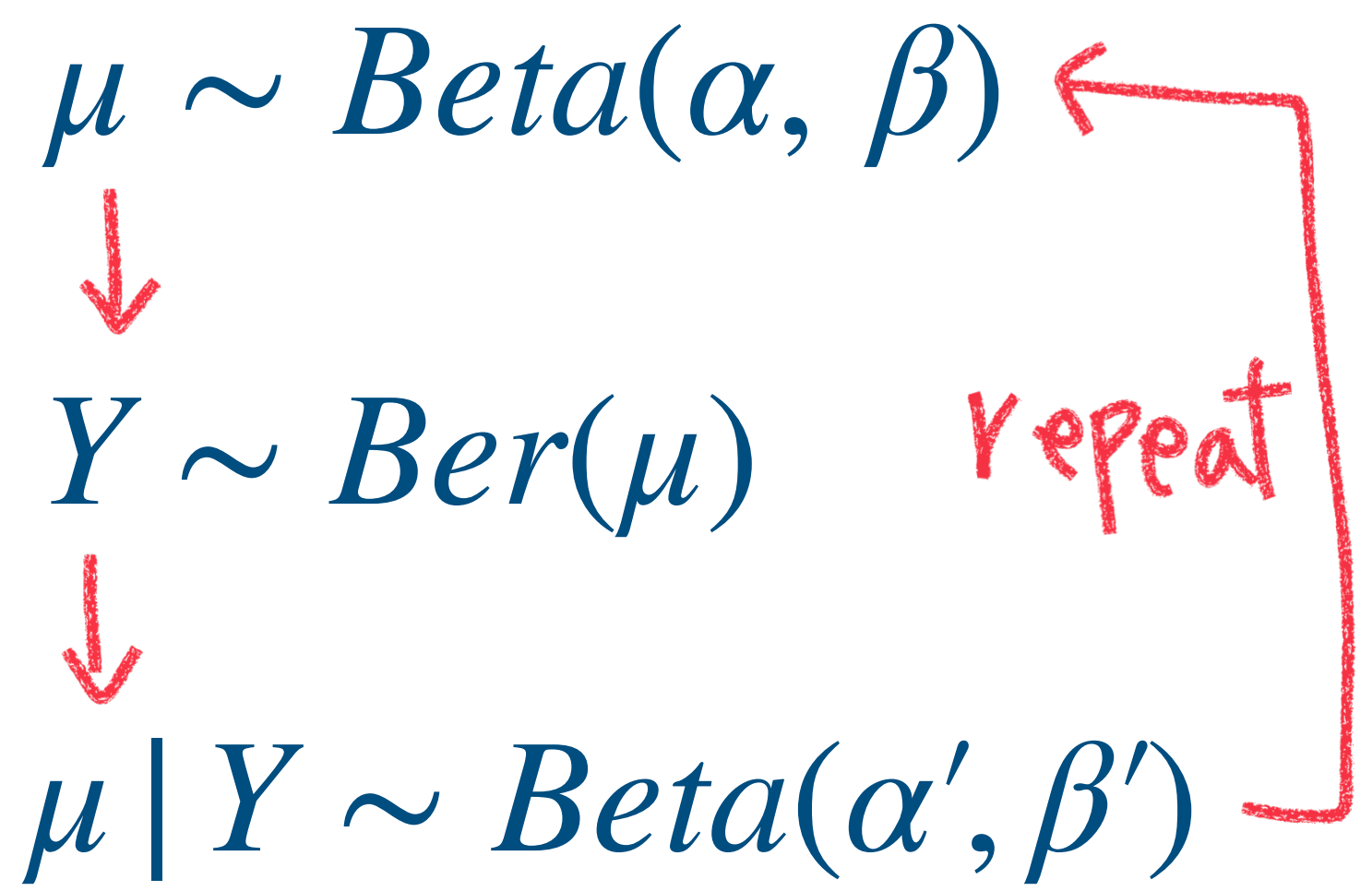
Question 2) How to get q_k ?

-> Thompson Sampling in the inner loop

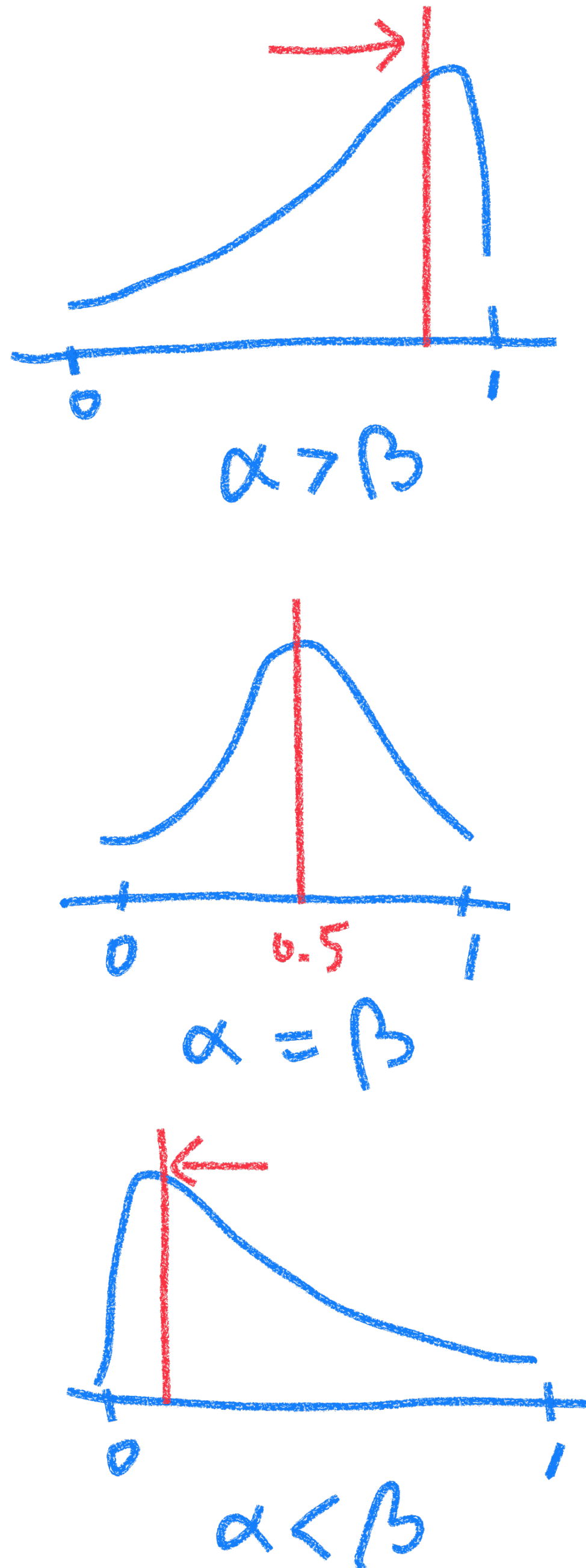
Multi-arm Thompson sampling



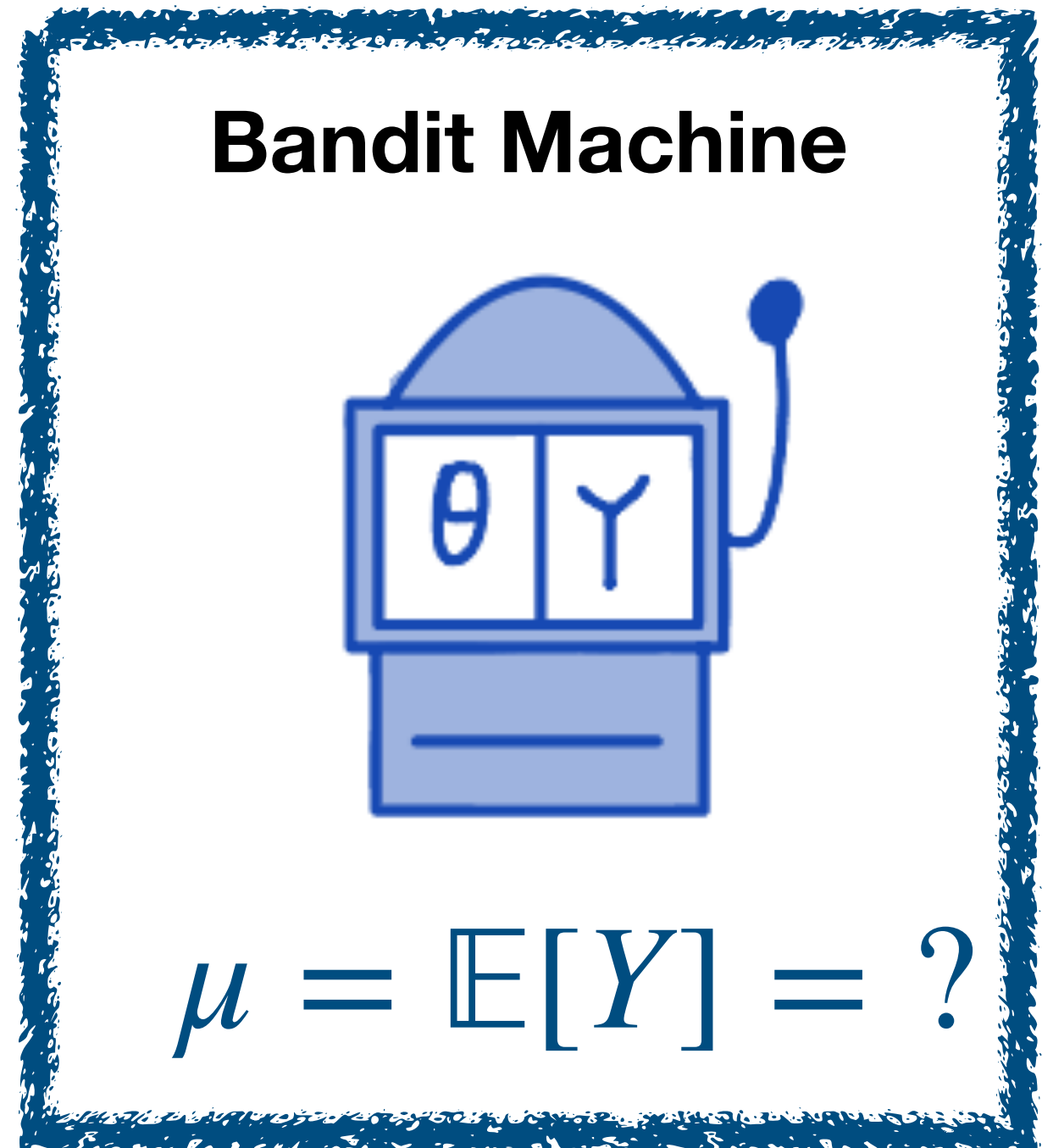
$$Y \in \{0,1\}$$



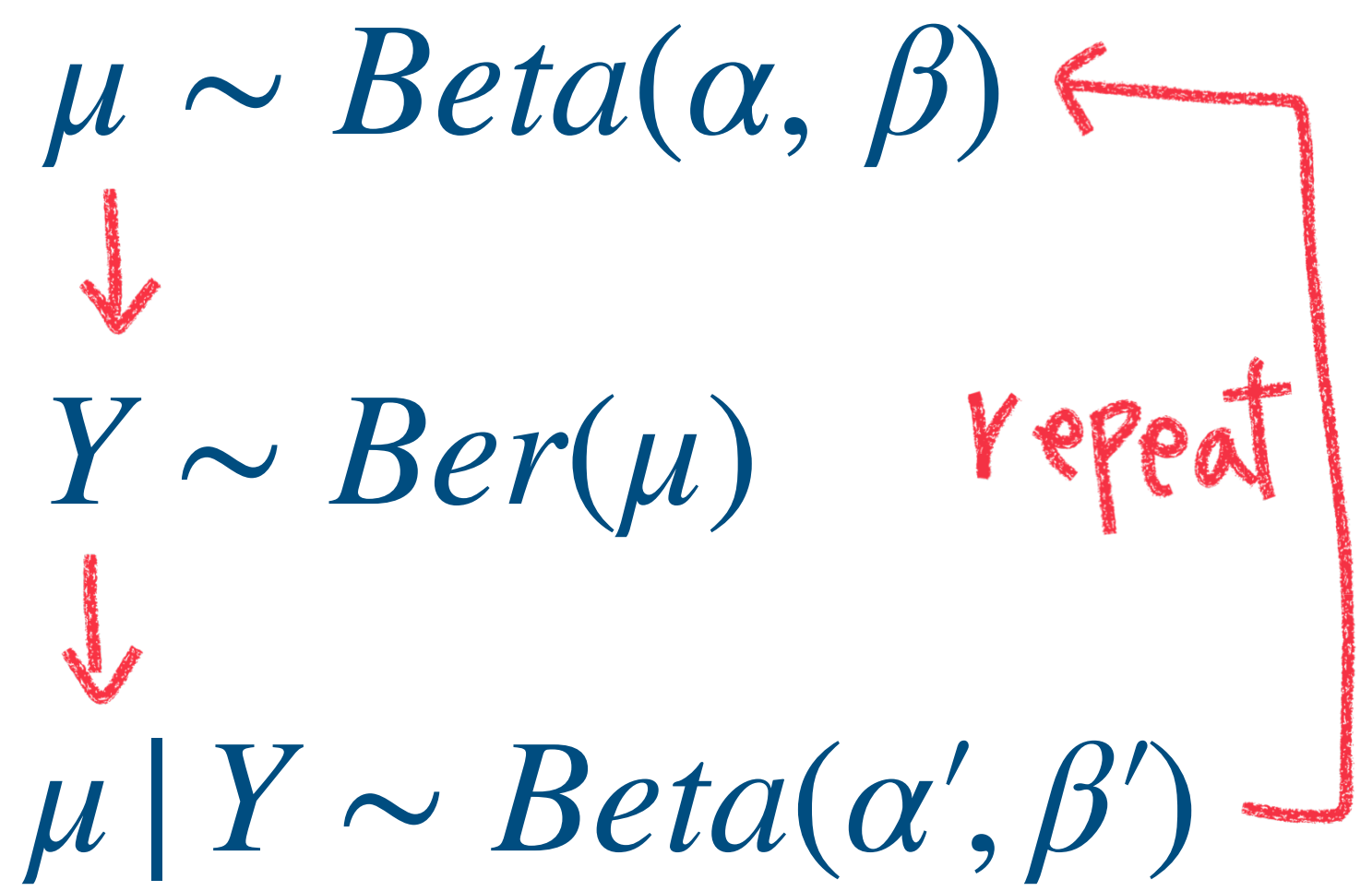
$$\alpha' = \alpha + Y$$
$$\beta' = \beta + (1 - Y)$$



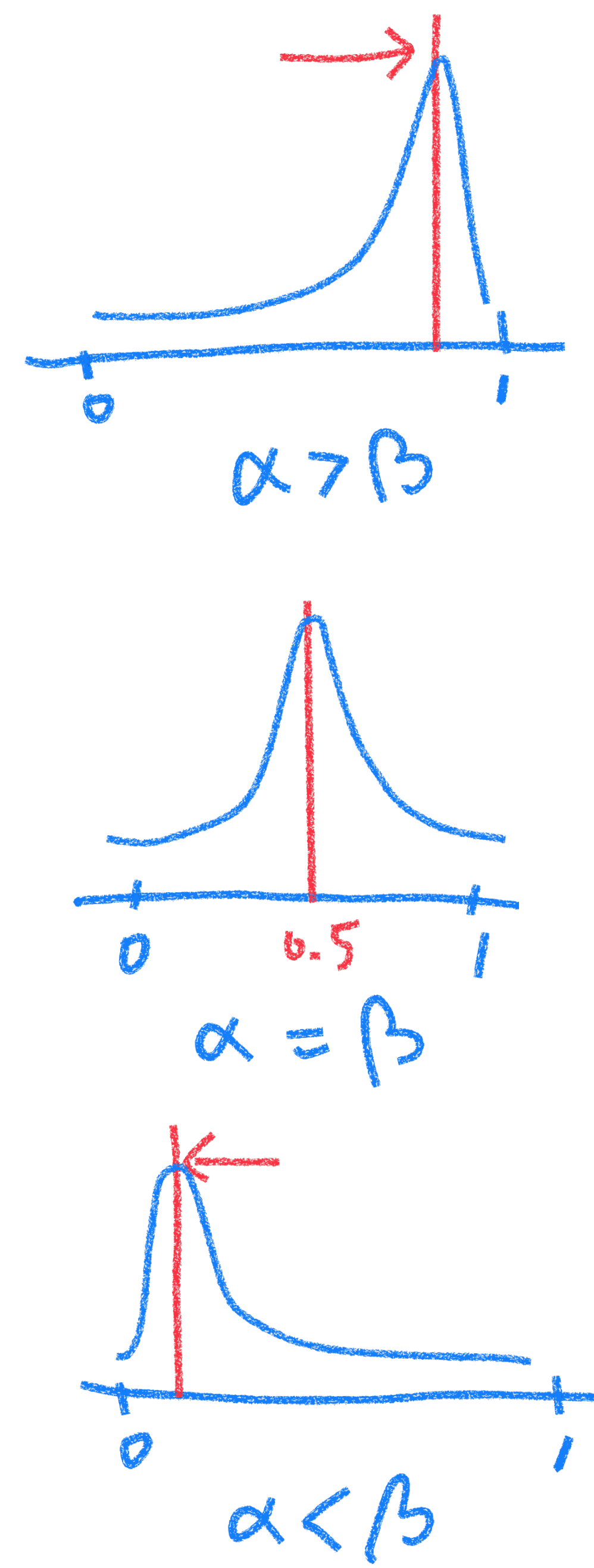
Multi-arm Thompson sampling



$$Y \in \{0,1\}$$

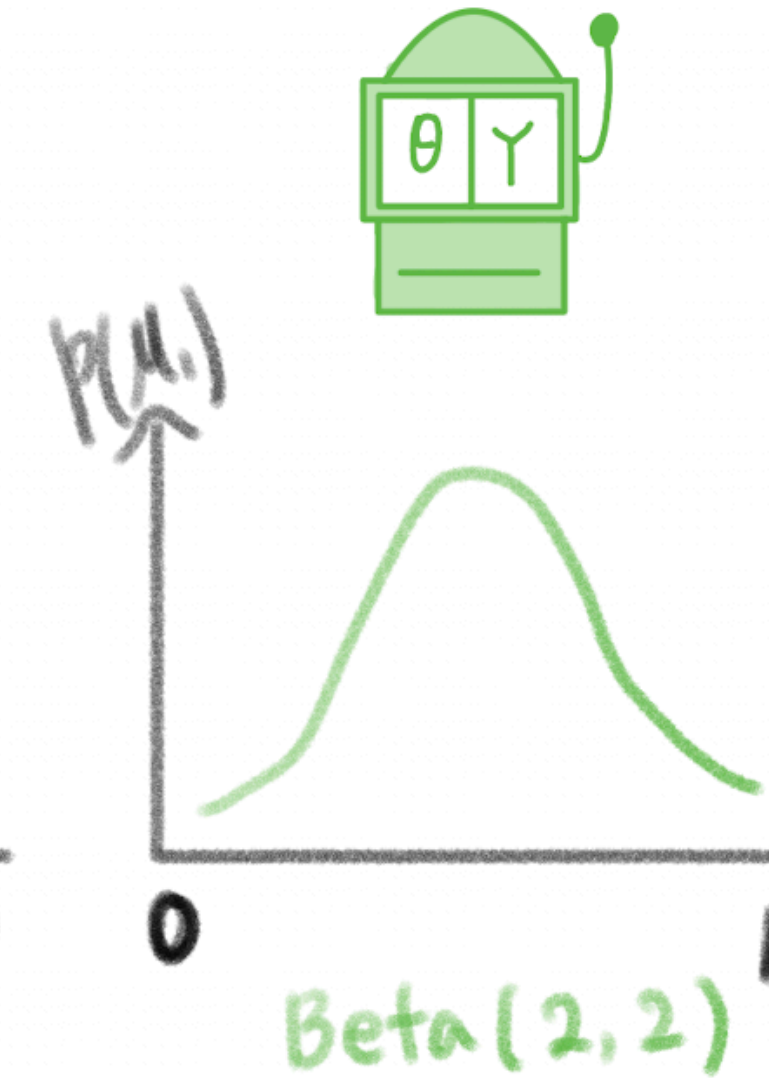
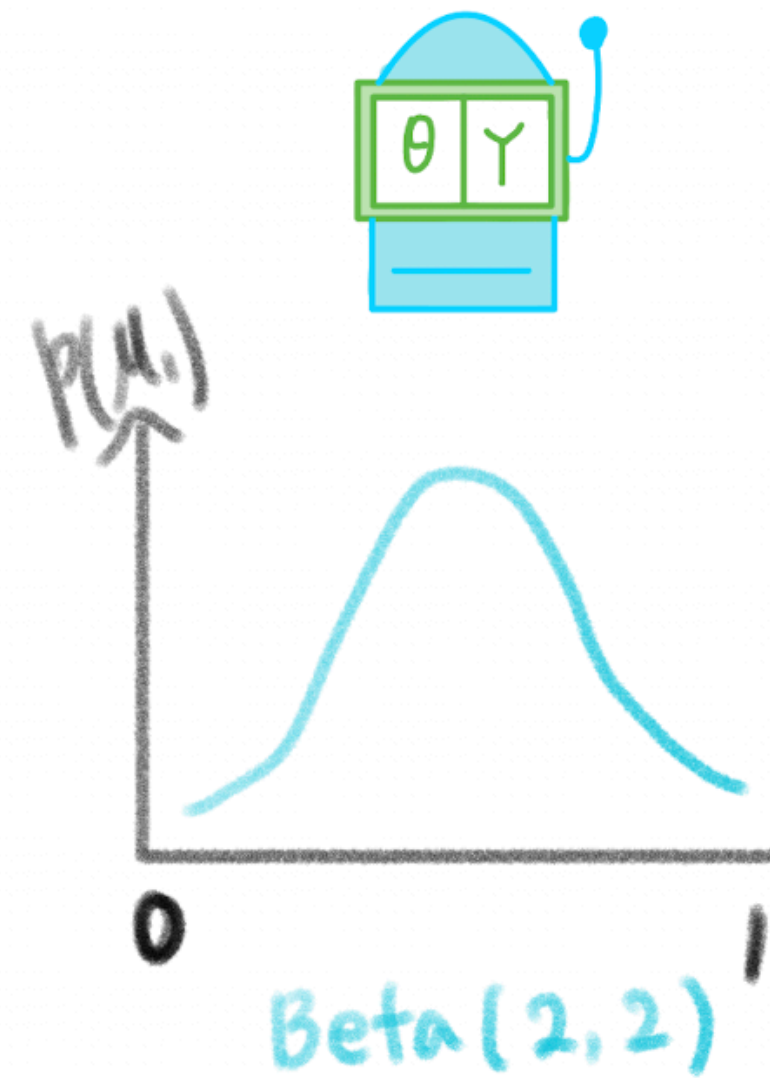
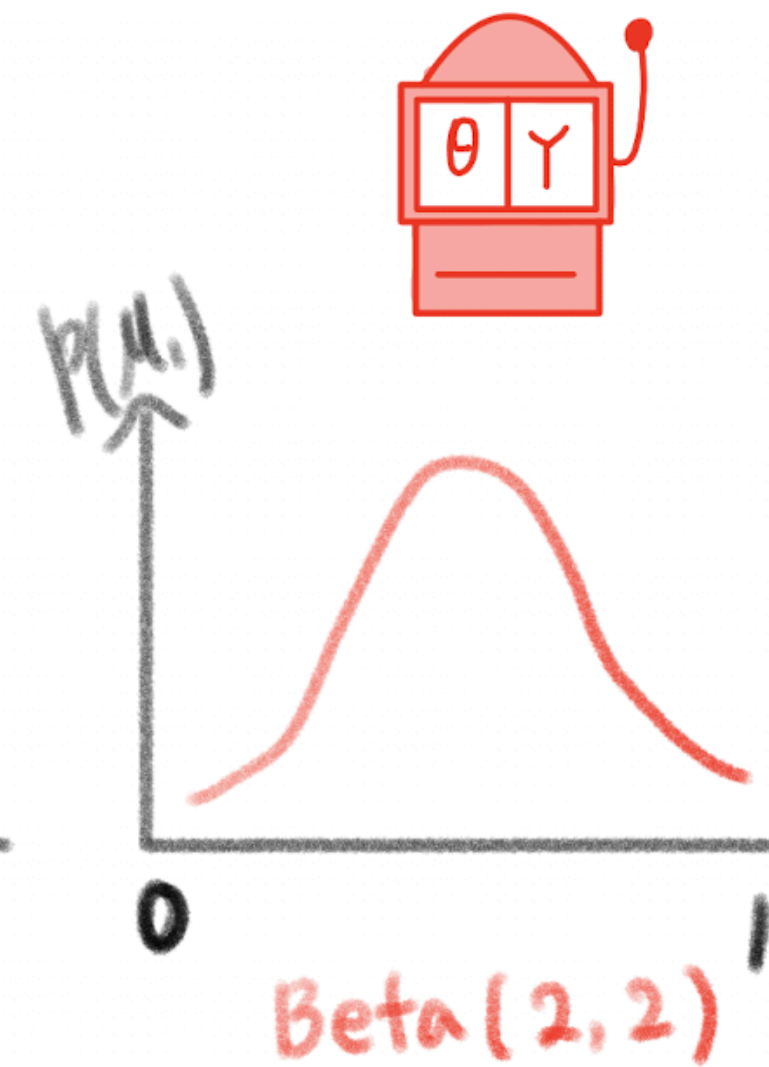
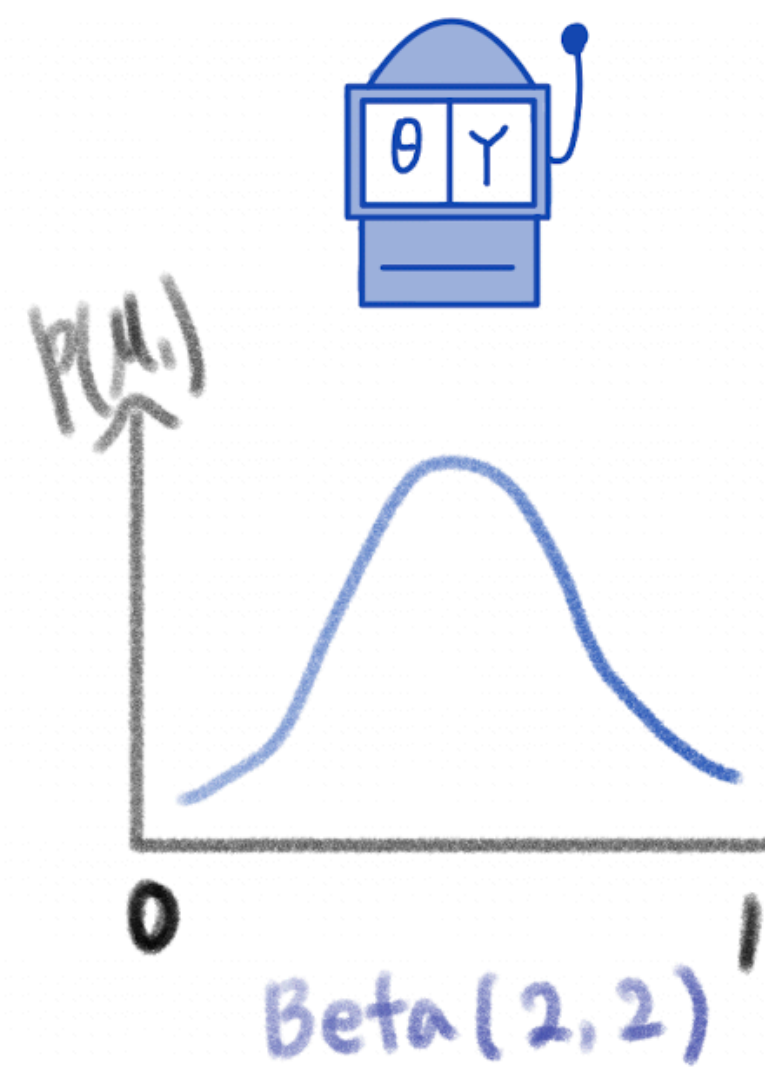
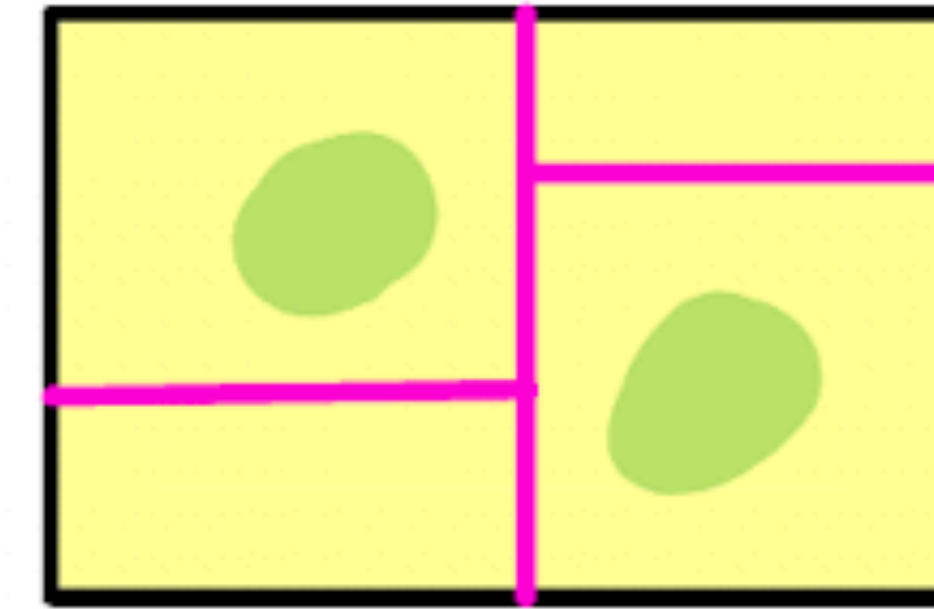
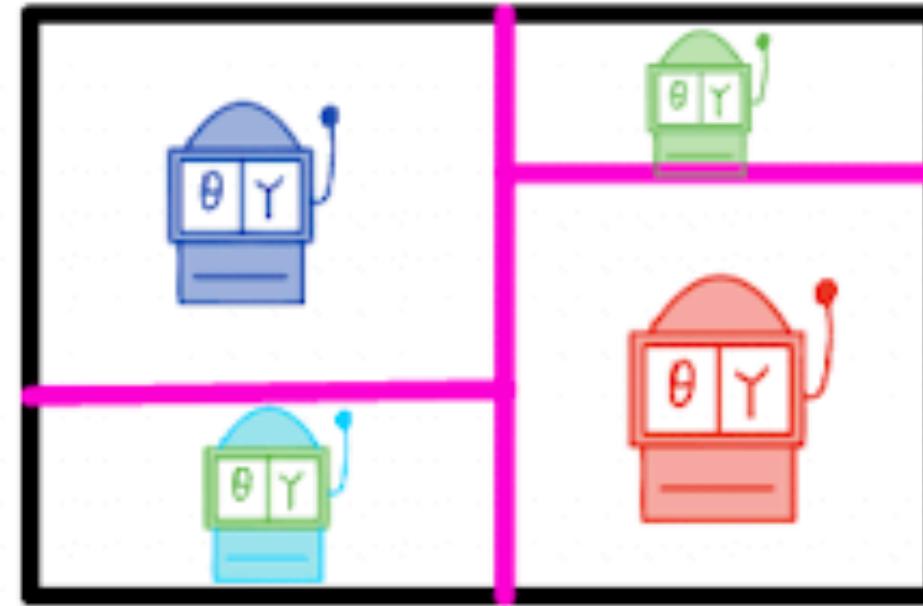


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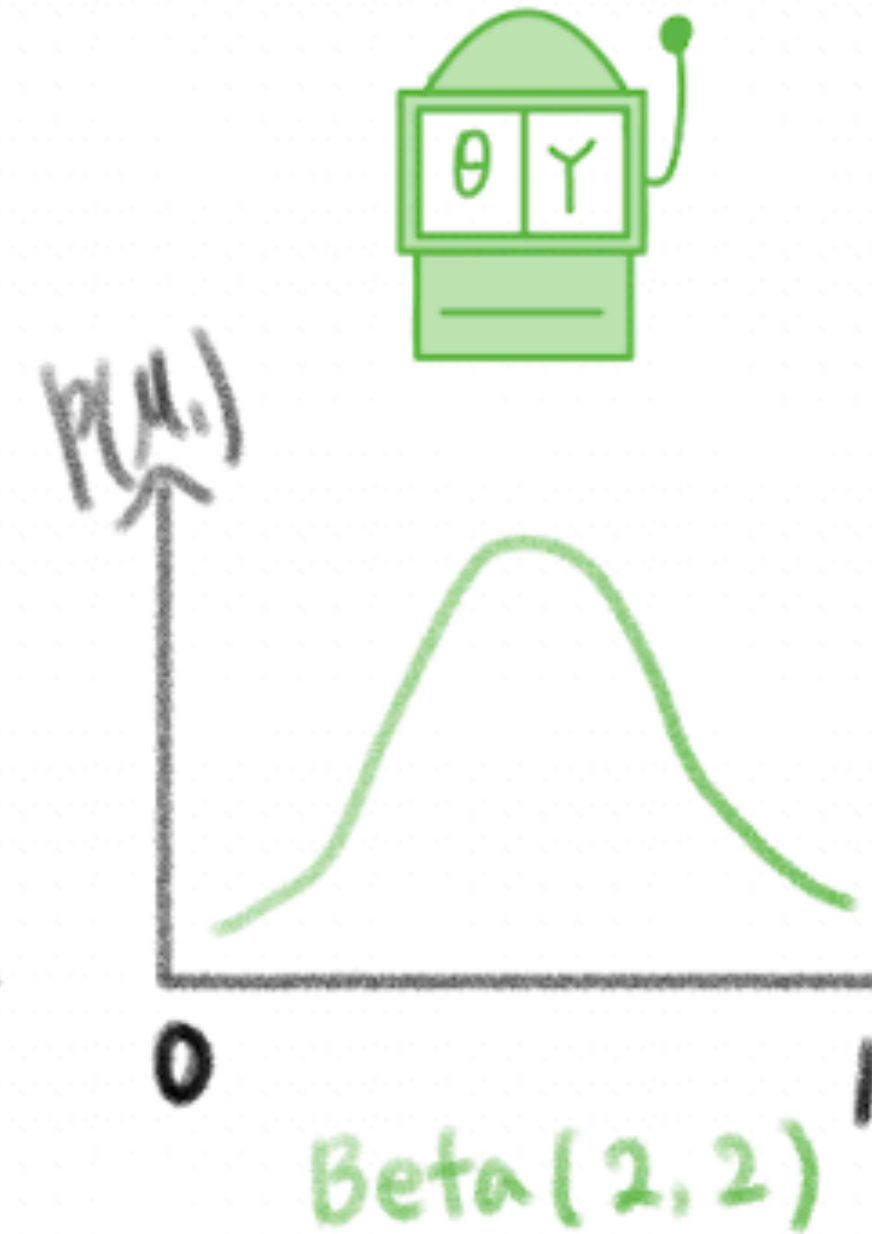
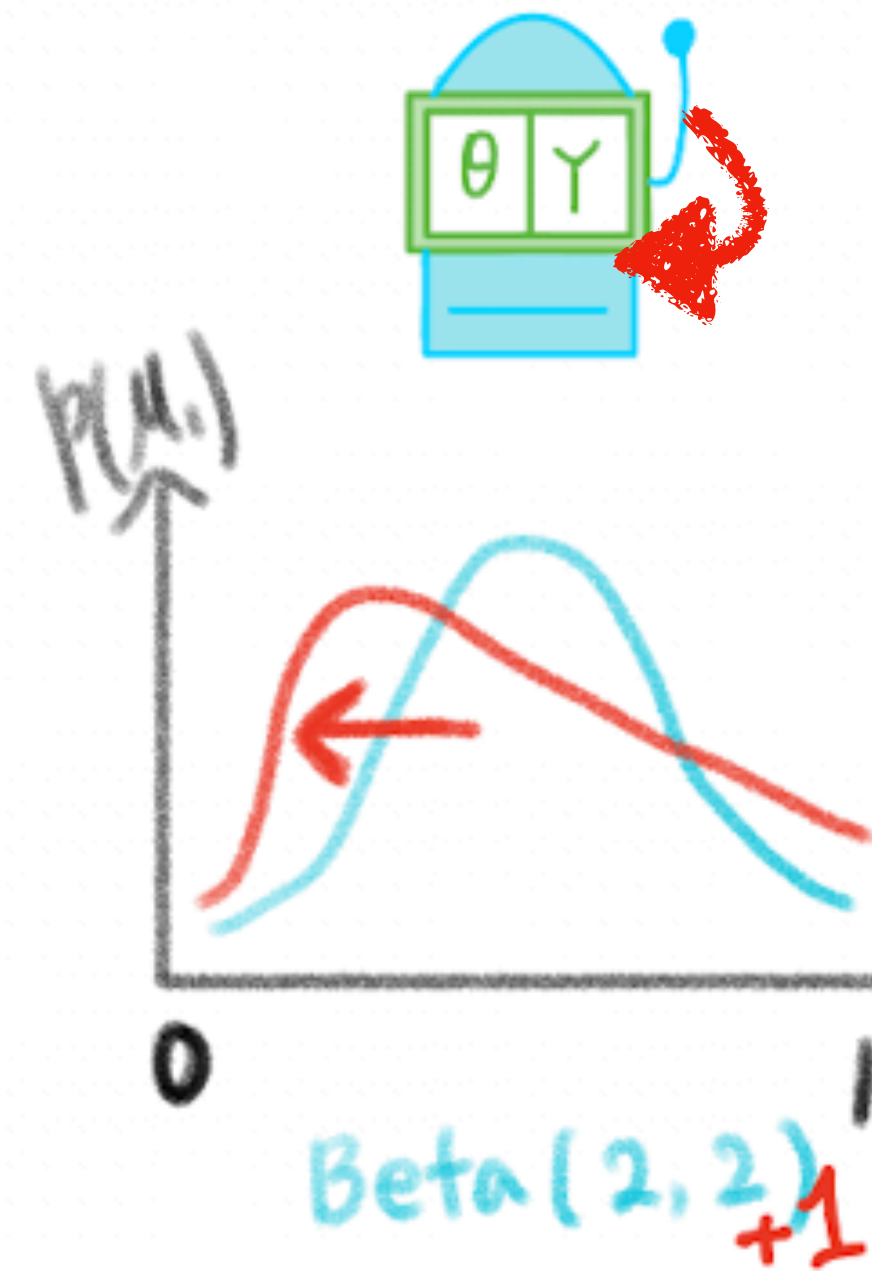
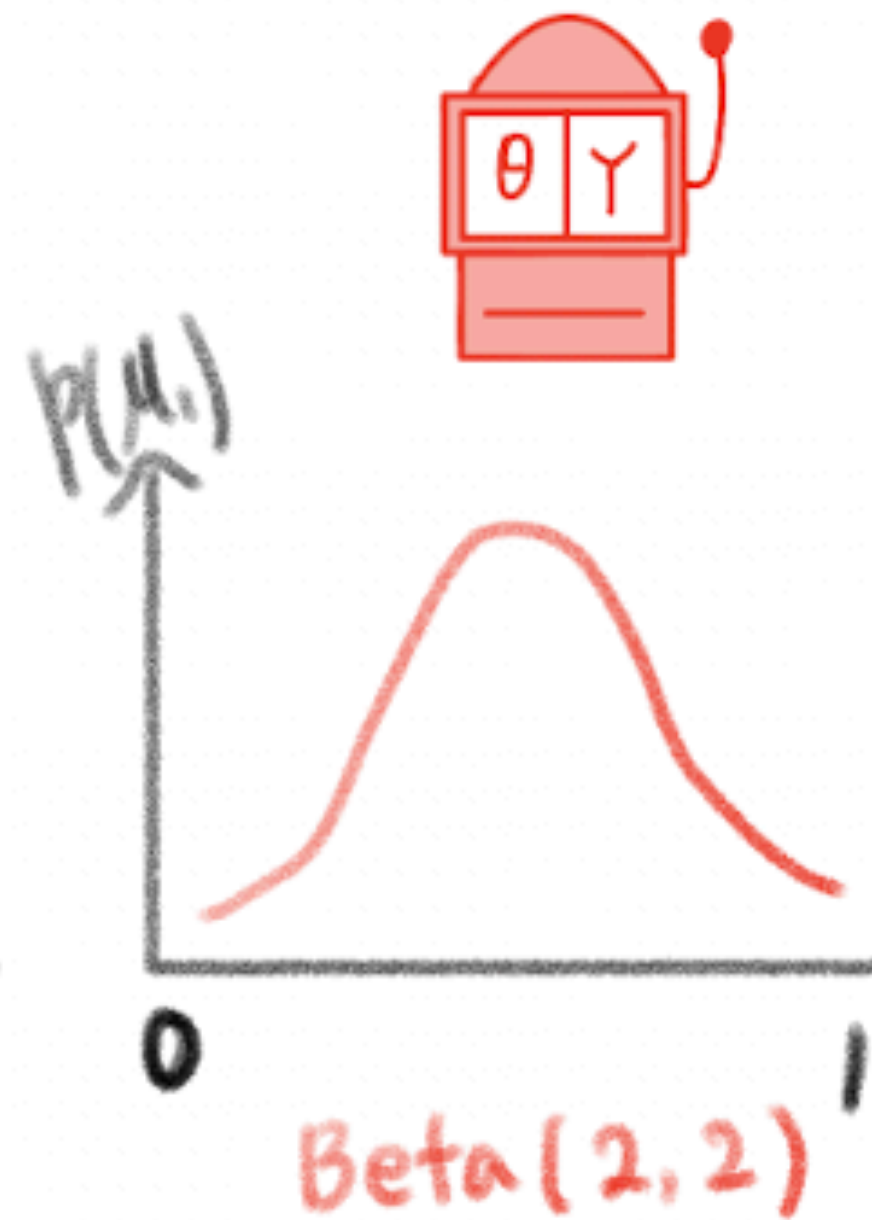
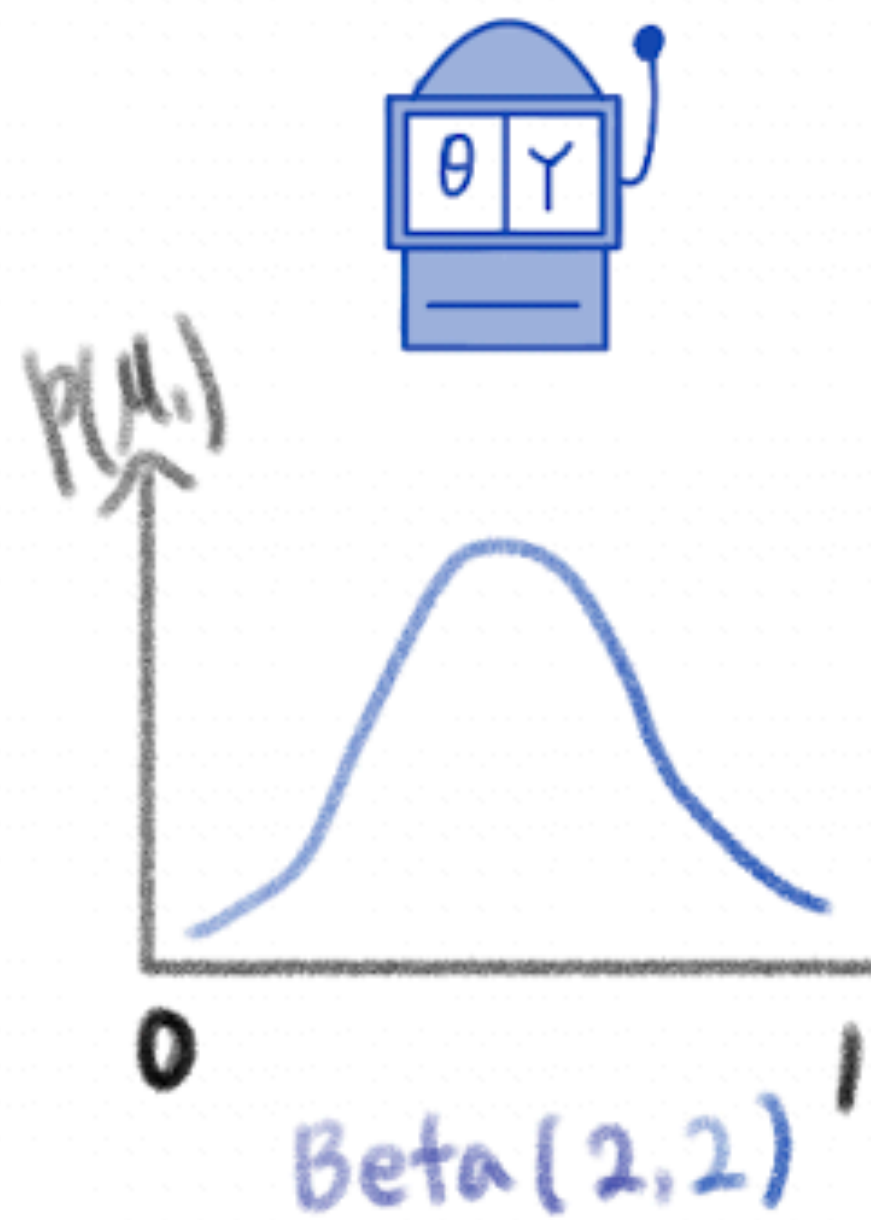
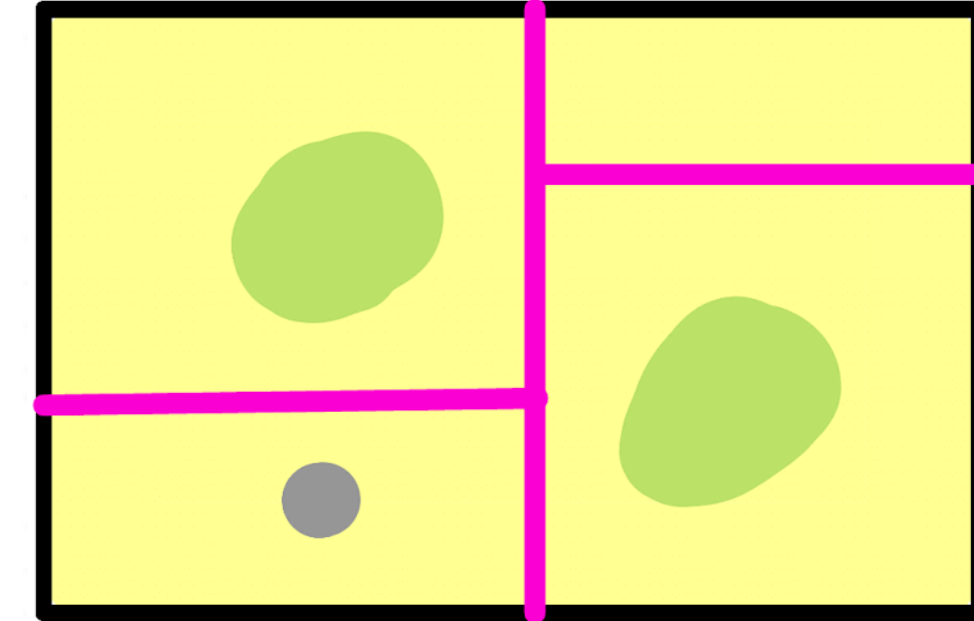
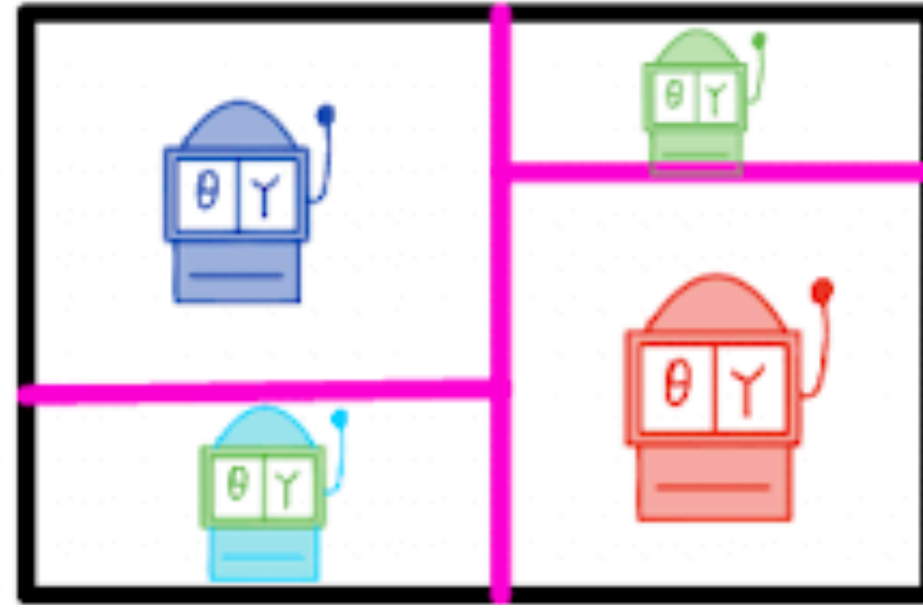
Inner Loop: learning q_k

$$\mu_k = \mathbb{E}[ABC | \Omega_k]$$



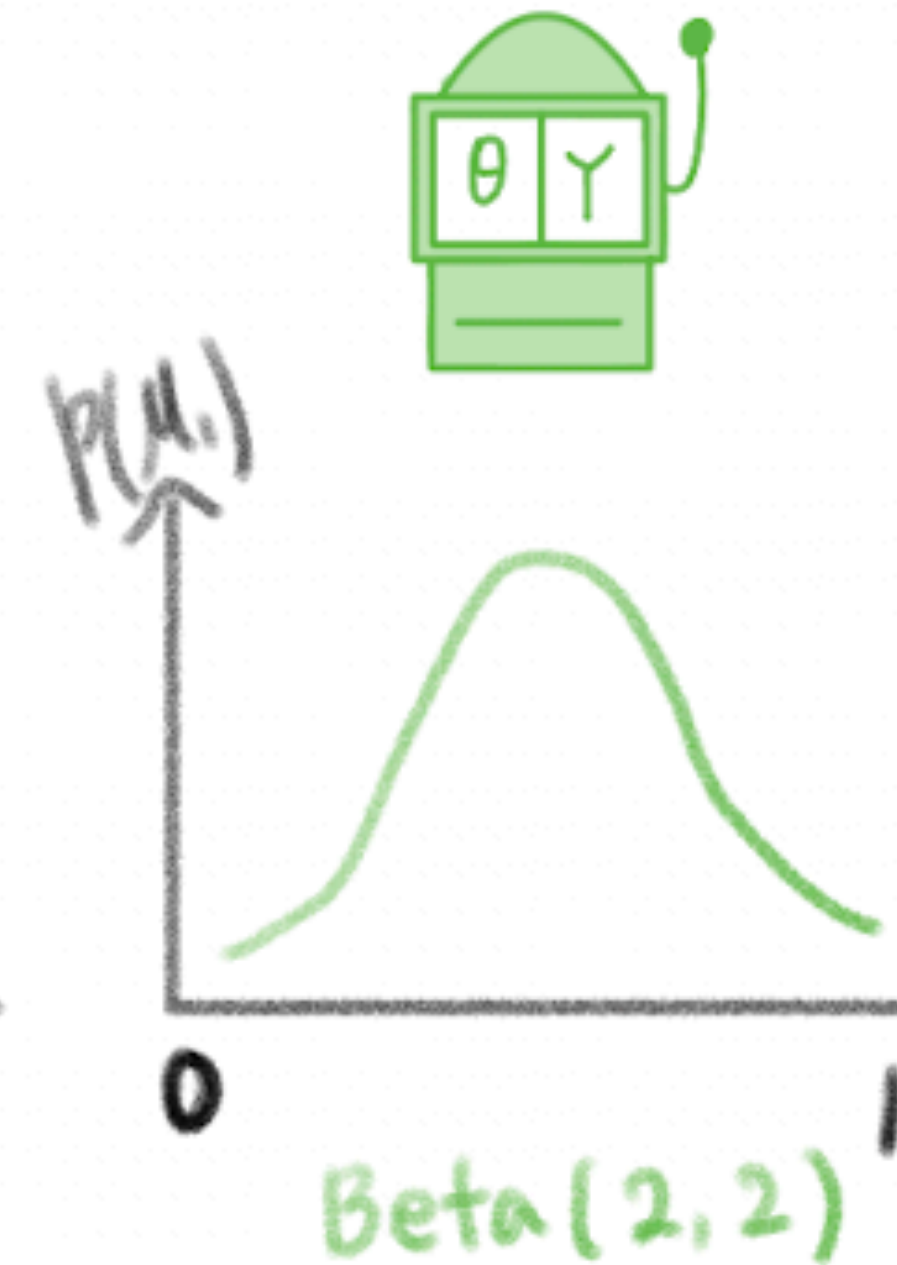
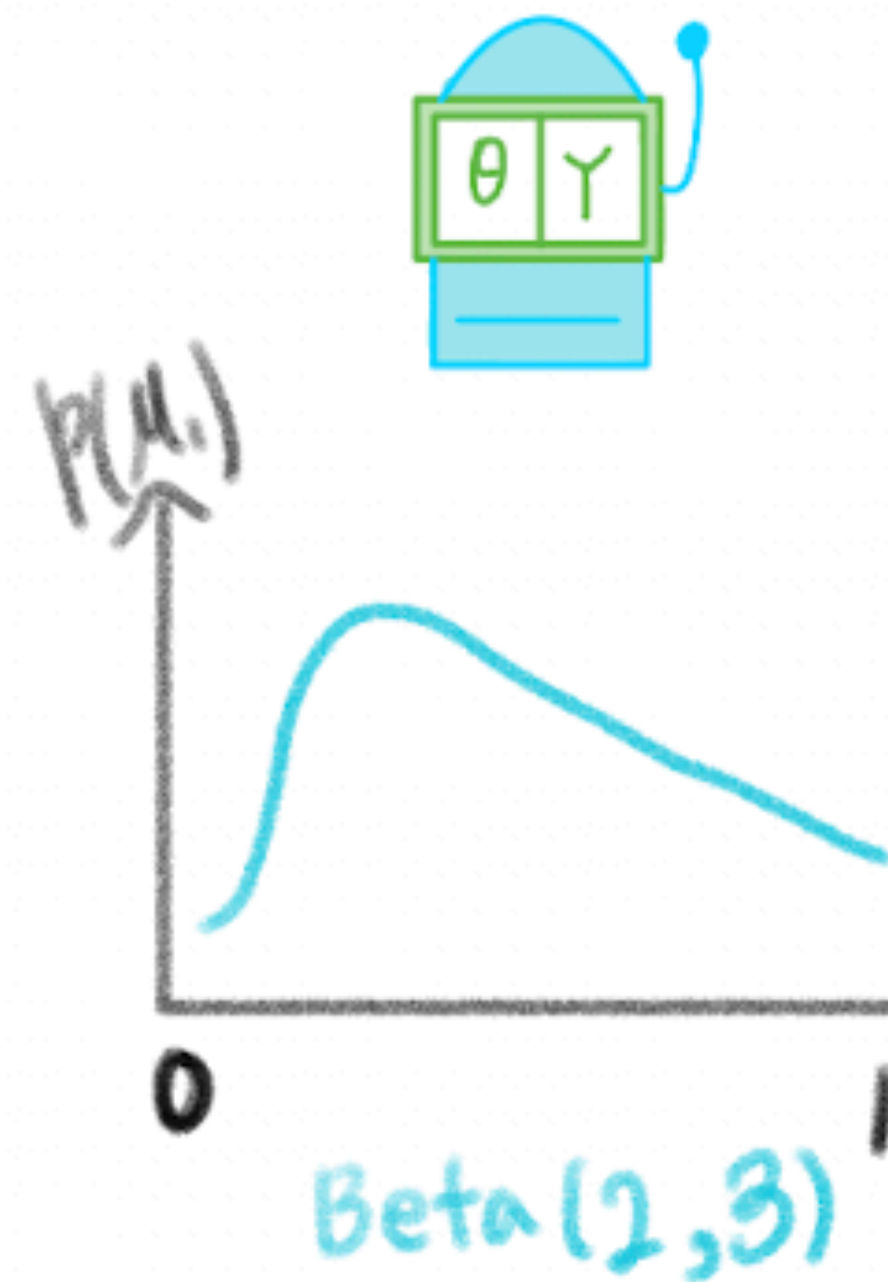
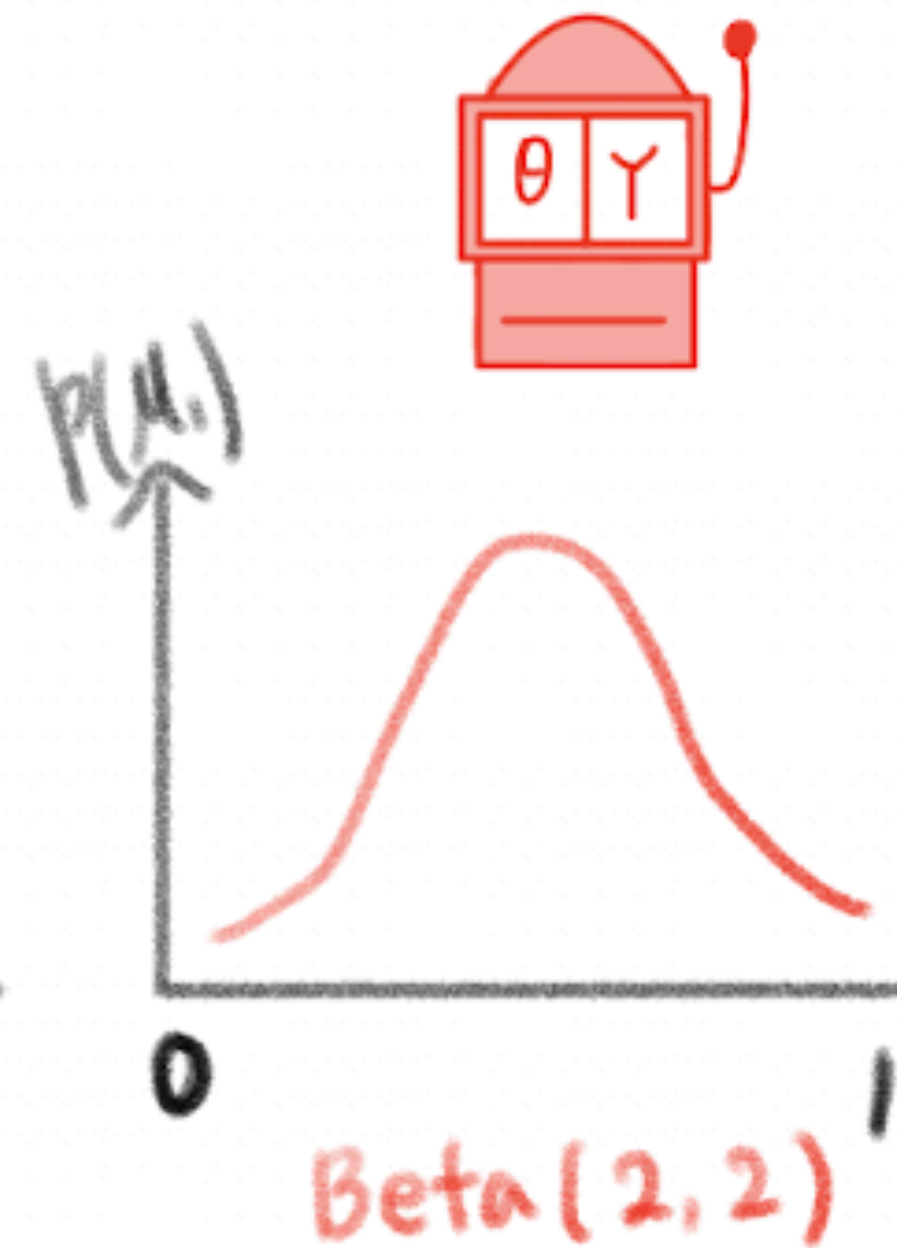
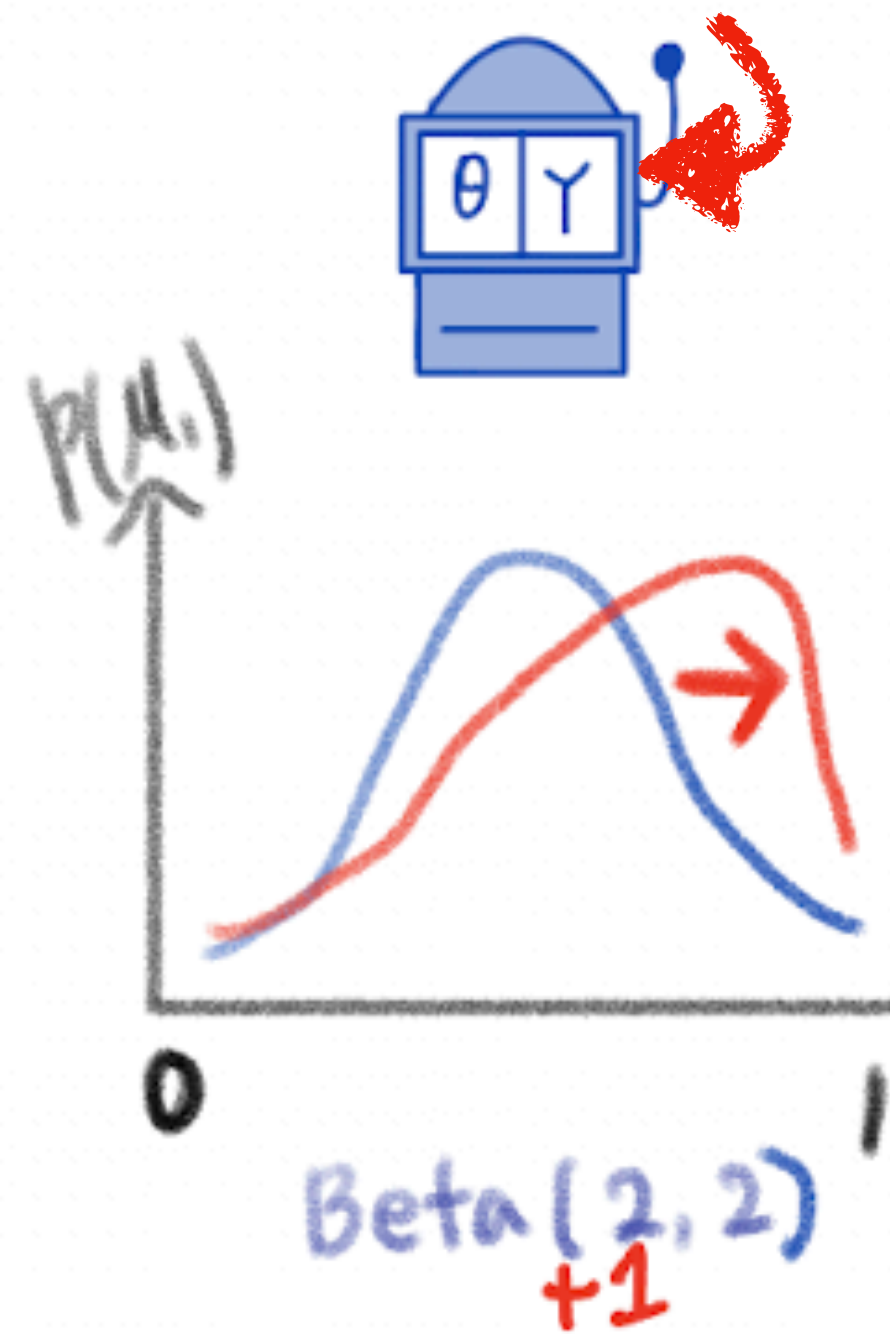
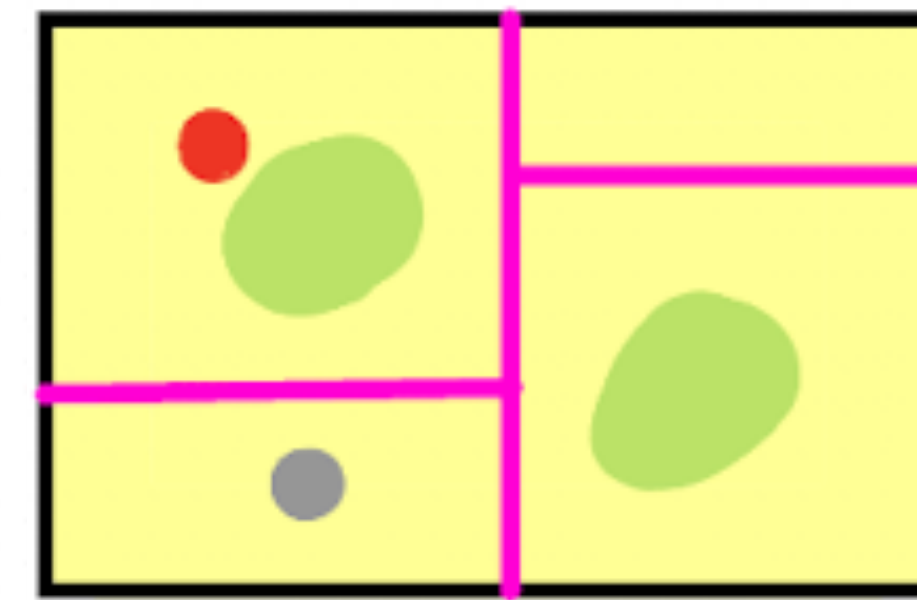
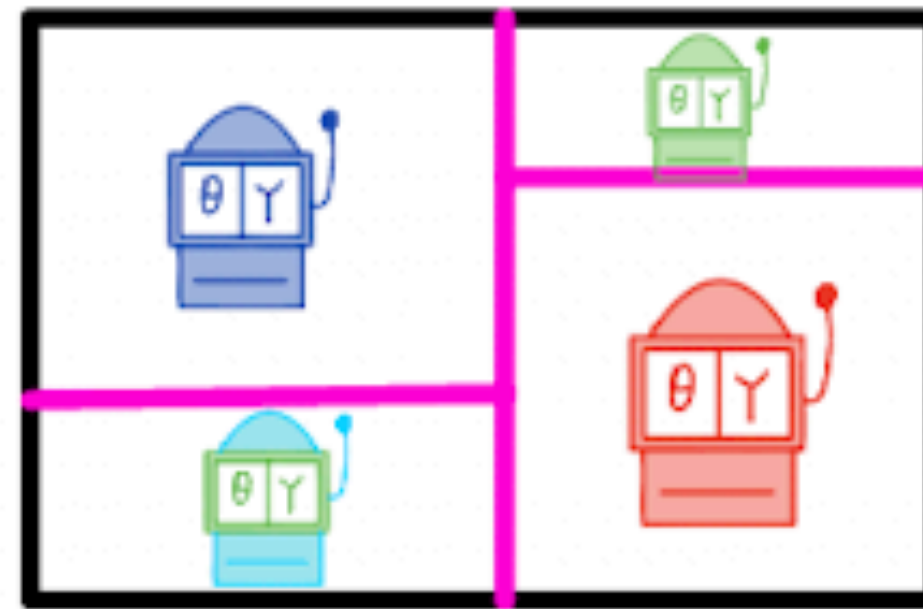
Inner Loop: learning q_k

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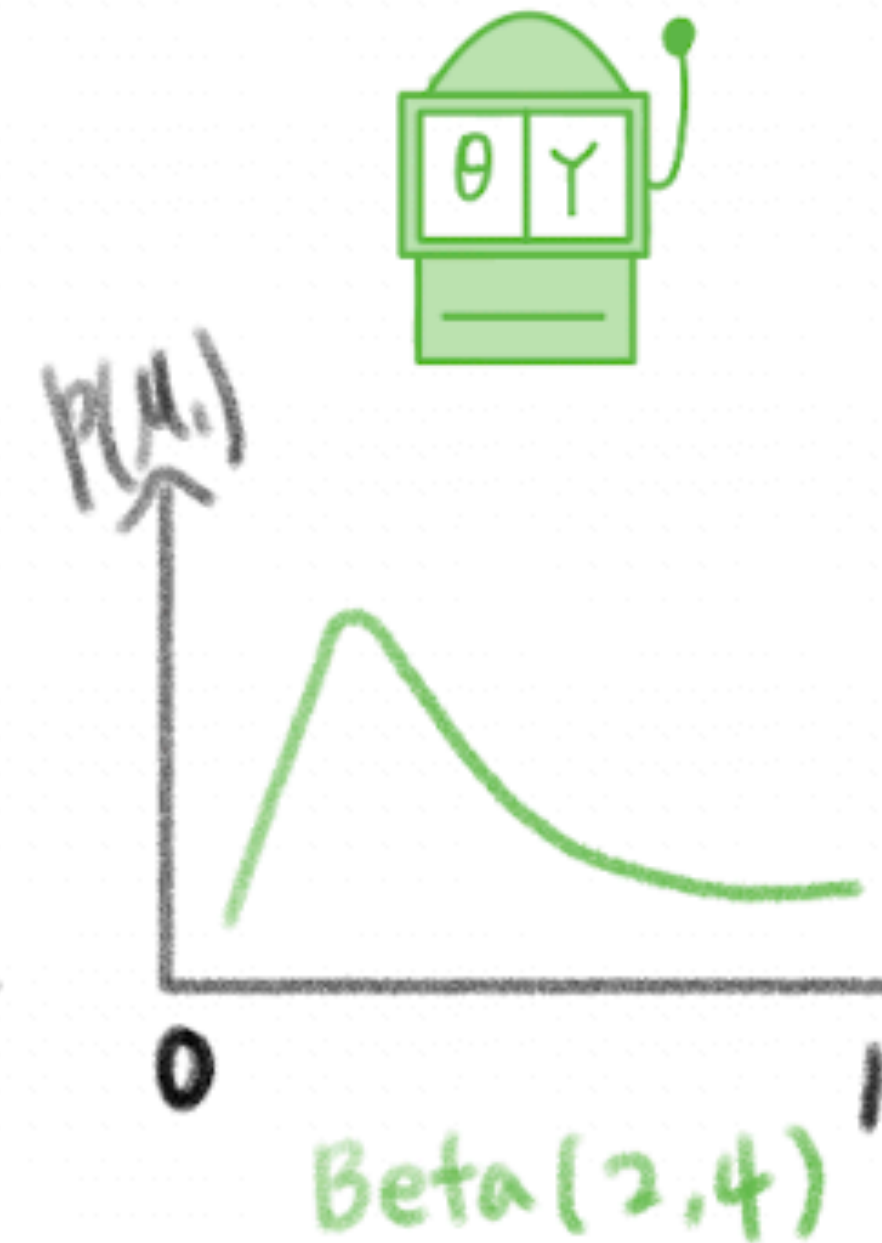
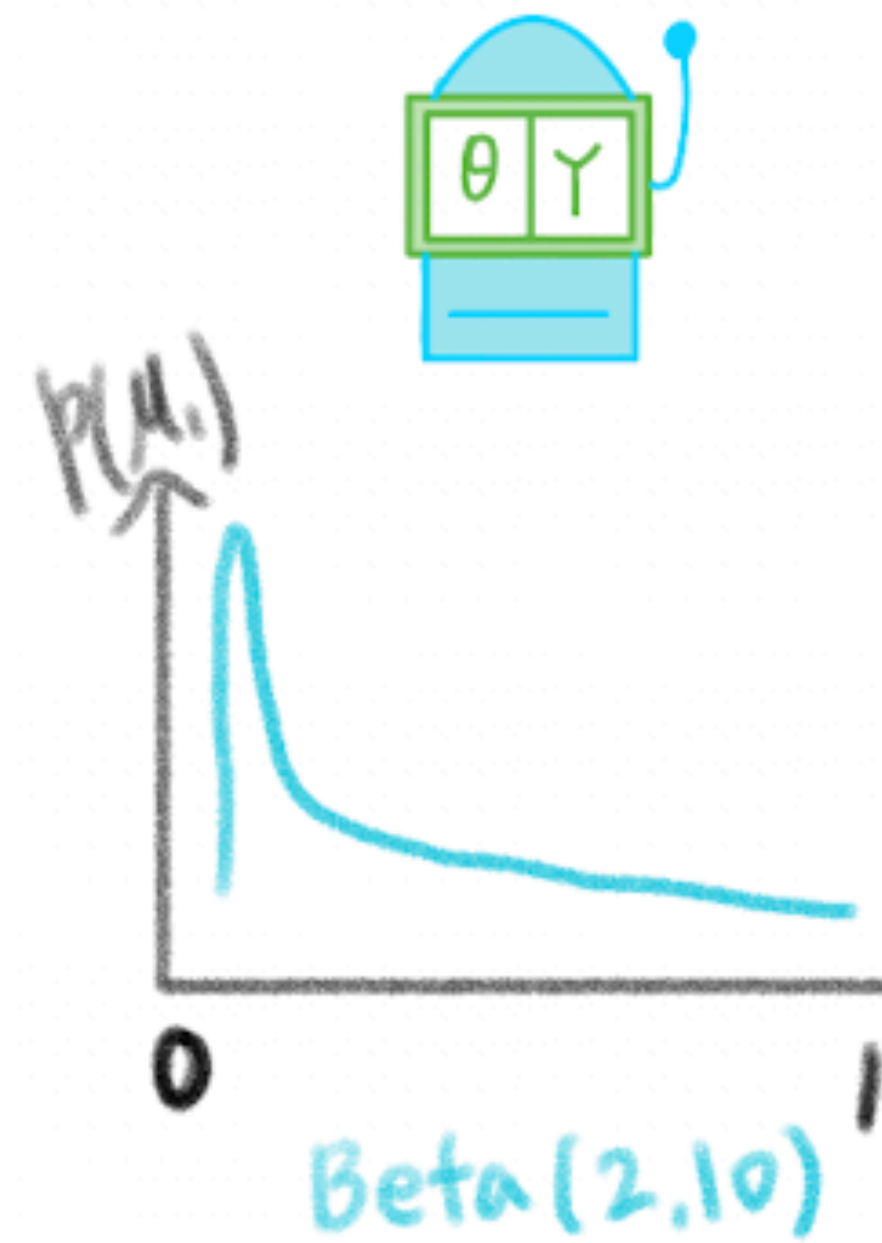
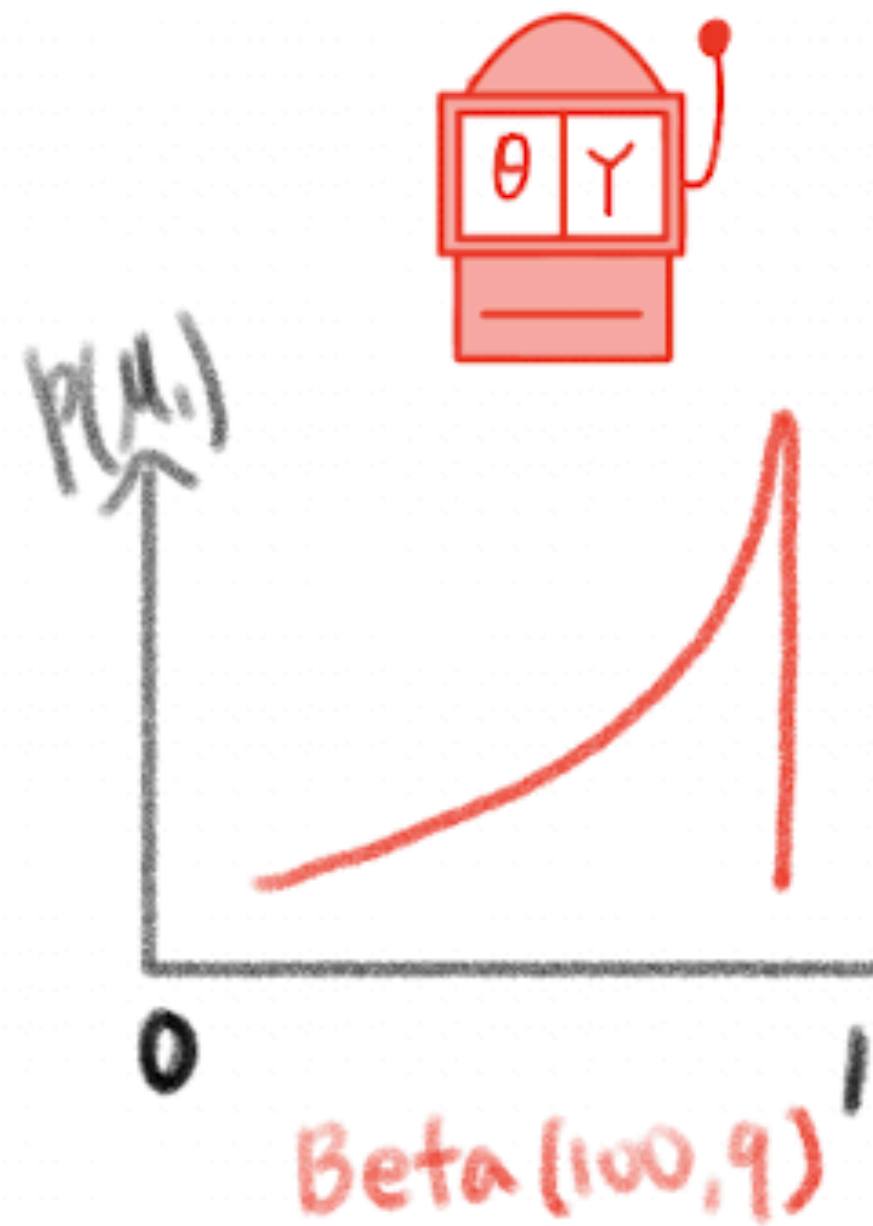
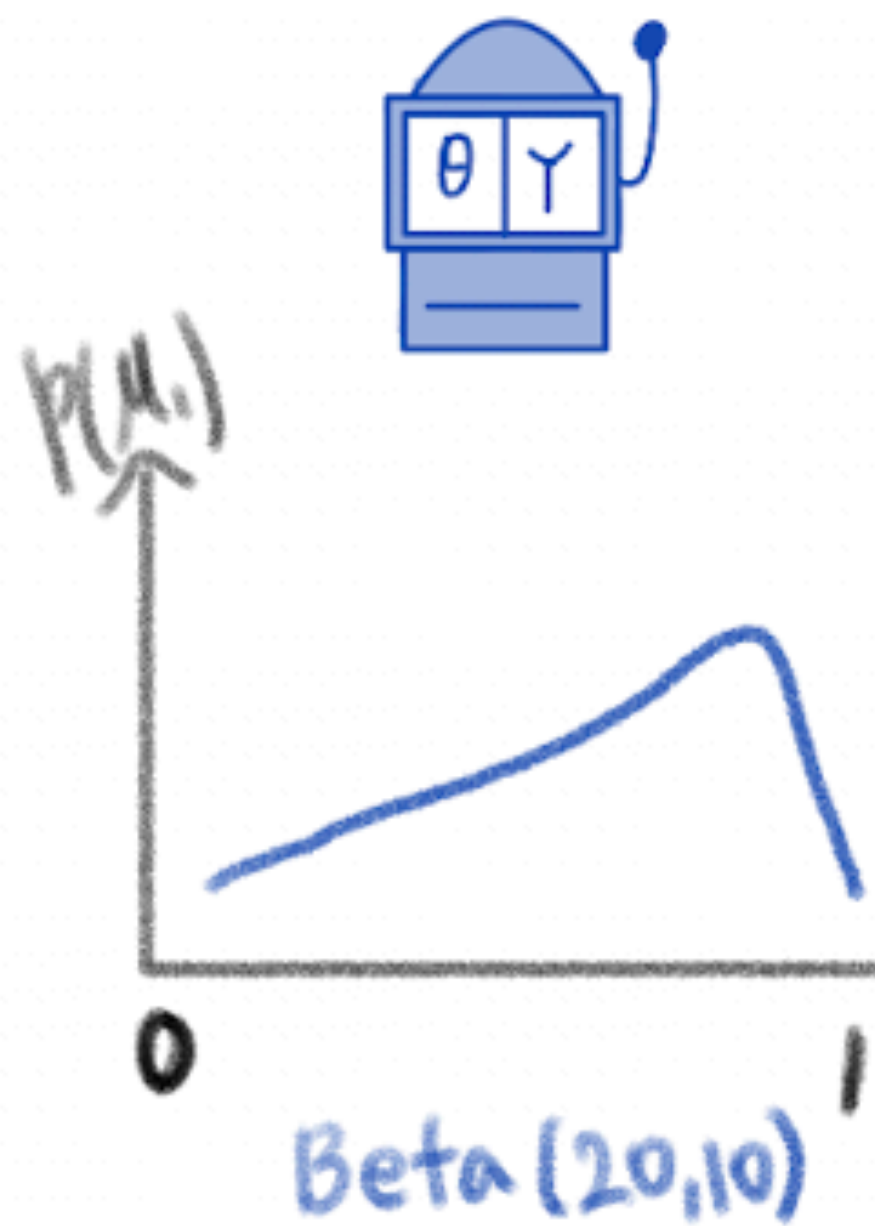
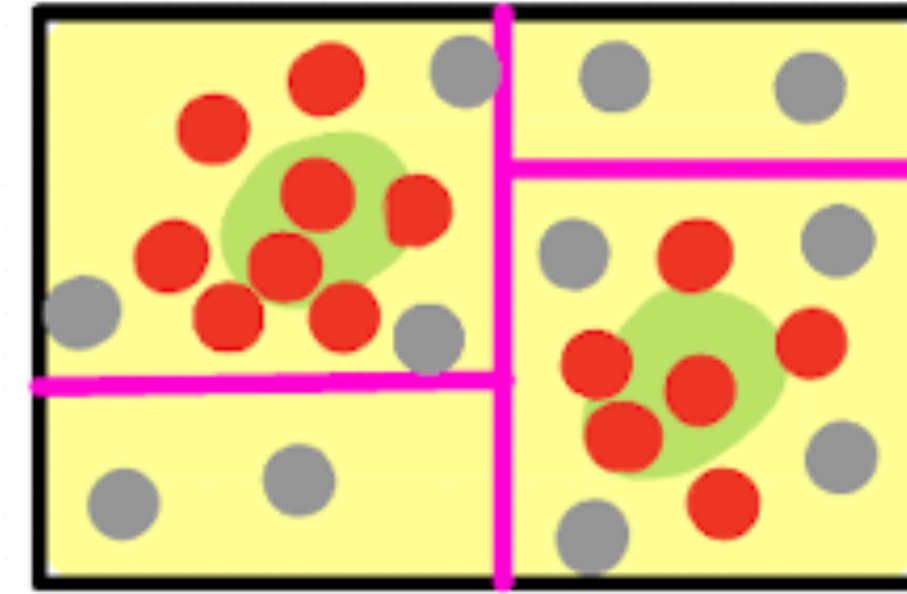
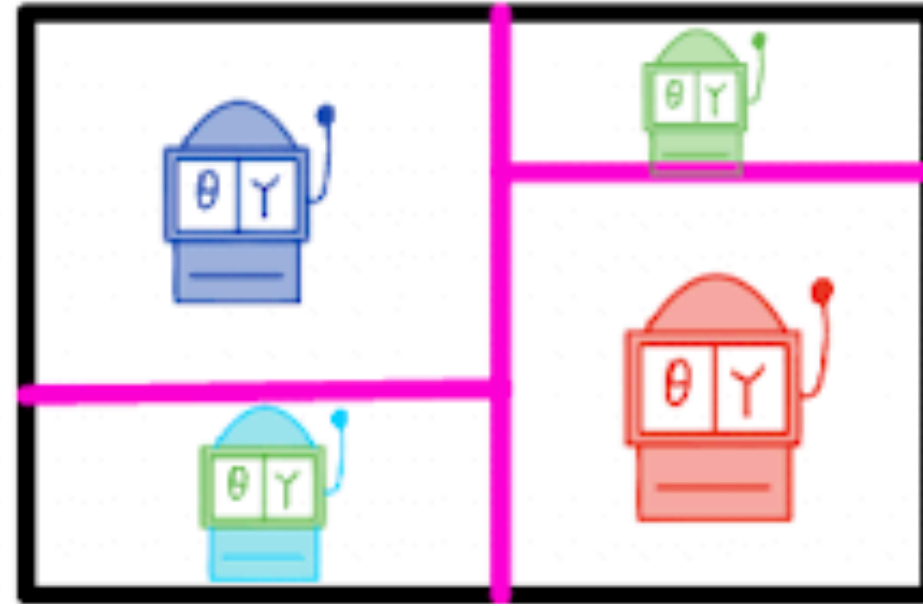
Inner Loop: learning q_k

$$\mu_k = \mathbb{E}[ABC | \Omega_k]$$

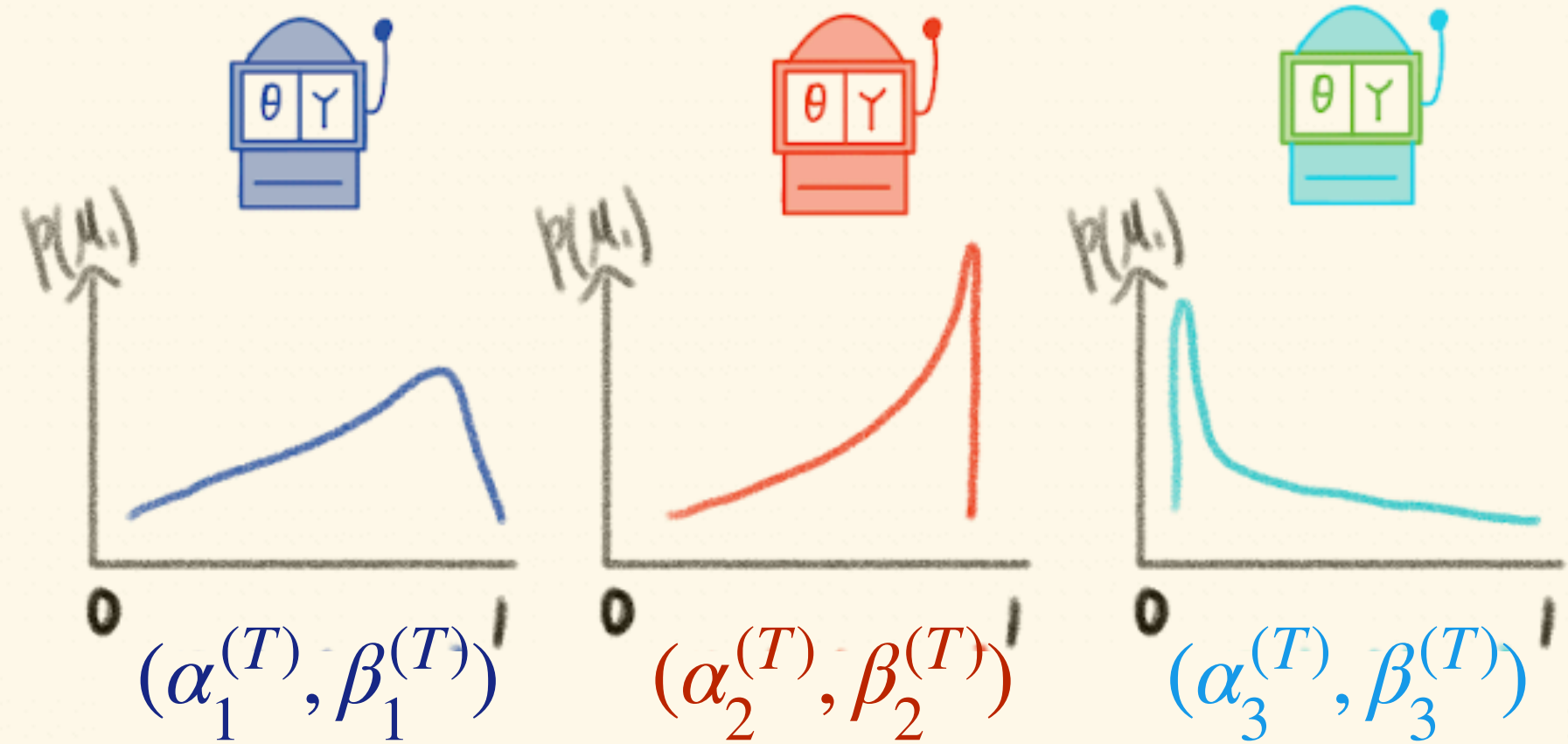


Inner Loop: learning q_k

$$\mu_k = \mathbb{E}[ABC | \Omega_k]$$



Arm Choice for Posterior Sampling



Exploitation and Exploration:

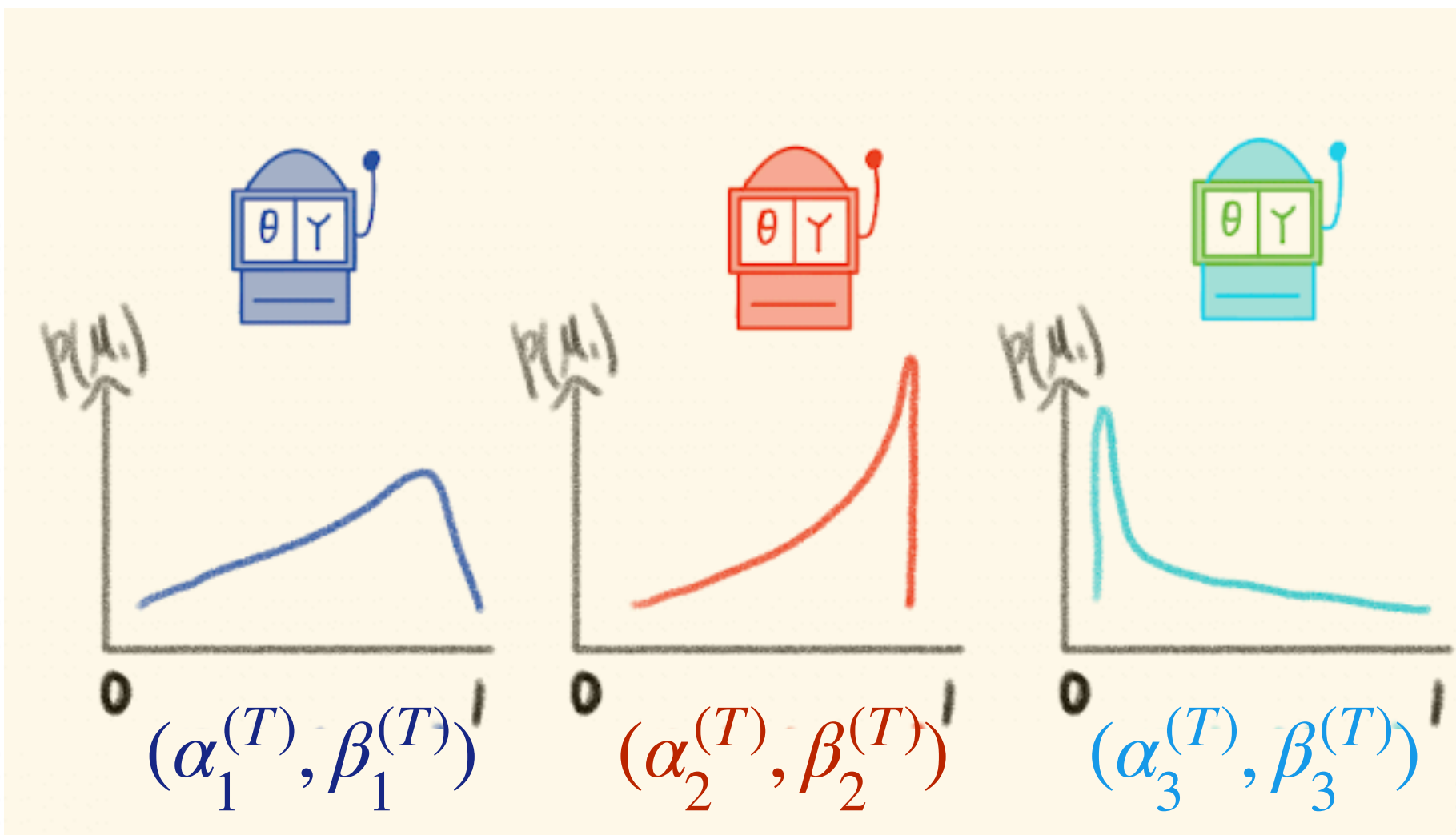
Estimate bin posterior by $\hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \frac{\alpha_k^{(T)}}{\alpha_k^{(T)} + \beta_k^{(T)}}$

Choose Arm by $Cat\{\hat{\mathbf{p}}_{\Omega}^{(T)}\}$, where $\hat{\mathbf{p}}_{\Omega}^{(T)} = (\hat{p}_{\Omega_1}^{(T)}, \hat{p}_{\Omega_2}^{(T)}, \hat{p}_{\Omega_3}^{(T)}, \hat{p}_{\Omega_4}^{(T)})$

$$\pi_{\varepsilon}(\theta | X^t) \propto \pi(\theta) \mathbb{E}_{X^t | \theta} [\text{ABC}(X^t, X_0, \varepsilon)]$$

$$\rightarrow \pi_{\varepsilon}(\Omega_k | X^t) \propto \pi(\Omega_k) \mathbb{E}_{X^t | \theta, \theta \sim \pi(\theta | \Omega_k)} [\text{ABC}(X^t, X_0, \varepsilon)]$$

Arm Choice for Posterior Sampling



Exploitation and Exploration:

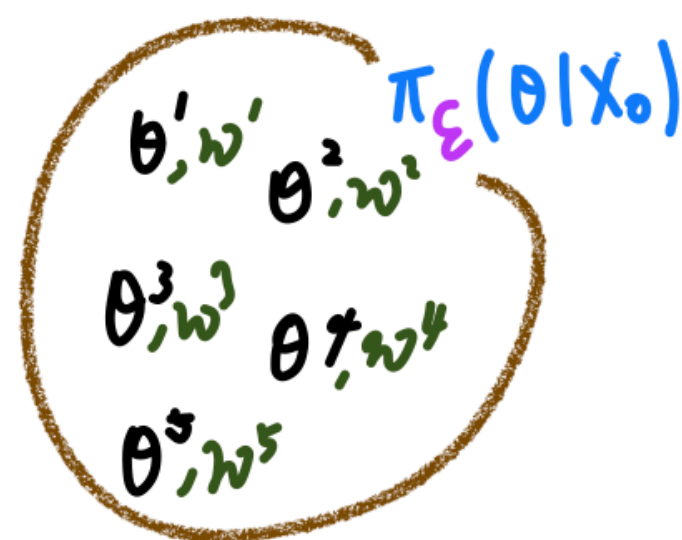
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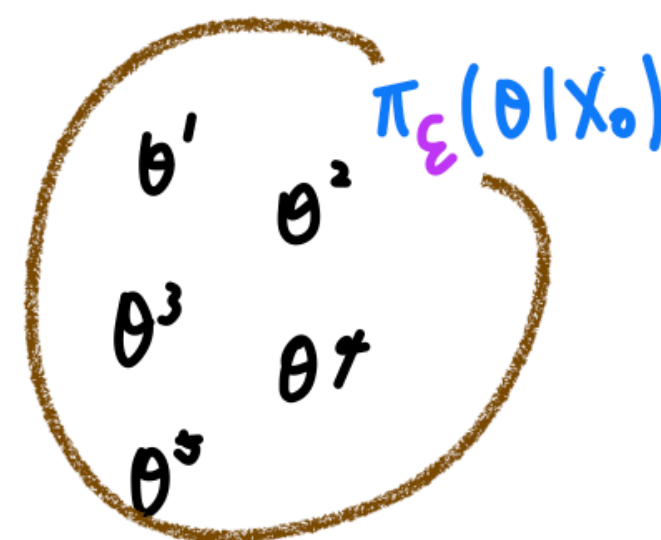
Pulling the best arm may not always be good!

$$\theta \sim q(\theta), \quad w(\theta) = \frac{\pi(\theta)}{q(\theta)}$$

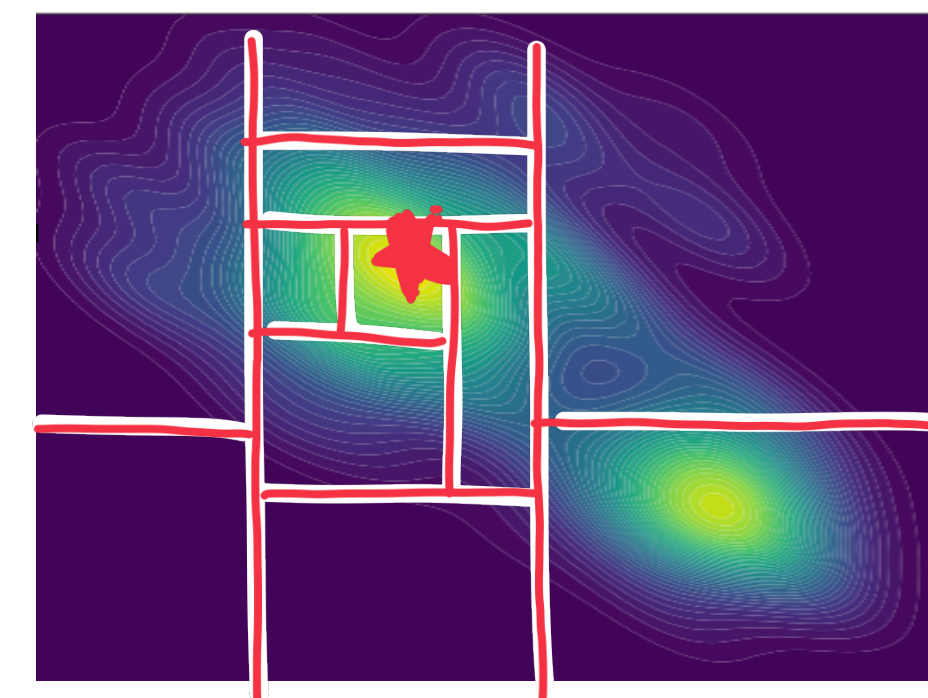
↓ ABC



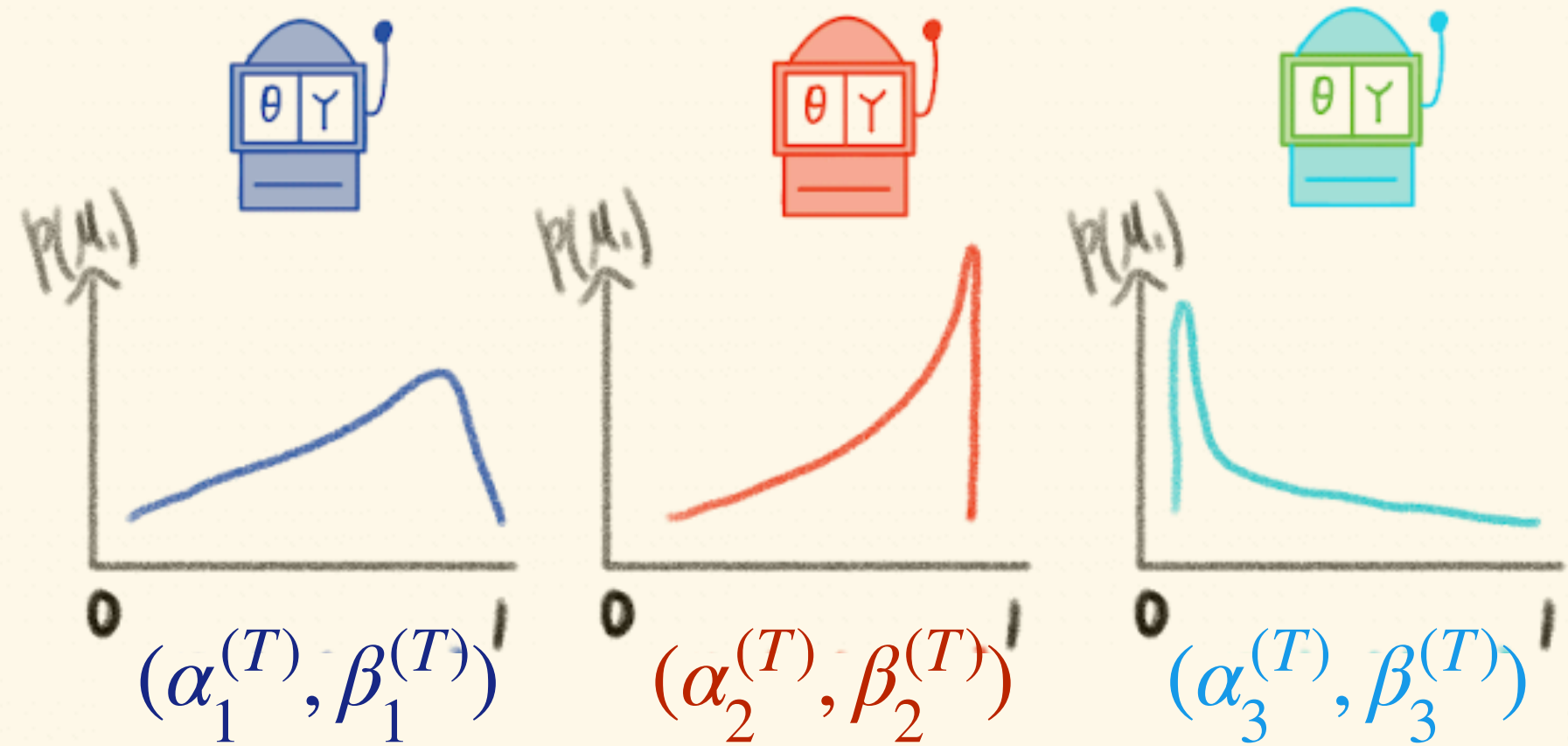
resample →



-> Importance weight variance



Arm Choice for Posterior Sampling



Regularized Exploitation and Exploration:

Estimate bin posterior by $\hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \frac{\alpha_k^{(T)}}{\alpha_k^{(T)} + \beta_k^{(T)}}$

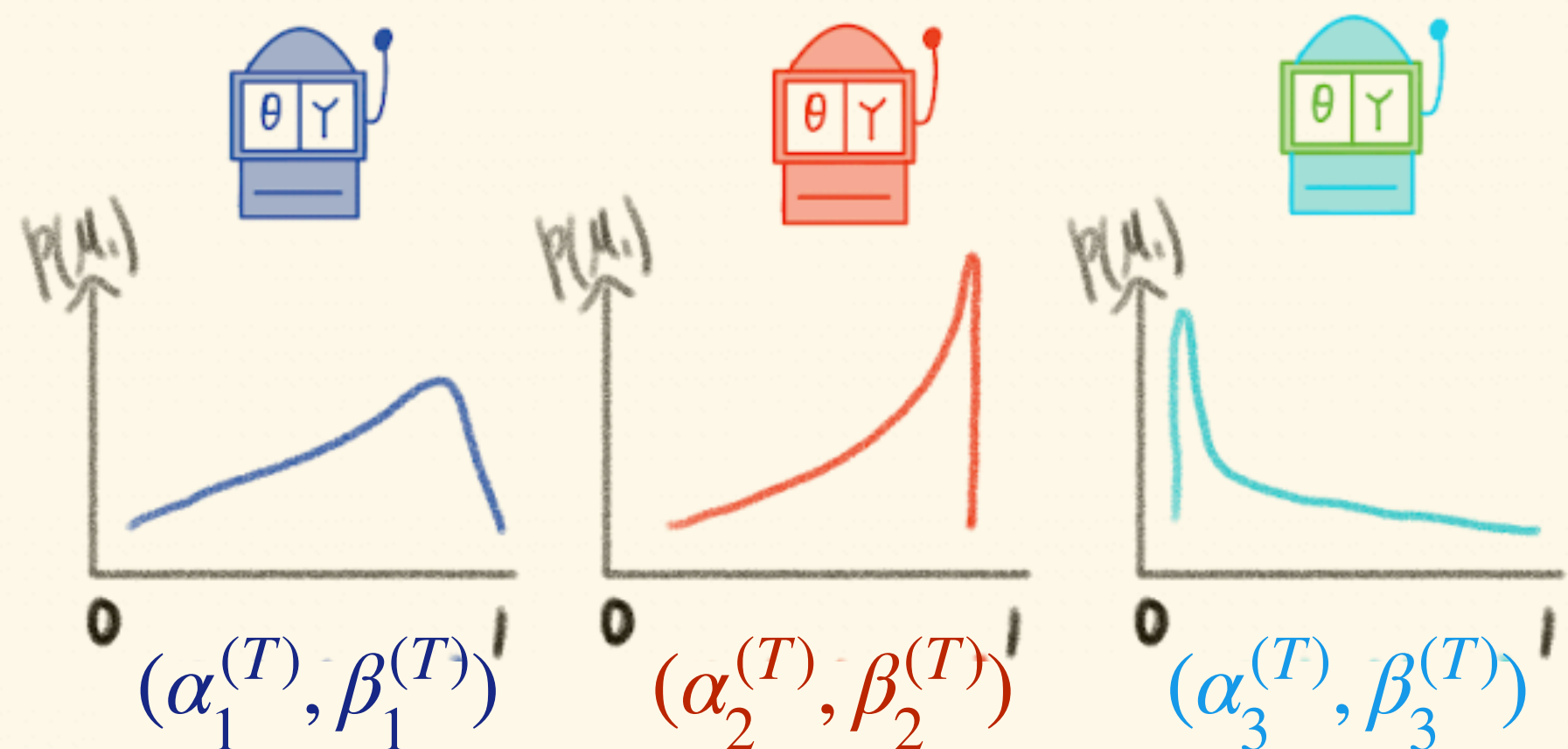
$(q_1, \dots, q_4) = \mathbf{q}^*(\hat{\mathbf{p}}_{\Omega}^{(T)})$, where $\mathbf{q}^*(\mathbf{p}) = \arg \max_{\mathbf{q}: \|\mathbf{q}\|_1=1} \omega_{\mathbf{p}}(\mathbf{q})$.

Choose Arm by $\text{Cat}\{q_1, q_2, q_3, q_4\}$

$$\text{For example: } \omega_{\mathbf{p}}^2(\mathbf{q}) = \frac{\sum_{k=1}^K q_k p_k / \pi_k}{\sum_{k=1}^K p_k \pi_k / q_k}.$$

sampling efficiency (Alsing et al. 2018)

Arm Choice for Posterior Sampling



Regularized Exploitation:

Estimate bin posterior by $\hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \frac{\alpha_k^{(T)}}{\alpha_k^{(T)} + \beta_k^{(T)}}$

$(q_1, \dots, q_4) = \mathbf{q}^*(\hat{\mathbf{p}}_{\Omega}^{(T)})$, where $\mathbf{q}^*(\mathbf{p}) = \arg \max_{\mathbf{q}: \|\mathbf{q}\|_1=1} \omega_{\mathbf{p}}(\mathbf{q})$.

Choose Arm by $Cat\{q_1, q_2, q_3, q_4\}$

Given regularity conditions, our algorithm is very good at optimizing the regret

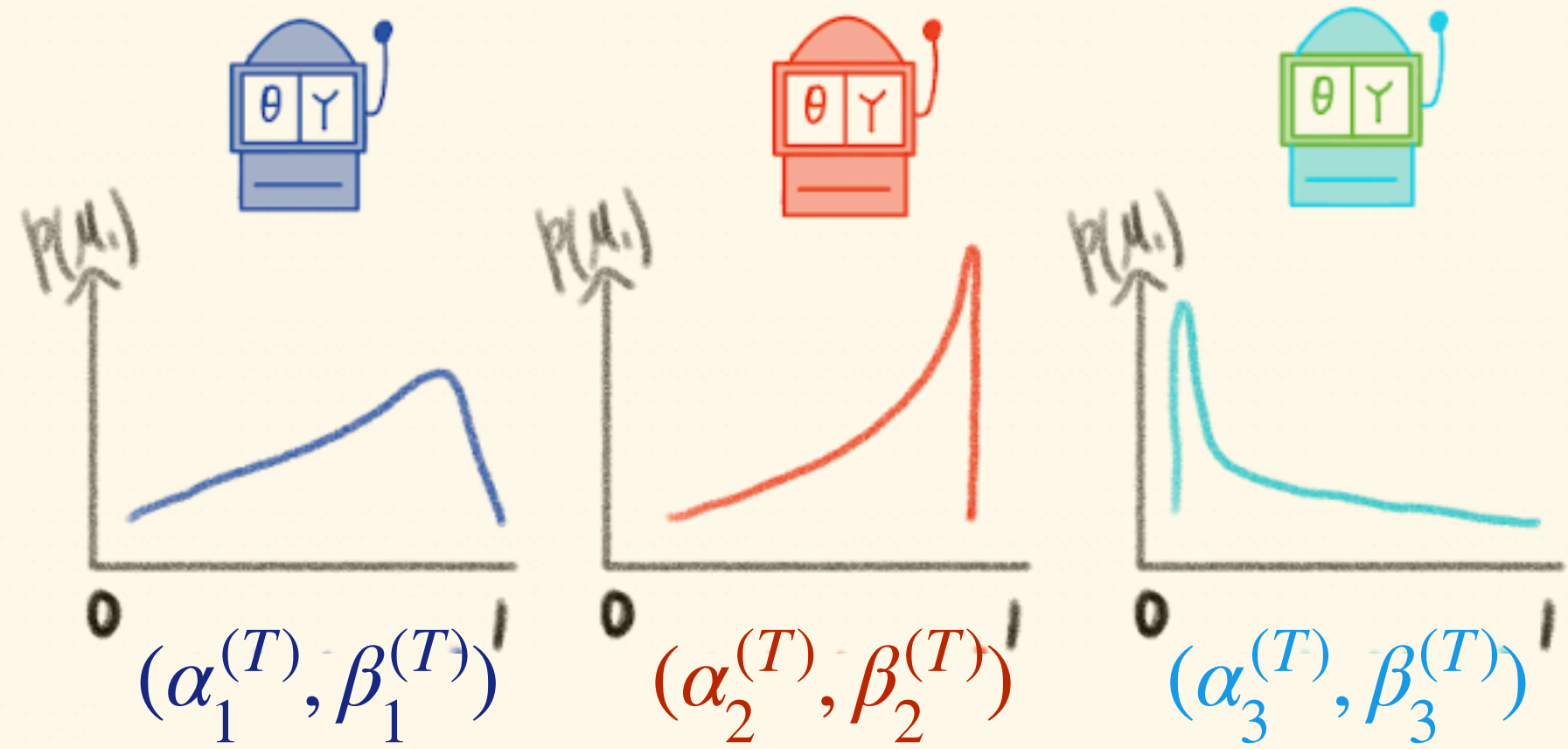
$$R_{TL}(\mathcal{A}, \mathbf{p}) := \omega_{\mathbf{p}}(\mathbf{q}^*) - \mathbb{E} \left[\frac{1}{T} \sum_{t=1}^T \omega_{\mathbf{p}}(\hat{\mathbf{q}}^{(t)}) \right]$$

Theorem Given $\pi(\Omega_k) = 1/K, k = 1, \dots, K$, and with \mathcal{A}' : our algorithm,

$$\sup_p R_{TL}(\mathcal{A}', p) \lesssim \frac{K^2 \log^2(T)}{T} \text{ and } \inf_{\mathcal{A}} \sup_p R_{TL}(\mathcal{A}, p) \gtrsim \frac{K^2}{T}$$

where the infimum is taken over all possible strategies \mathcal{A} . T : time, K : # of bins

Arm Choice for Maximum a Posteriori (MAP)

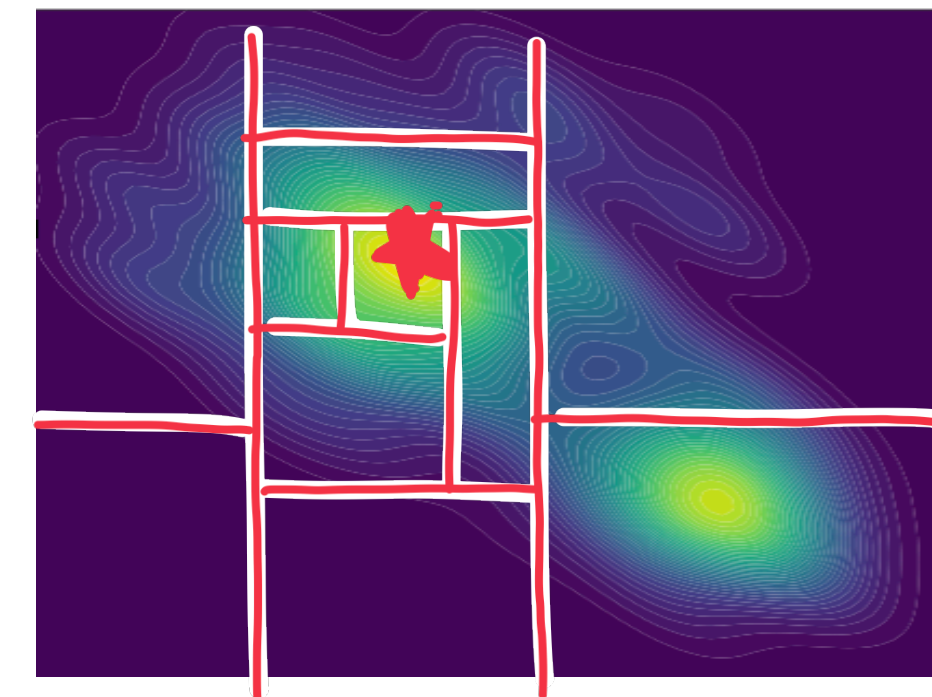


Estimated **average** posterior in each bin:

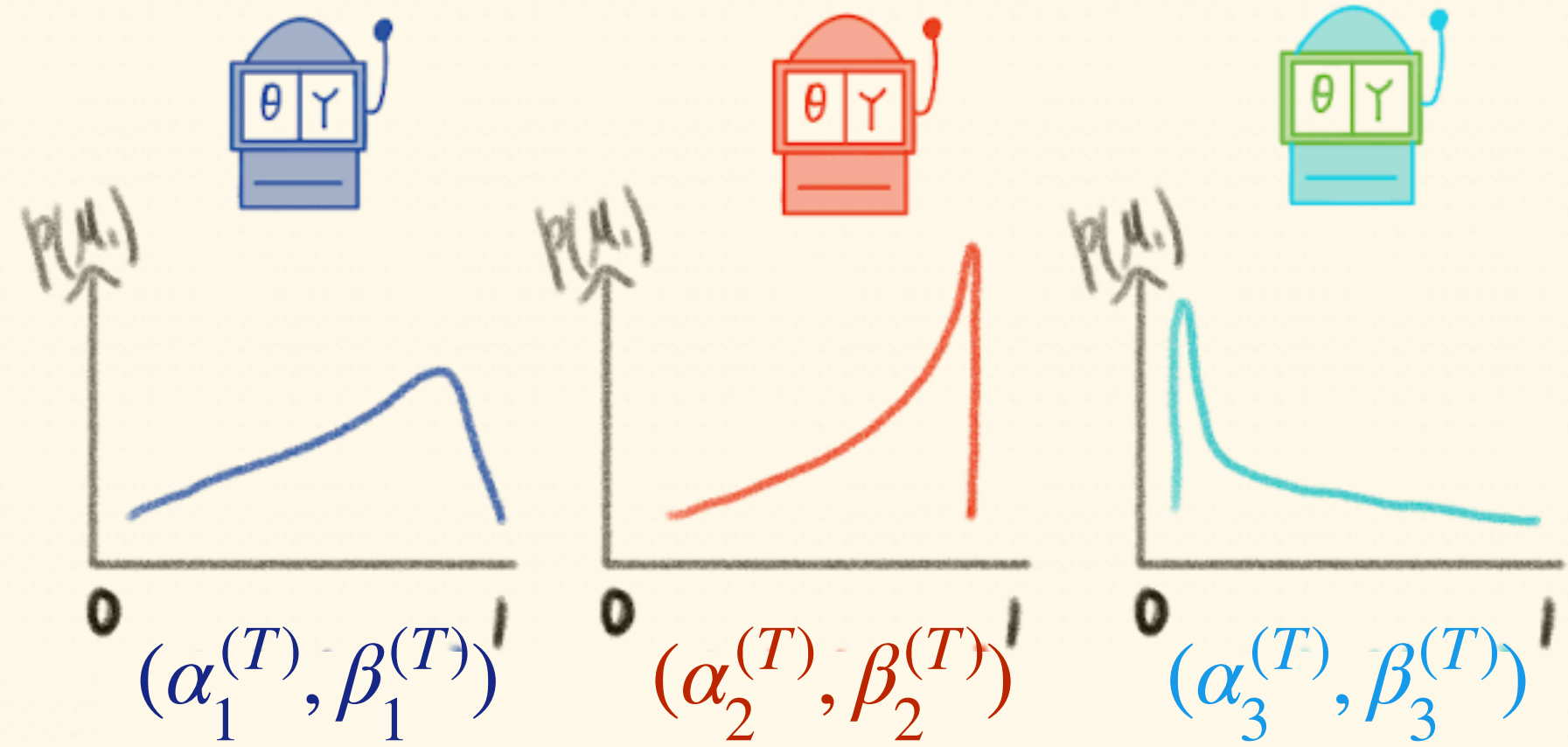
$$\hat{p}_k^{\Omega}(\theta | X) = \frac{\hat{p}_{\Omega_k}^{(T)}}{|\Omega_k|} \text{ for } \theta \in \Omega_k, \hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \times \frac{\alpha_k^{(T)}}{\alpha_k^{(T)} + \beta_k^{(T)}}$$

Exploitation: Pull $\arg \max \{\hat{p}_k^{\Omega}(\theta | X)\}_{k=1}^K$

Importance weight variance: No worries-!



Arm Choice for Maximum a Posteriori (MAP)



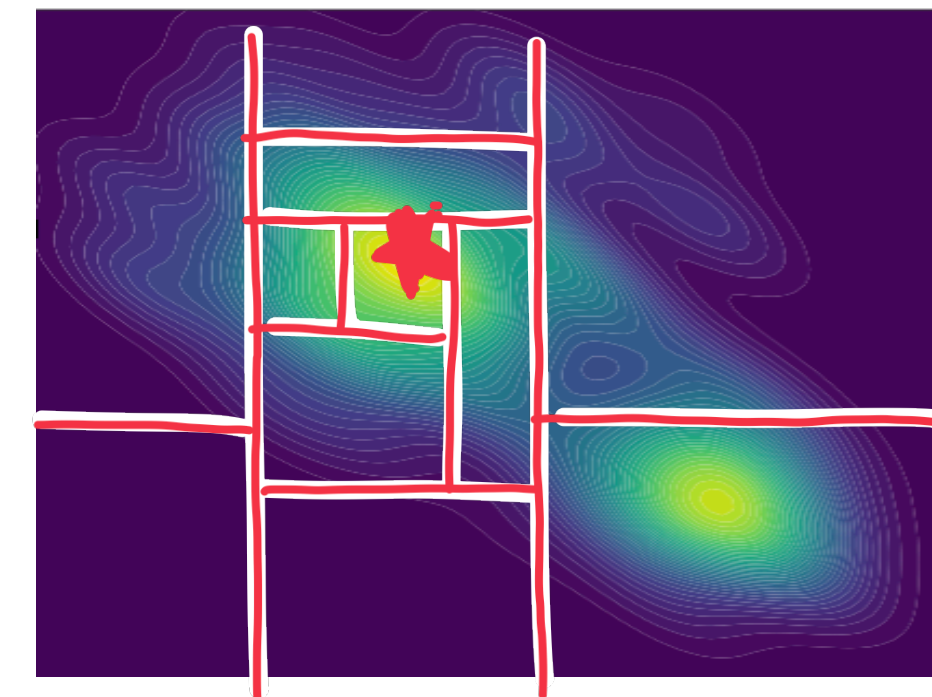
Exploration: $(\eta_1, \eta_2, \eta_3, \eta_4) \sim \bigotimes_{k=1}^K \text{Beta} \left(\alpha_k^{(T)}, \beta_k^{(T)} \right)$

Sampled average posterior in each bin:

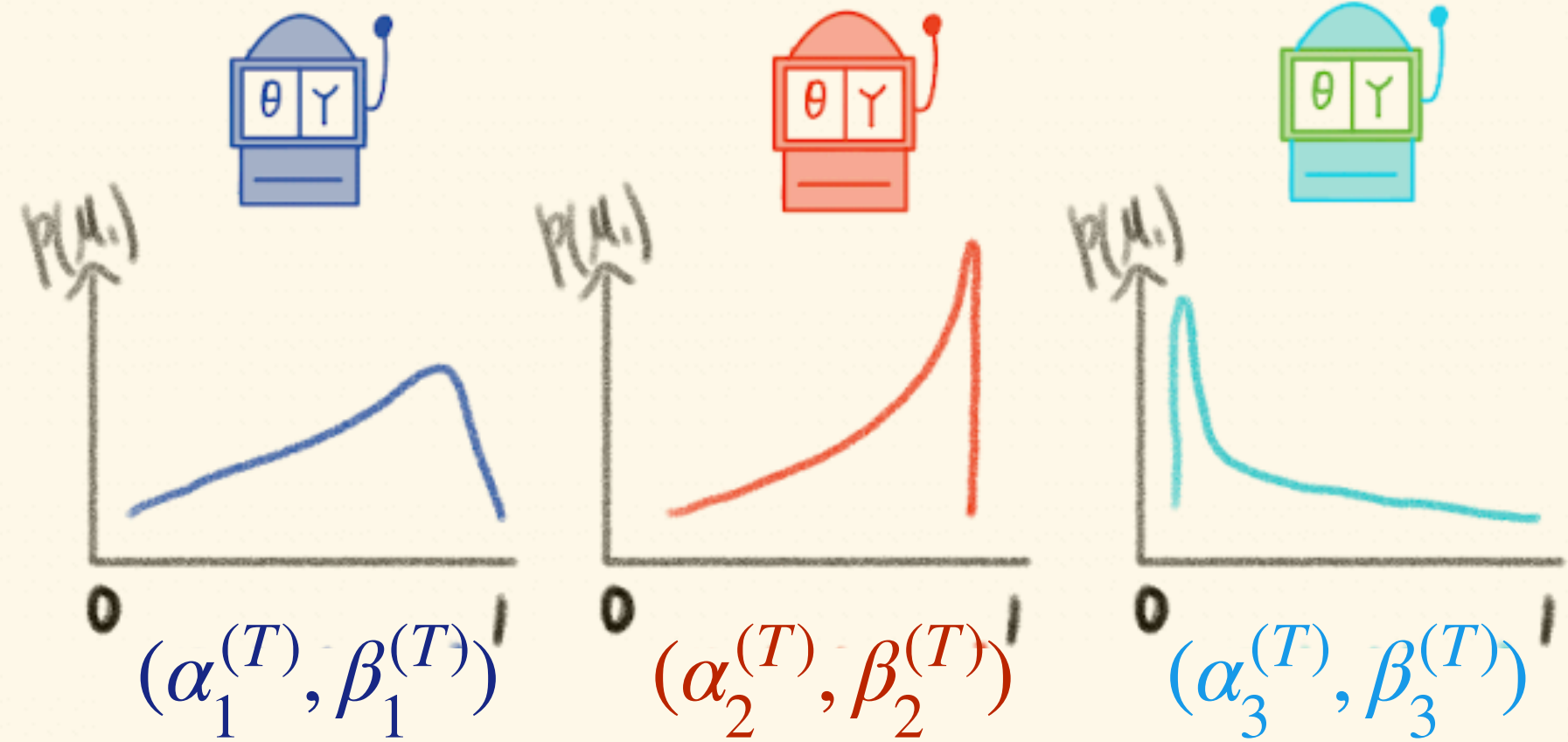
$$\hat{p}_\epsilon^{\Omega_k}(\theta | X) = \frac{\hat{p}_{\Omega_k}^{(T)}}{|\Omega_k|} \text{ for } \theta \in \Omega_k, \quad \hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \times \eta_k$$

Exploitation: Pull $\arg \max \{ \hat{p}_k^{\Omega_k}(\theta | X) \}_{k=1}^K$

Importance weight variance: No worries-!



Arm Choice for Maximum a Posteriori (MAP)



Exploration: $(\eta_1, \eta_2, \eta_3, \eta_4) \sim \bigotimes_{k=1}^K \text{Beta}(\alpha_k^{(T)}, \beta_k^{(T)})$

Sampled average posterior in each bin:

$$\hat{p}_\epsilon^{\Omega_k}(\theta | X) = \frac{\hat{p}_{\Omega_k}^{(T)}}{|\Omega_k|} \text{ for } \theta \in \Omega_k, \quad \hat{p}_{\Omega_k}^{(T)} \propto \pi(\Omega_k) \times \eta_k$$

Exploitation: Pull $\arg \max \{\hat{p}_k^{\Omega}(\theta | X)\}_{k=1}^K$

Given regularity conditions, our algorithm is very good at optimizing the regret

$$r_T = \pi_\epsilon(\theta^{\text{MAP}} | X) - \pi_\epsilon(\tilde{\theta}^{(T)} | X), \text{ where } \tilde{\theta}^{(T)}: \text{the center of the bin chosen at time } T$$

Theorem Given $\pi(\Omega_k) = 1/K, k = 1, \dots, K$, with \mathcal{A}' : our algorithm, for any $\mu = (p_{\Omega_1}, \dots, p_{\Omega_K})$, there exists a constant Γ_μ such

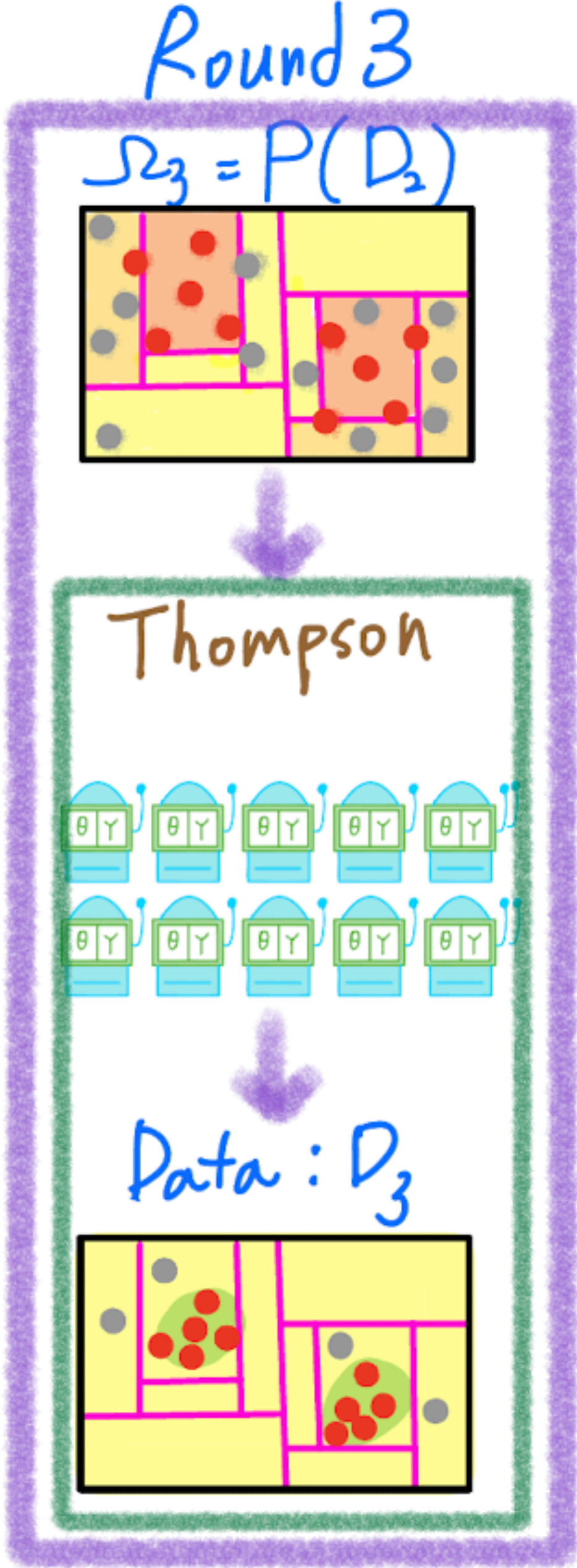
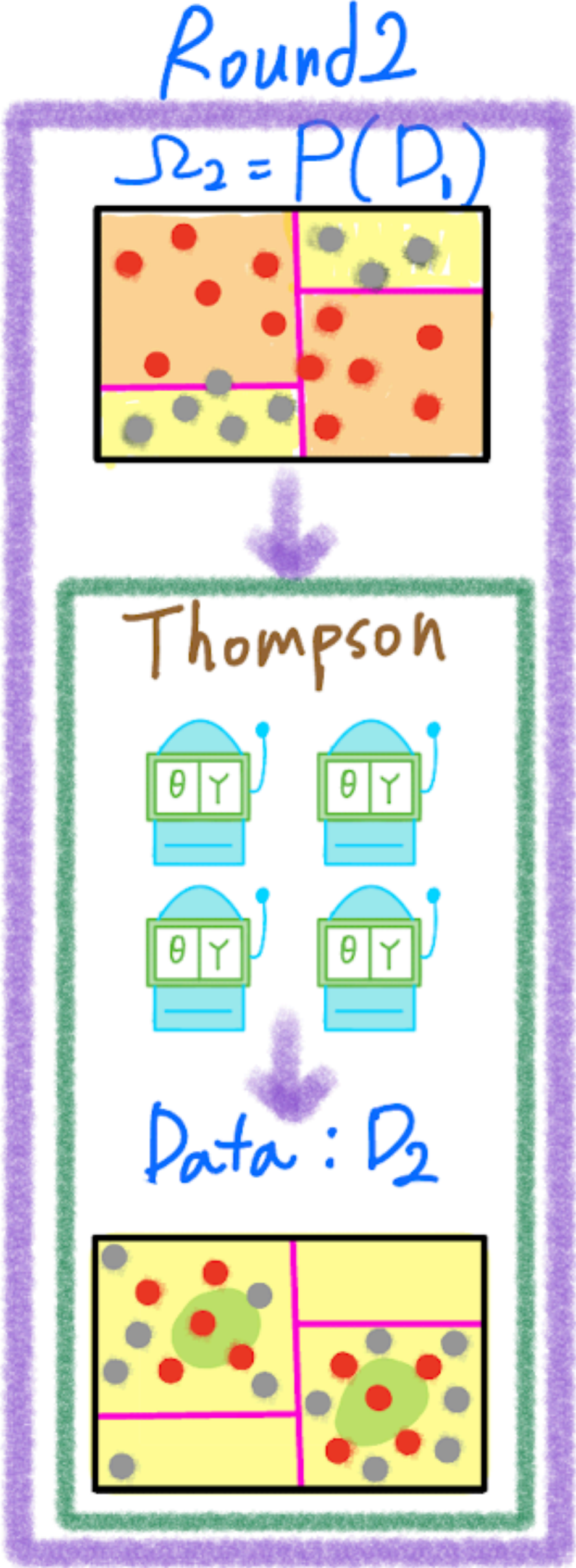
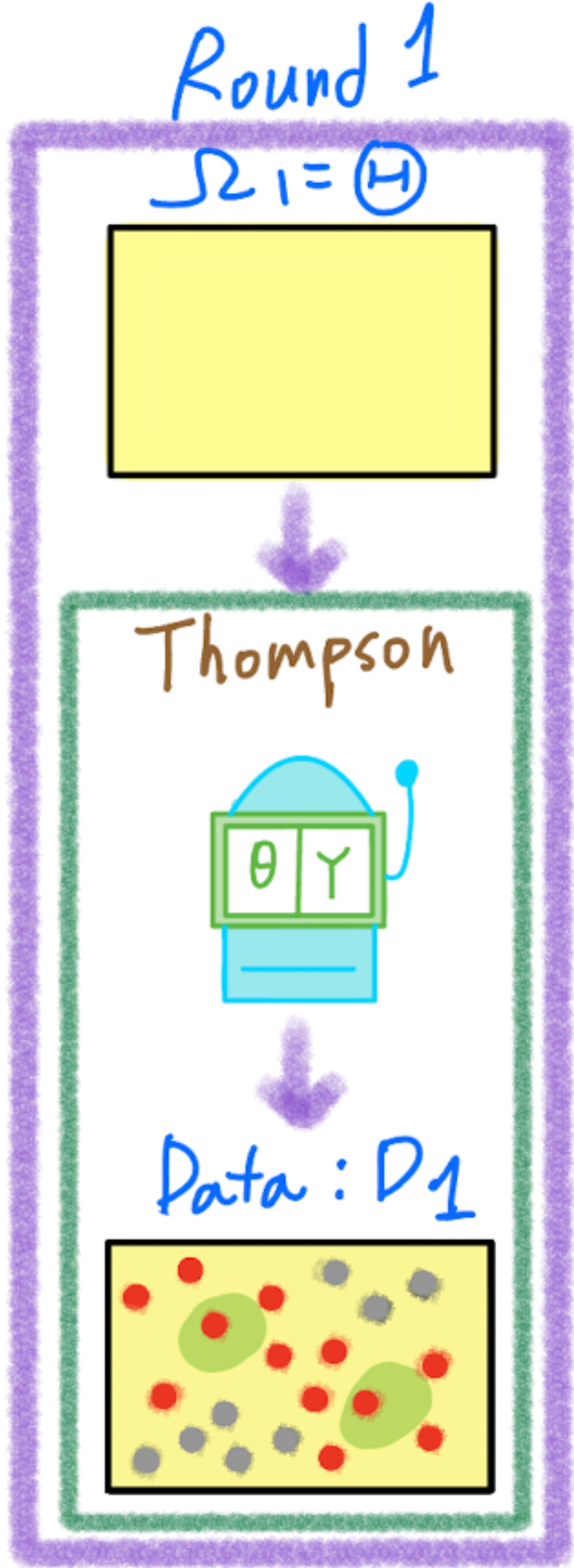
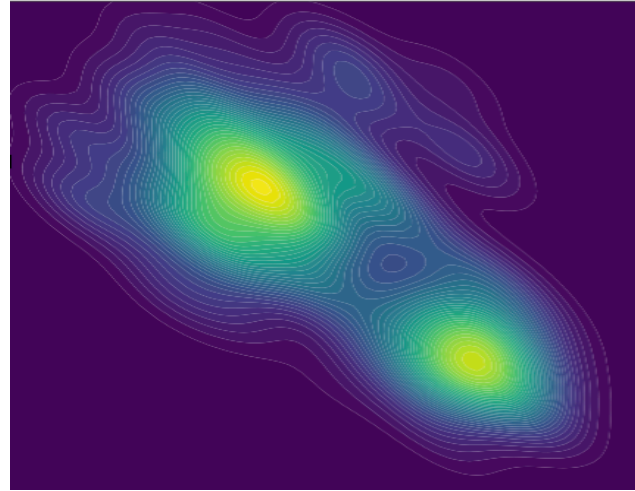
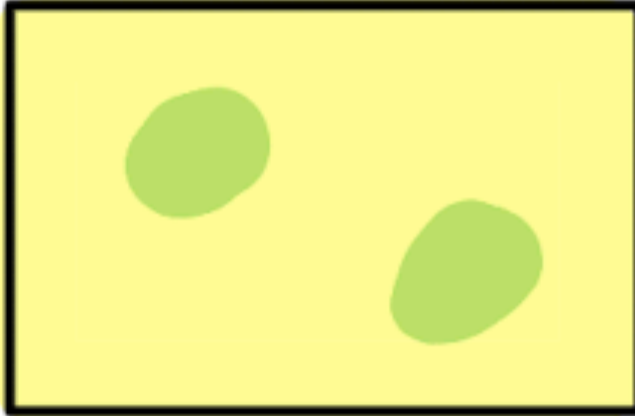
$$P(\hat{k}_{\mathcal{A}'}^{(T)} \neq k^*) = \exp(-T(\Gamma_\mu + o(1))).$$

Moreover, any algorithm \mathcal{A} must satisfy $P(\hat{k}_{\mathcal{A}}^{(T)} \neq k^*) \geq \exp(-T(2\Gamma_\mu + o(1)))$.

k^* : the bin index having the true MAP

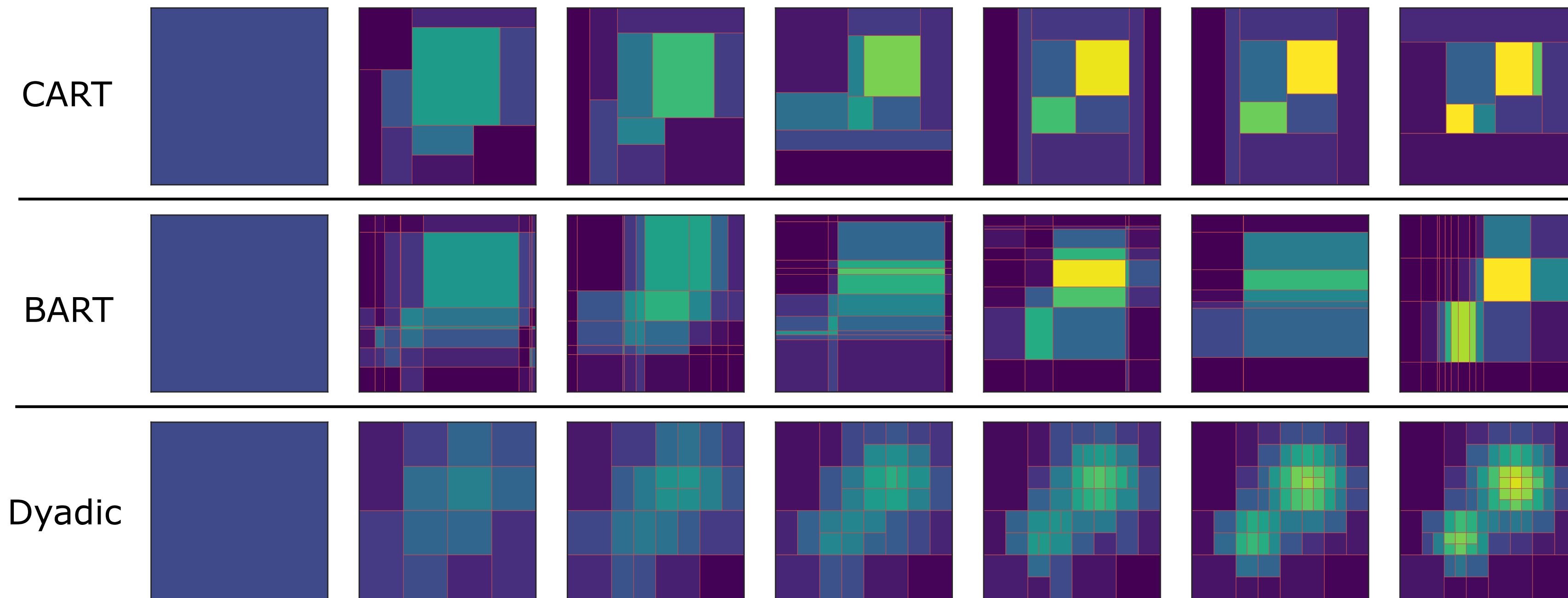
Algorithm

True Posterior

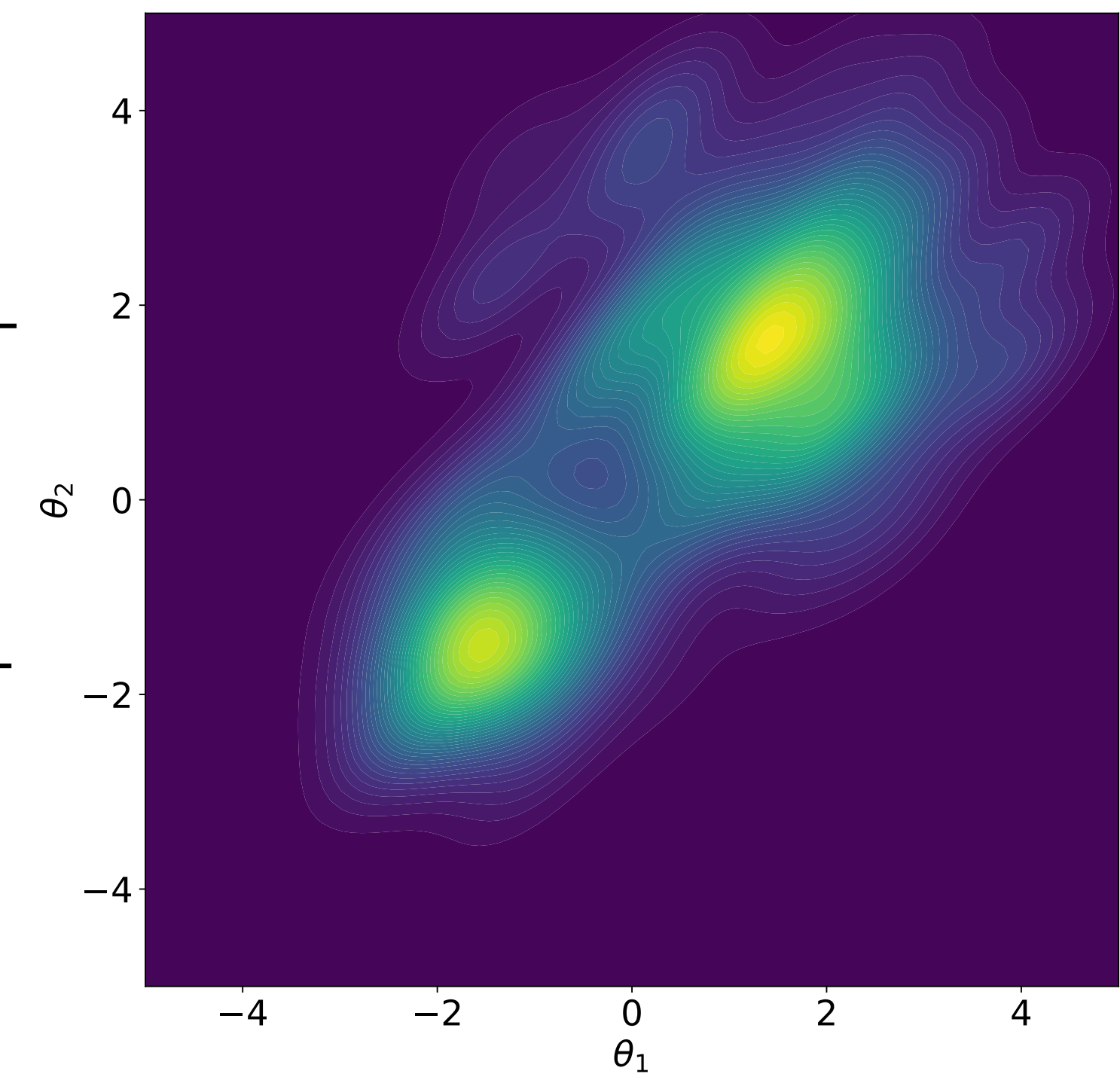


Example Posterior Sampling

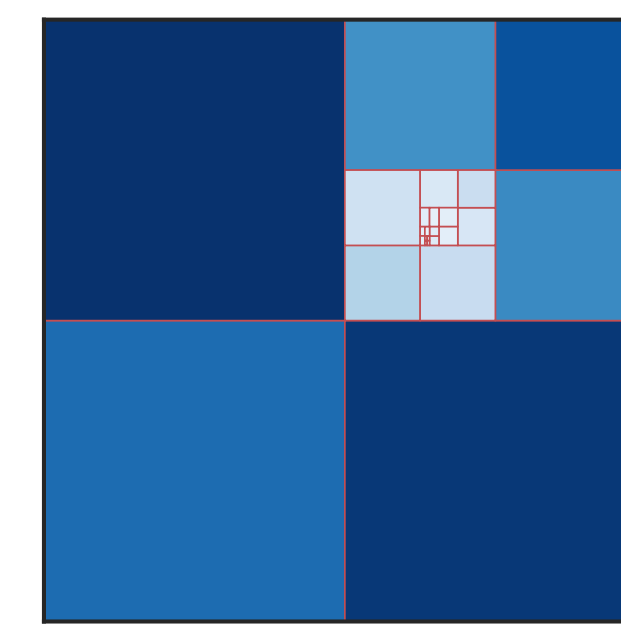
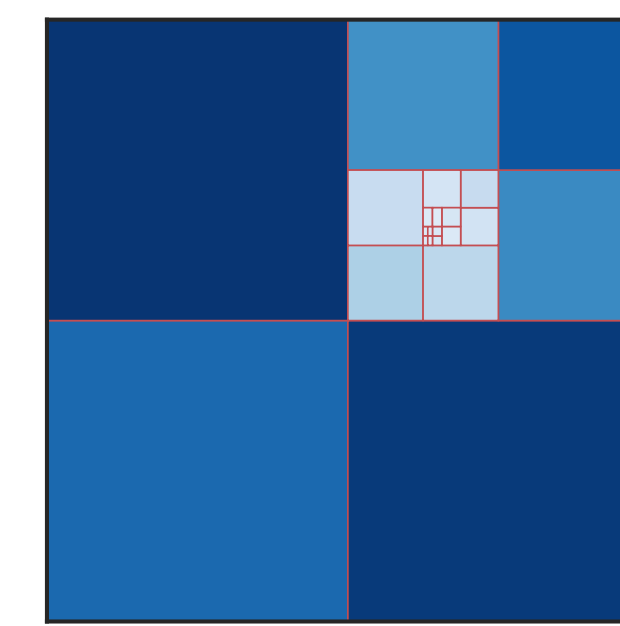
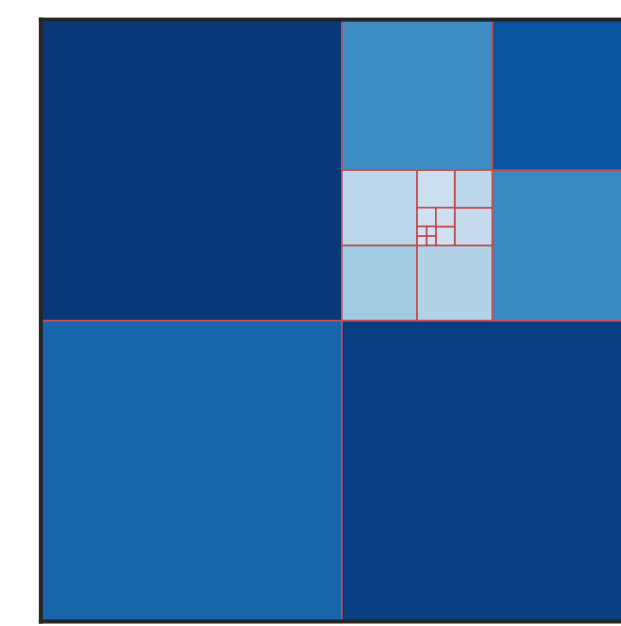
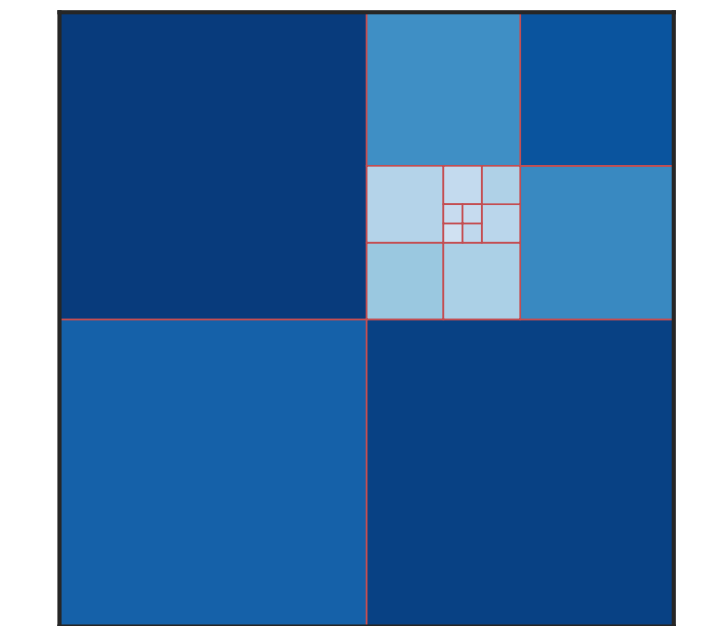
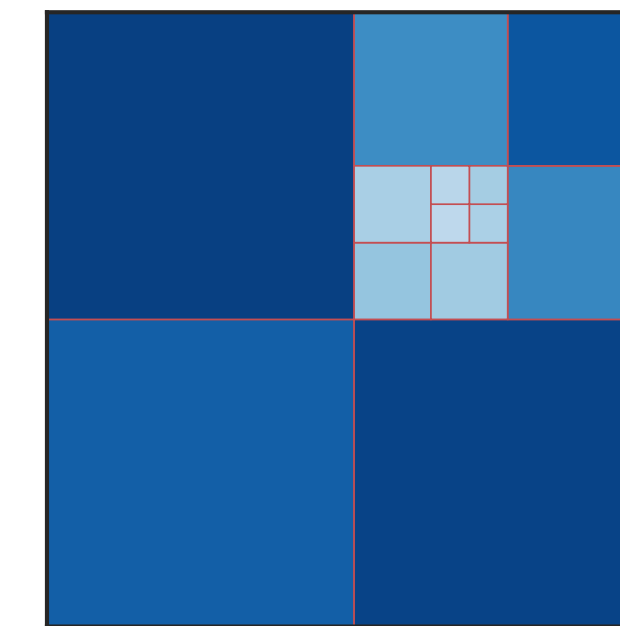
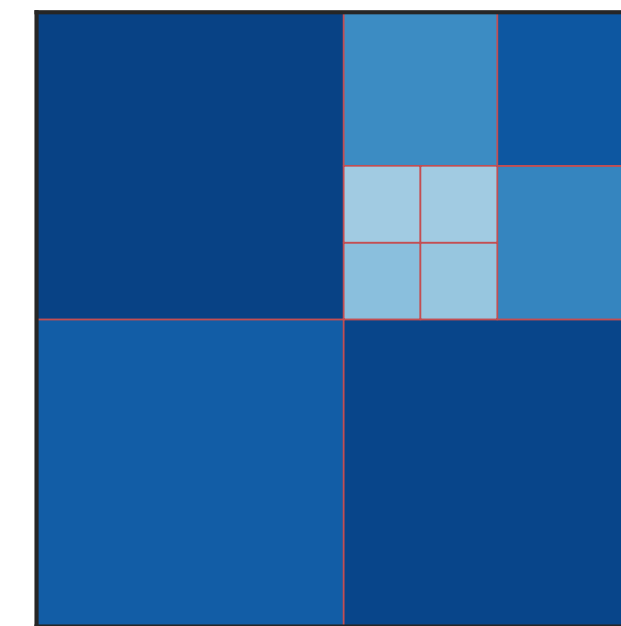
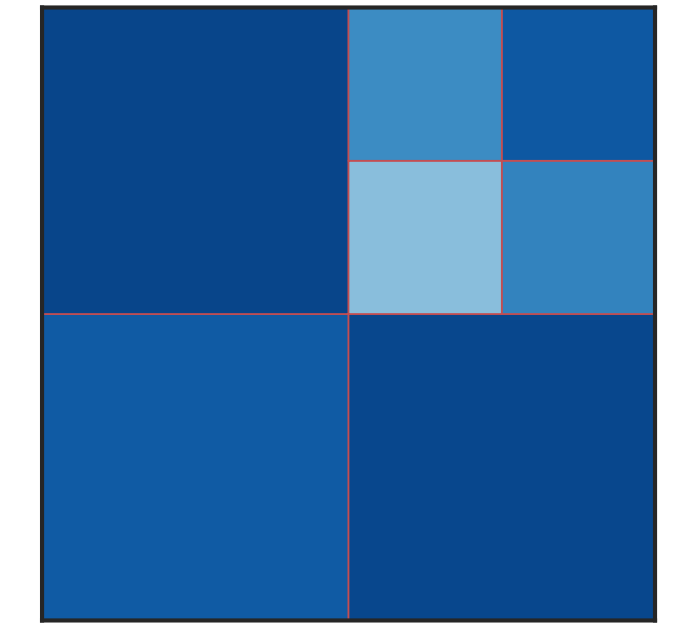
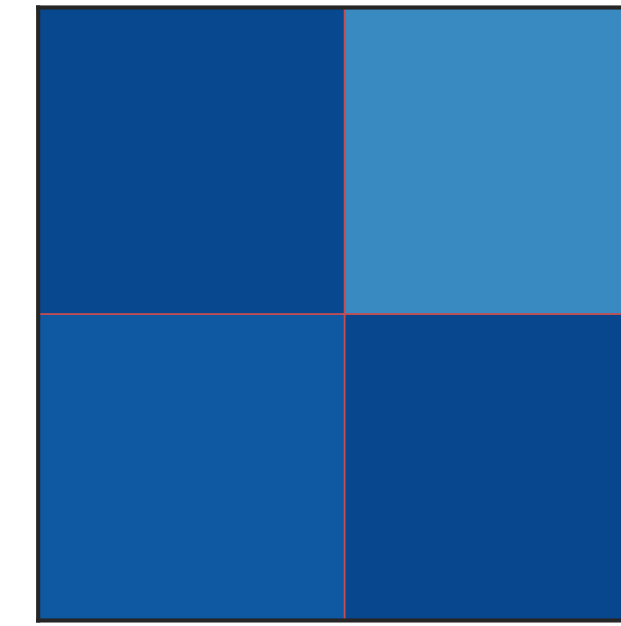
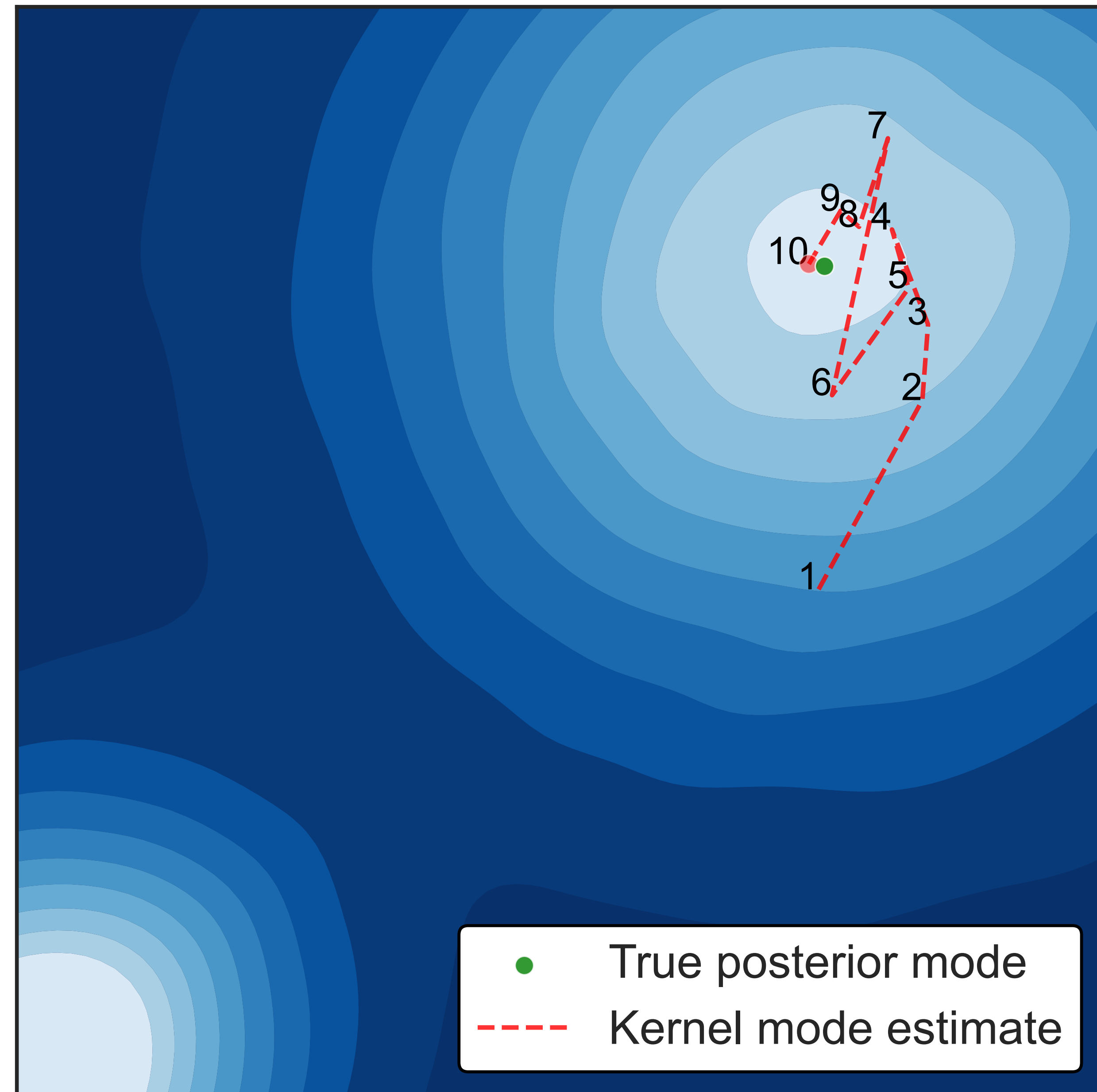
(a) Sequential Proposal Distributions



(b) True ABC Posterior

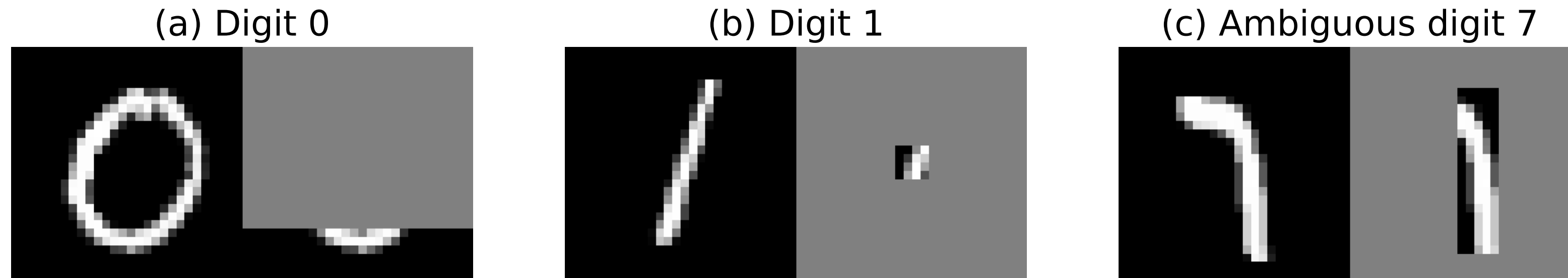


Example MAP (Maximum a posteriori)



Experiment

Generative Unmasking Problem

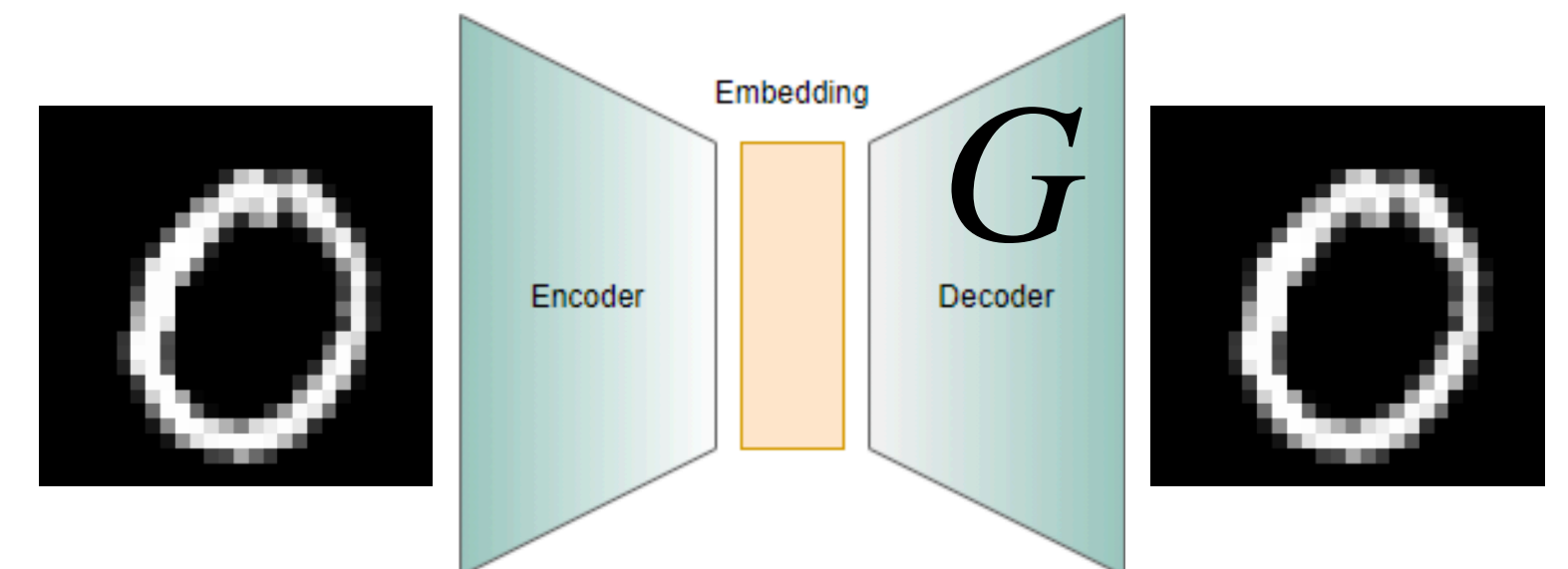


Model: $X = G(\theta) + \epsilon, \theta \sim N(0, I_{d_\theta}), \epsilon \sim N(0, \sigma_0^2 I_{d_x})$

Data: $X = (X_{\text{obs}}, X_{\text{mask}})$

Sampling: $\tilde{\theta} \sim \pi(\theta | X_{\text{obs}})$

Unmasking: $\tilde{X}_{\tilde{\theta}} = G(\tilde{\theta}) + \epsilon, \epsilon \sim N(0, \sigma_0^2 I_{d_x})$

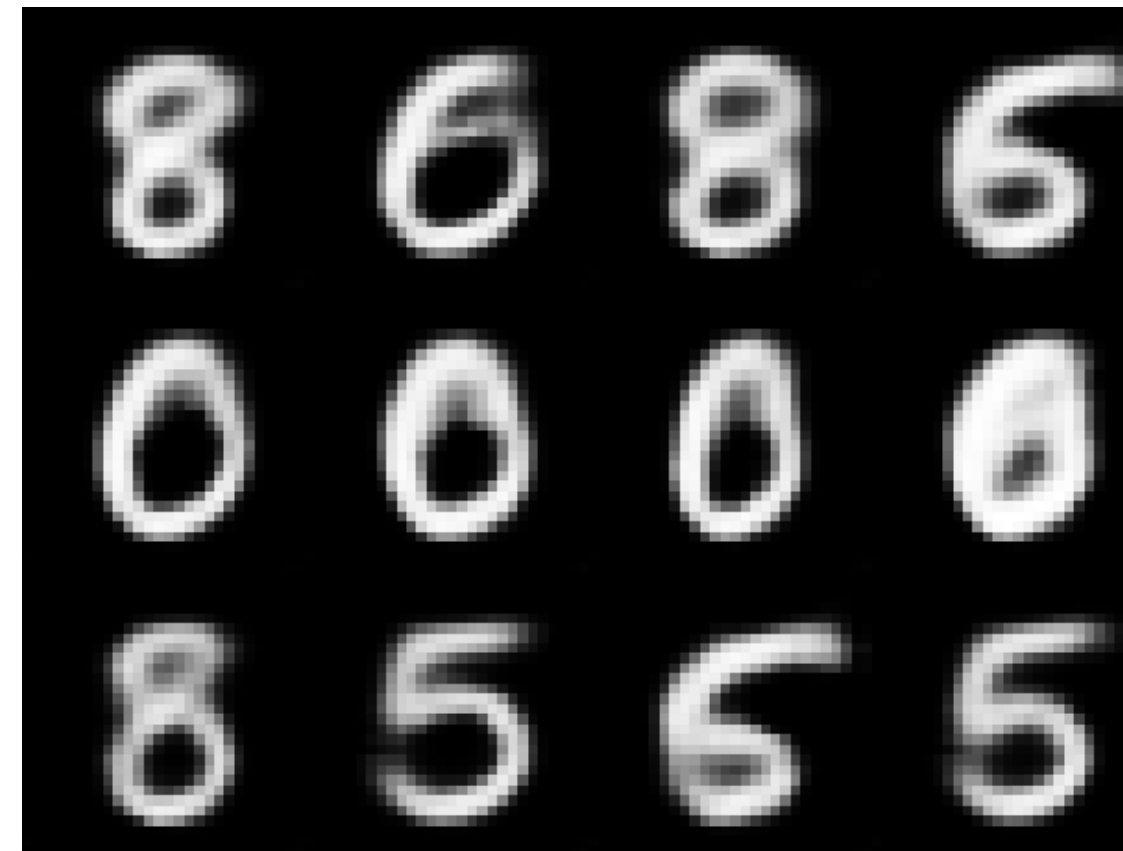


Posterior Sampling: Multi-modality captured-!

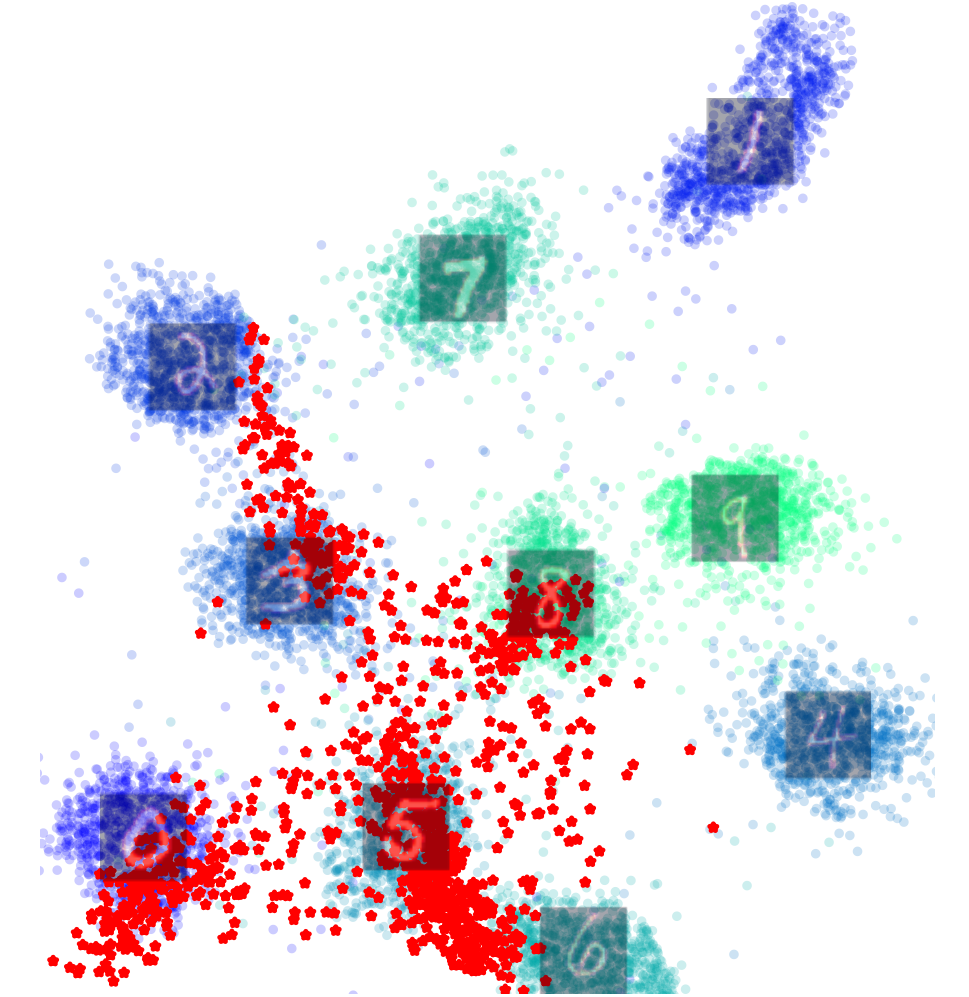
$$X = (X_{\text{obs}}, X_{\text{mask}})$$



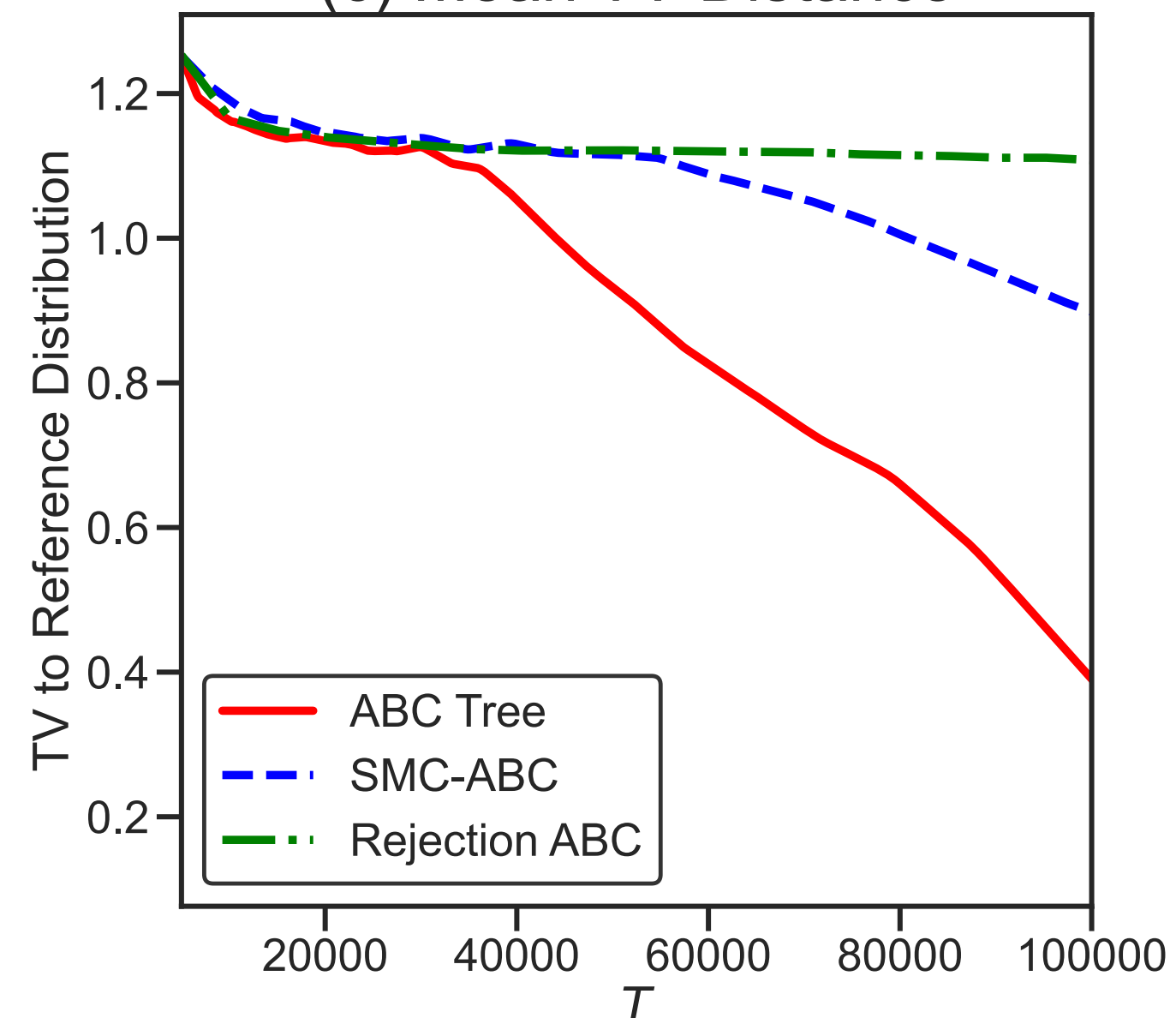
(a) Generated (Unmasked) Images



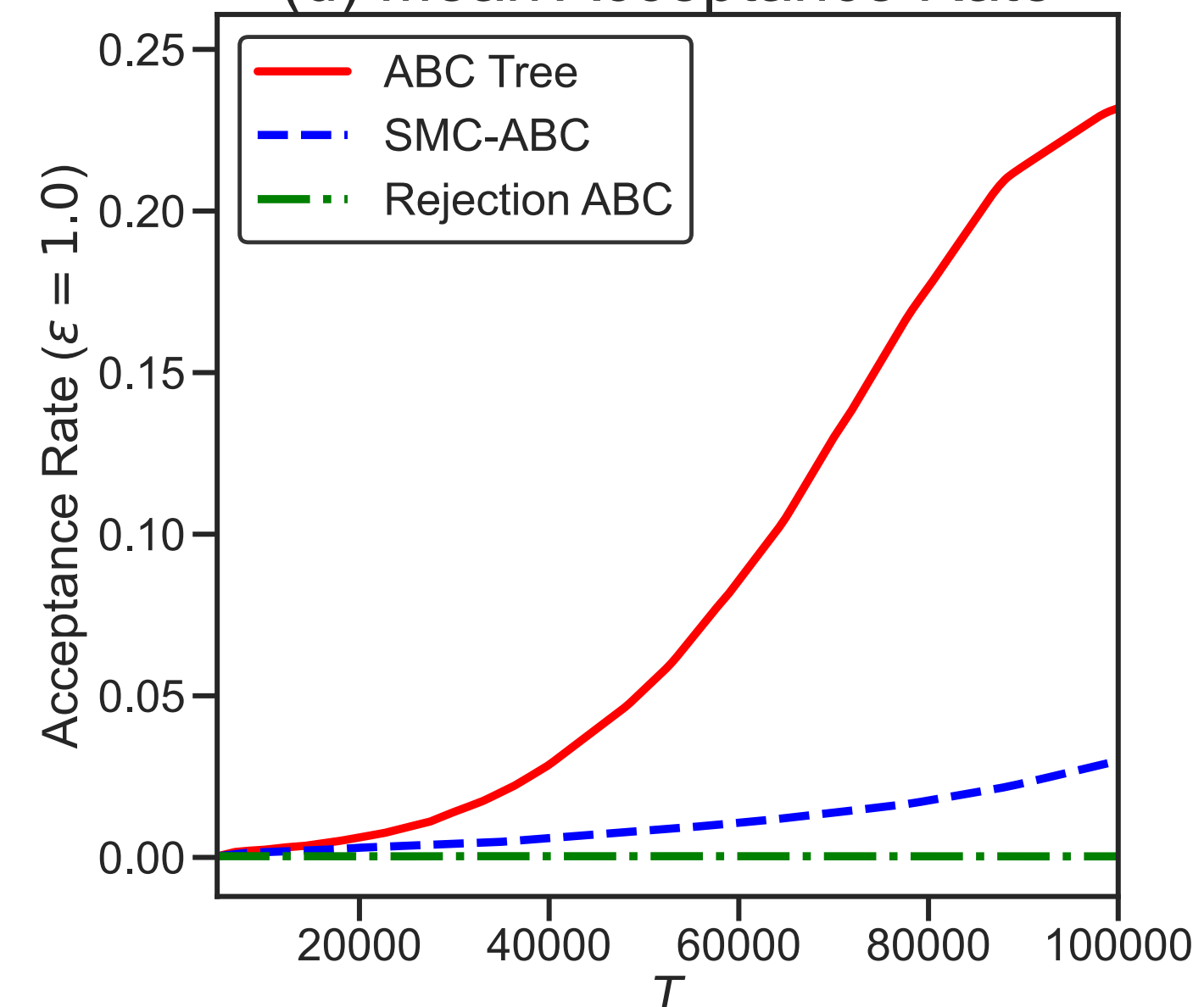
(b) Posterior Samples



(c) Mean TV Distance



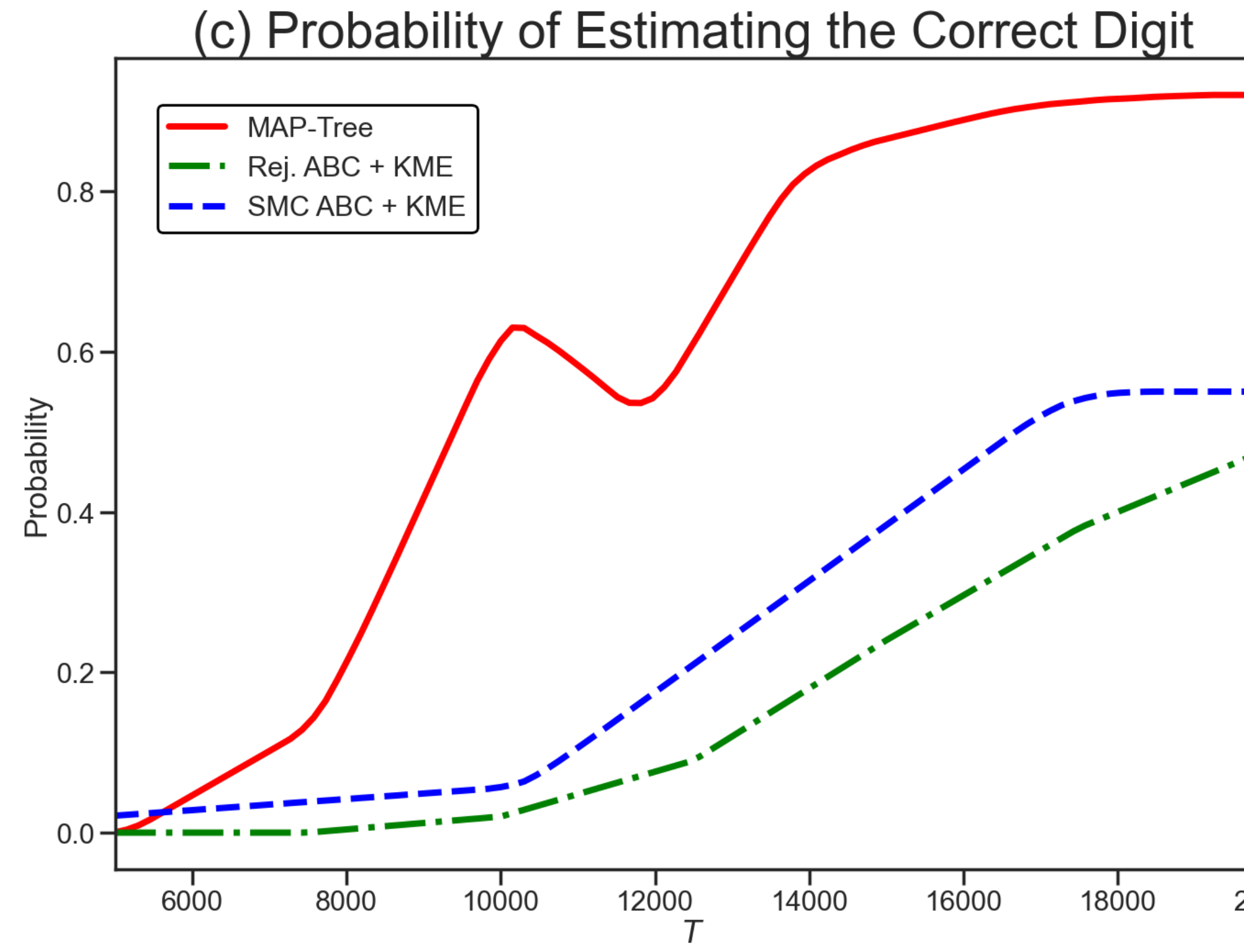
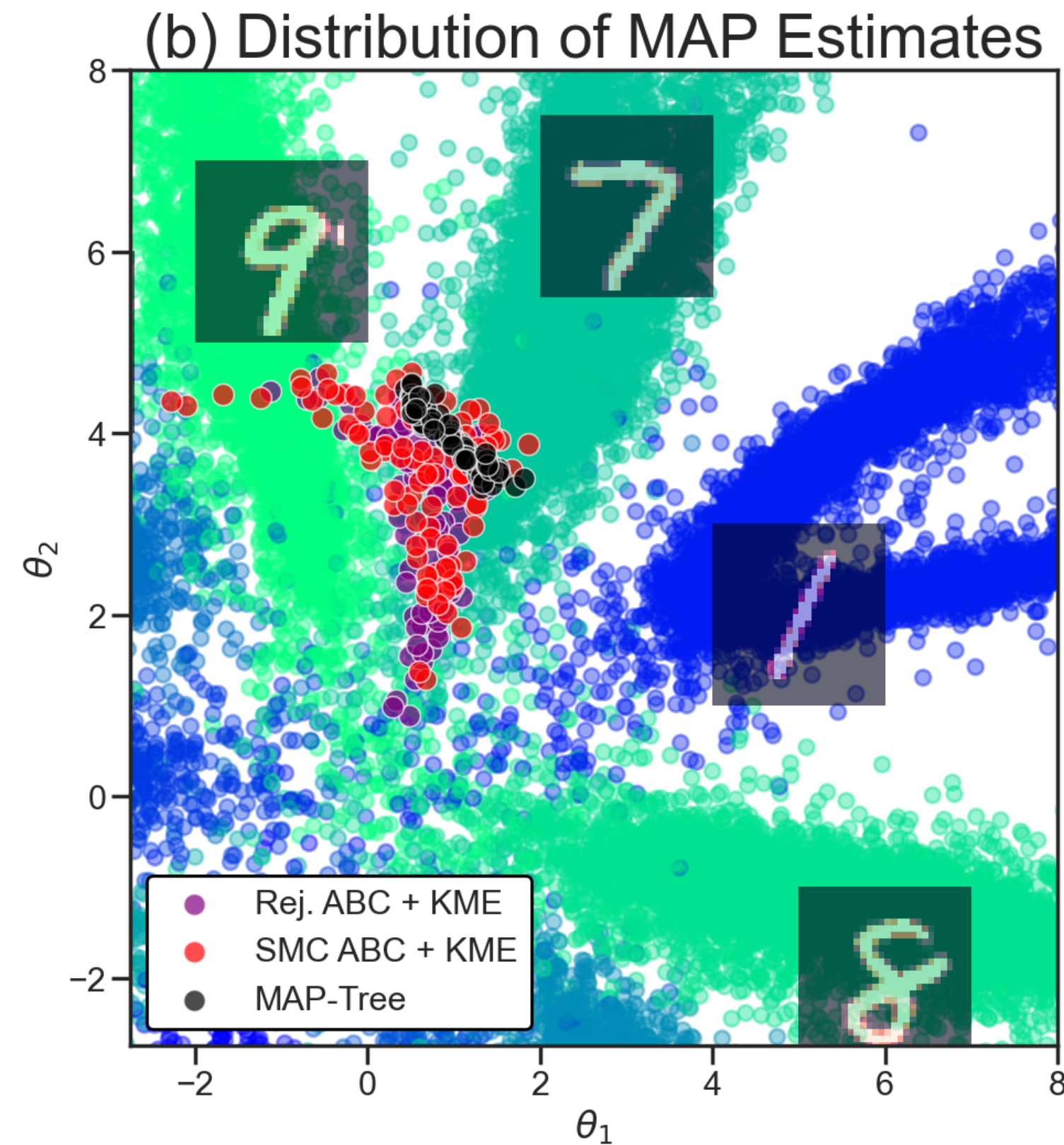
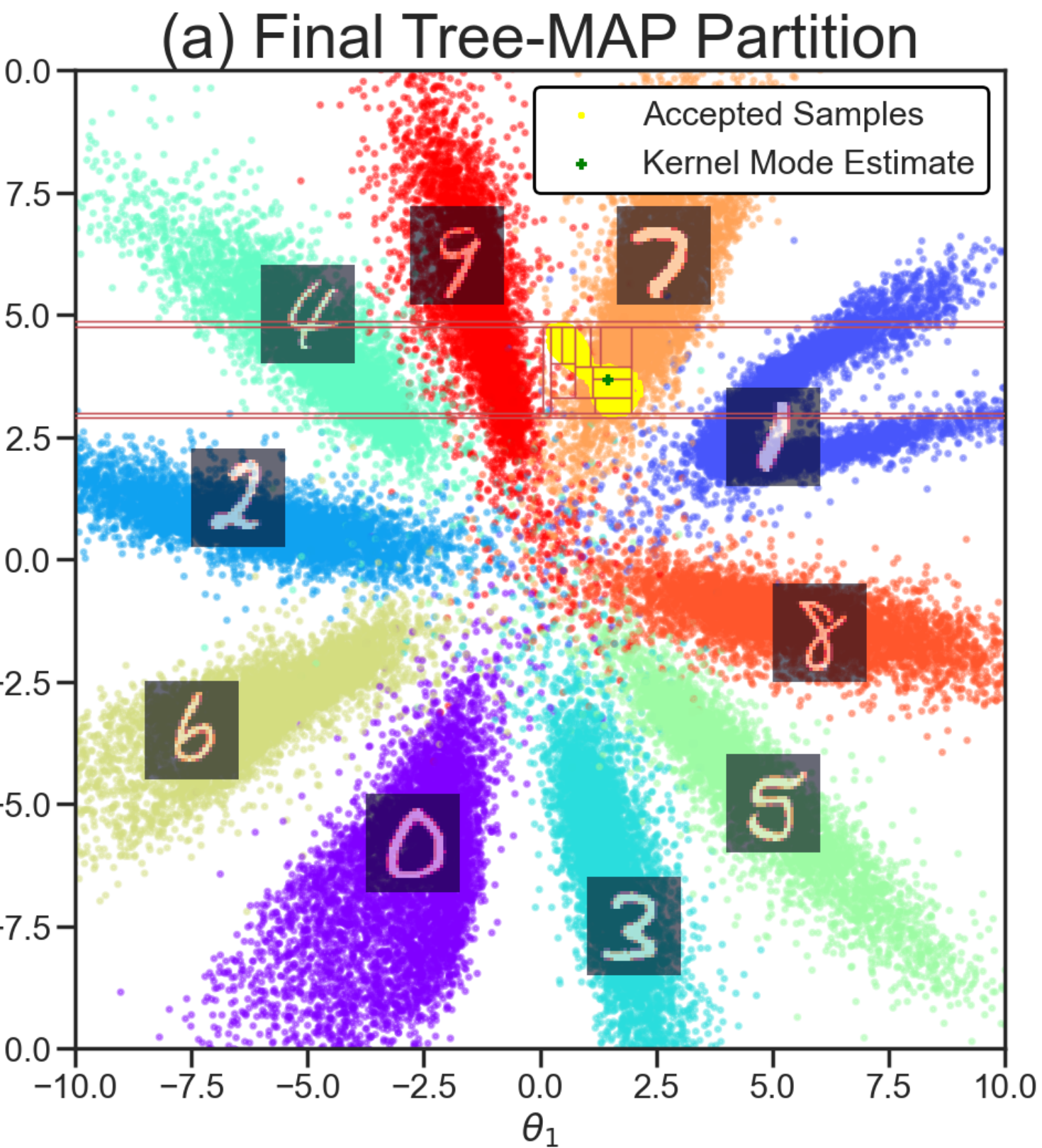
(d) Mean Acceptance Rate



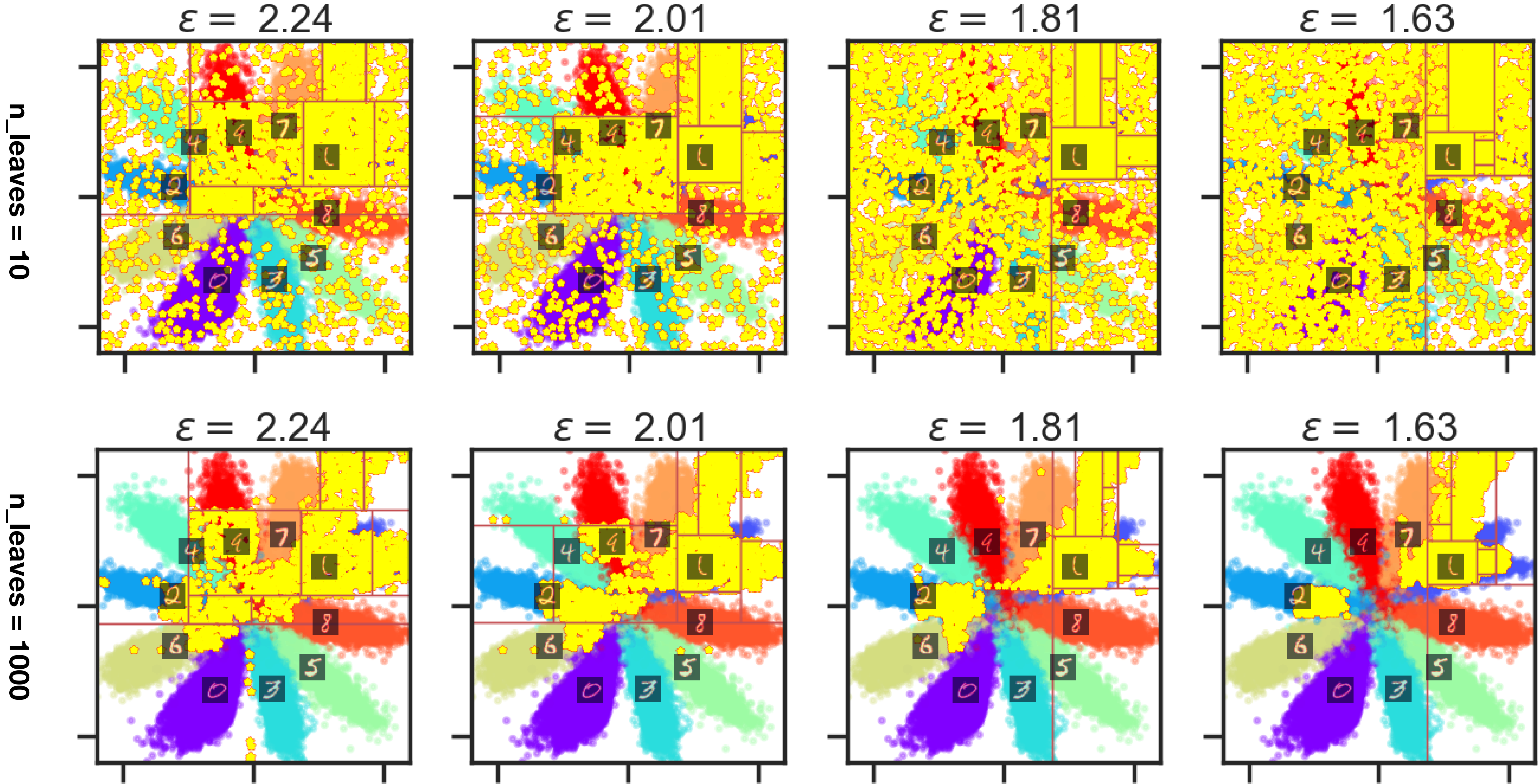
Likelihood-Free MAP:

smaller MAP regions-!

$$X = (X_{\text{obs}}, X_{\text{mask}})$$



Maximum size of trees



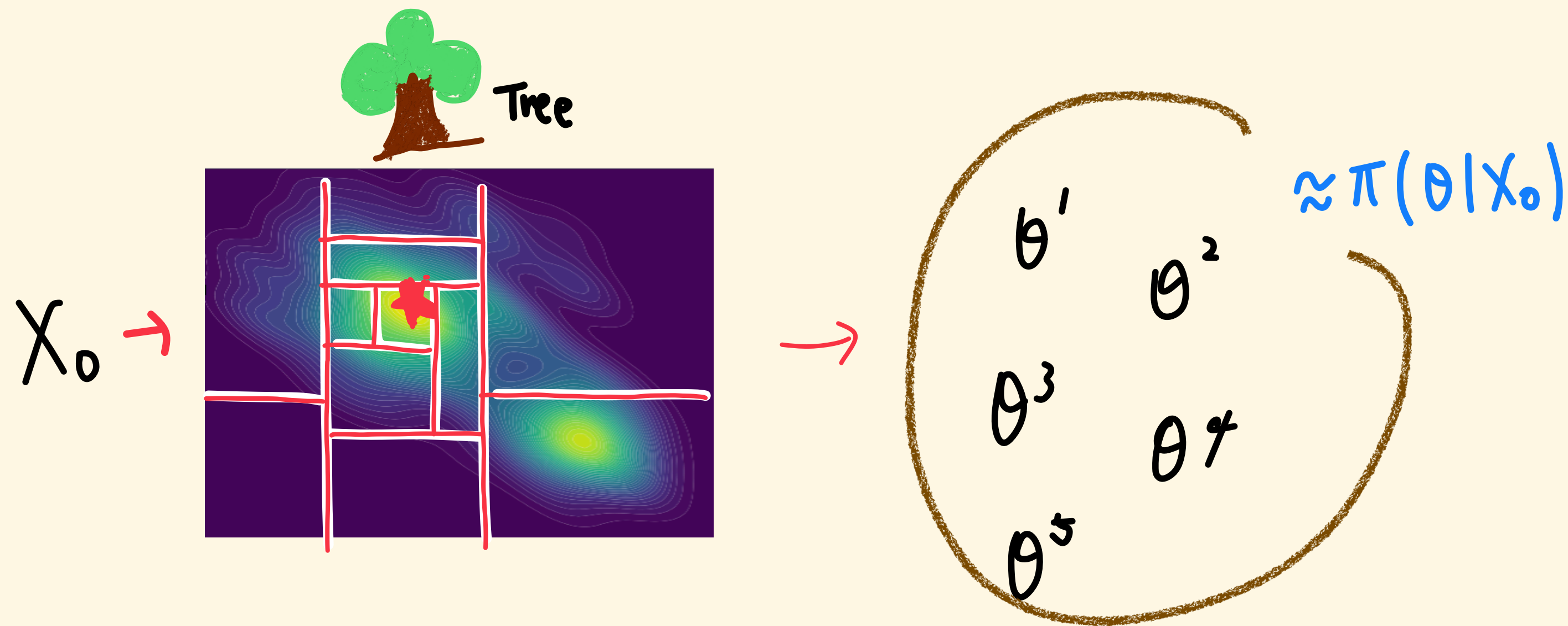
Concluding Remarks

A B C



Our Contribution

By Combining **Tree** with
Active ABC learning



1. Query efficient ABC

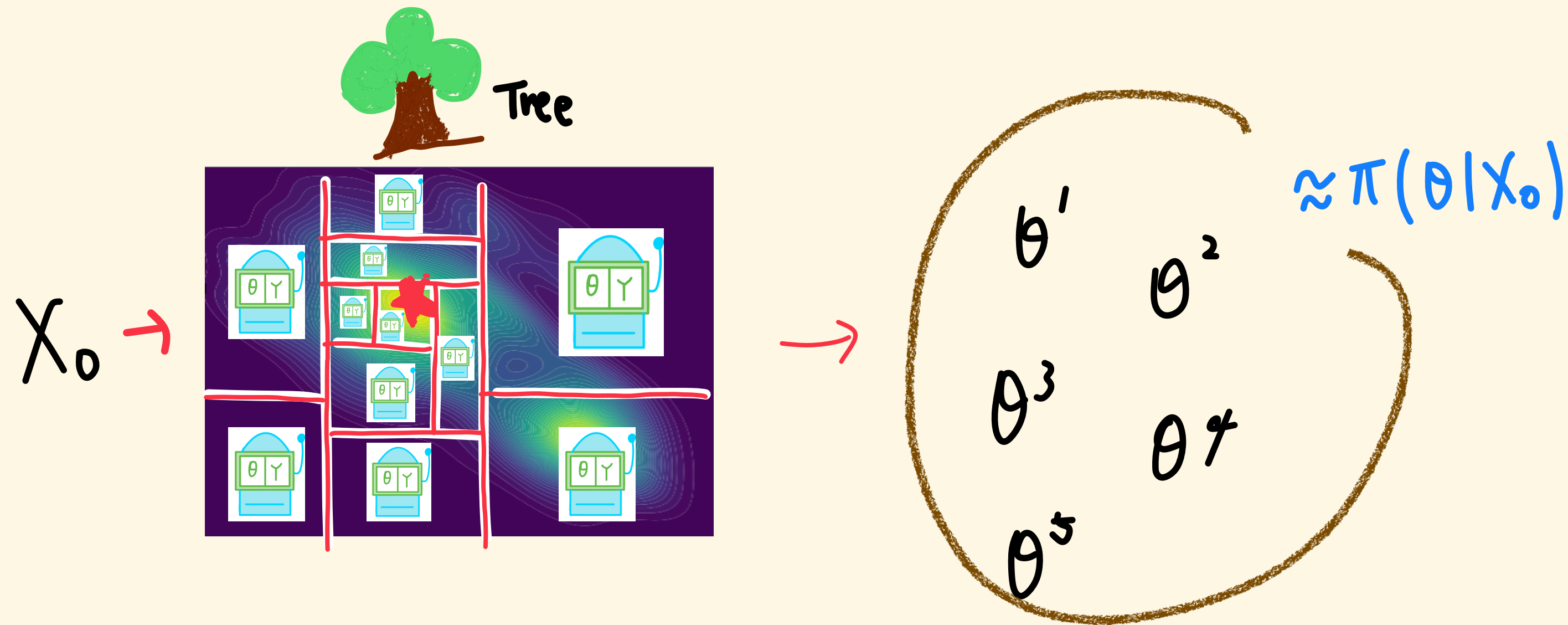
2. Likelihood Free MAP
(Maximum a Posteriori)

A B C



Our Contribution

By Combining **Tree** with
Active ABC learning



1. Query efficient ABC

2. Likelihood Free MAP
(Maximum a Posteriori)

References

My Thompson algorithm explanation is inspired by and benefited from a very helpful YouTube video by @aiinsights-riturajkaushik1618: <https://www.youtube.com/watch?v=p701cYQeqew>

Alsing, Justin, Benjamin D. Wandelt, and Stephen M. Feeney. "Optimal proposals for approximate Bayesian computation." *arXiv preprint arXiv:1808.06040* (2018).

Thank you!

And, thank you, Veronika and Sean-!

For more theoretical/numerical results:

Please check out <https://arxiv.org/abs/2404.10436>

Any comments on the slides and my presentation are appreciated-!!